

Estimation

Maximum Likelihood and Smoothing

Introduction to Natural Language Processing

Computer Science 585—Fall 2009

University of Massachusetts Amherst

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Simple Estimation

- Probability courses usually start with equiprobable events
 - Coin flips, dice, cards
- How likely to get a 6 rolling 1 die?
- How likely the sum of two dice is 6?
- How likely to see 3 heads in 10 flips?

Binomial Distribution

For n trials, k successes, and success probability p :

$$P(k) = \binom{n}{k} p^k (1-p)^{n-k} \quad \text{Prob. mass function}$$

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}$$

Estimation problem: If we observe n and k , **what is p ?**

Maximum Likelihood

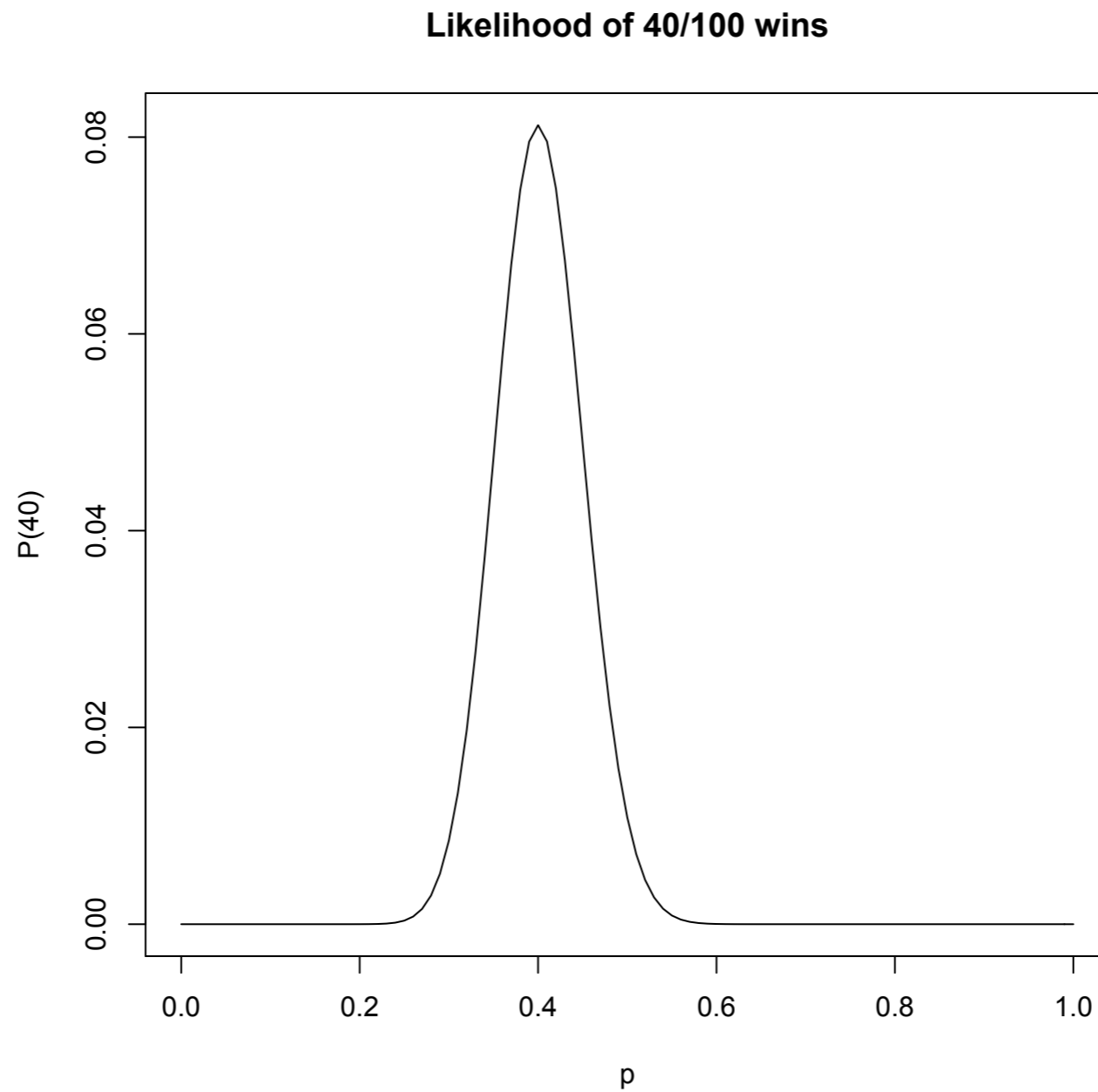
Say we win 40 games out of 100.

$$P(40) = \binom{100}{40} p^{40} (1 - p)^{60}$$

The maximum likelihood estimator for p solves:

$$\max_p P(\text{observed data}) = \max_p \binom{100}{40} p^{40} (1 - p)^{60}$$

Maximum Likelihood



Maximum Likelihood

How to solve $\max_p \binom{100}{40} p^{40} (1-p)^{60}$

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$$\begin{aligned} 0 &= \frac{\partial}{\partial p} \binom{100}{40} p^{40} (1-p)^{60} \\ &= 40p^{39} (1-p)^{60} - 60p^{40} (1-p)^{59} \\ &= p^{39} (1-p)^{59} [40(1-p) - 60p] \\ &= p^{39} (1-p)^{59} 40 - 100p \end{aligned}$$

Maximum Likelihood

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Solutions: 0, 1, .4

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In general, k/n

Solutions: 0, 1, .4

This is trivial here, but a widely useful approach.

ML for Language Models

- Say the corpus has “in the” 100 times
- If we see “in the beginning” 5 times,
 $p_{\text{ML}}(\text{beginning} \mid \text{in the}) = ?$
- If we see “in the end” 8 times,
 $p_{\text{ML}}(\text{end} \mid \text{in the}) = ?$
- If we see “in the kitchen” 0 times,
 $p_{\text{ML}}(\text{kitchen} \mid \text{in the}) = ?$

ML for Naive Bayes

- Recall: $p(+ \mid \text{Damon movie})$
 $= p(\text{Damon} \mid +) p(\text{movie} \mid +) p(+)$
- If corpus of positive reviews has 1000 words, and “Damon” occurs 50 times,
 $p_{\text{ML}}(\text{Damon} \mid +) = ?$
- If pos. corpus has “Affleck” 0 times,
 $p(+ \mid \text{Affleck Damon movie}) = ?$

Will the Sun Rise Tomorrow?



Will the Sun Rise Tomorrow?

Laplace's Rule of Succession:
On day $n+1$, we've observed that
the sun has risen s times before.



$$p_{Lap}(S_{n+1} = 1 \mid S_1 + \dots + S_n = s) = \frac{s + 1}{n + 2}$$

What's the probability on day 0?

On day 1?

On day 10^6 ?

Start with prior assumption of equal rise/not-rise probabilities; *update* after every observation.

Laplace (Add One) Smoothing

- From our earlier example:

$p_{\text{ML}}(\text{beginning} \mid \text{in the}) = 5/100?$ reduce!

$p_{\text{ML}}(\text{end} \mid \text{in the}) = 8/100?$ reduce!

$p_{\text{ML}}(\text{kitchen} \mid \text{in the}) = 0/100?$ increase!

Laplace (Add One) Smoothing

- Let V be the vocabulary size:
i.e., the number of unique words that could follow “in the”

- From our earlier example:

$$p_{\text{ML}}(\text{beginning} \mid \text{in the}) = (5 + 1) / (100 + V)$$

$$p_{\text{ML}}(\text{end} \mid \text{in the}) = (8 + 1) / (100 + V)$$

$$p_{\text{ML}}(\text{kitchen} \mid \text{in the}) = (0 + 1) / (100 + V)$$

Generalized Additive Smoothing

- Laplace add-one smoothing now assigns *too much* probability to unseen words
- More common to use λ instead of 1:

$$\begin{aligned} p(w_3 \mid w_1, w_2) &= \frac{C(w_1, w_2, w_3) + \lambda}{C(w_1, w_2) + \lambda V} \\ &= \mu \frac{C(w_1, w_2, w_3)}{C(w_1, w_2)} + (1 - \mu) \frac{1}{V} \\ \mu &= \frac{C(w_1, w_2)}{C(w_1, w_2) + \lambda V} \end{aligned}$$

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$$p(w_3 \mid w_1, w_2) = \frac{C(w_1, w_2, w_3) + \lambda}{C(w_1, w_2) + \lambda V}$$

interpolation

$$= \mu \frac{C(w_1, w_2, w_3)}{C(w_1, w_2)} + (1 - \mu) \frac{1}{V}$$

$$\mu = \frac{C(w_1, w_2)}{C(w_1, w_2) + \lambda V}$$

Generalized Additive Smoothing

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$$p(w_3 \mid w_1, w_2) = \frac{C(w_1, w_2, w_3) + \lambda}{C(w_1, w_2) + \lambda V}$$

What's the right λ ?

interpolation

$$= \mu \frac{C(w_1, w_2, w_3)}{C(w_1, w_2)} + (1 - \mu) \frac{1}{V}$$

$$\mu = \frac{C(w_1, w_2)}{C(w_1, w_2) + \lambda V}$$

Picking Parameters

- What happens if we optimize parameters on training data, i.e. the same corpus we use to get counts?
- Maximum likelihood estimate!
- Use *held-out data* aka *development data*

Good-Turing Smoothing

- Intuition: Can judge rate of novel events by rate of singletons
 - Developed to estimate # of unseen species in field biology
- Let $N_r = \#$ of word types with r training tokens
 - e.g., $N_0 =$ number of unobserved words
 - e.g., $N_1 =$ number of singletons (hapax legomena)
- Let $N = \sum r N_r =$ total # of training tokens

Good-Turing Smoothing

- Max. likelihood estimate if w has r tokens? r/N
- Total max. likelihood probability of all words with r tokens? N_r / N
- Good-Turing estimate of this total probability:
 - Defined as: $N_{r+1} (r+1) / N$
 - So proportion of novel words in test data is estimated by proportion of singletons in training data.
 - Proportion in test data of the N_1 singletons is estimated by proportion of the N_2 doubletons in training data. etc.
 - $p(\text{any given word } w/\text{freq. } r) = N_{r+1} (r+1) / (N N_r)$
- NB: No parameters to tune on held-out data

Backoff

- Say we have the counts:

$$C(\text{in the kitchen}) = 0$$

$$C(\text{the kitchen}) = 3$$

$$C(\text{kitchen}) = 4$$

$$C(\text{arboretum}) = 0$$

- ML estimates seem counterintuitive:

$$p(\text{kitchen} \mid \text{in the}) = p(\text{arboretum} \mid \text{in the}) = 0$$

Backoff

- Clearly we shouldn't treat “kitchen” the same as “arboretum”
- Basic add- λ (and other) smoothing methods assign the same prob. to *all* unseen events
- **Backoff** divides up prob. of unseen unevenly in proportion to, e.g., lower-order n-grams
- If $p(z \mid x,y) = 0$, use $p(z \mid y)$, etc.

Deleted Interpolation

- Simplest form of backoff
- Form a *mixture* of different order n-gram models; learn weights on held-out data

$$p_{del}(z \mid x, y) = \alpha_3 p(z \mid x, y) + \alpha_2 p(z \mid y) + \alpha_1 p(z)$$
$$\sum \alpha_i = 1$$

- How else could we back off?

Readings, etc.

- For more information on basic probability, read M&S 2.1
- For more information on language model estimation, read M&S 6
- Next, time Hidden Markov Models