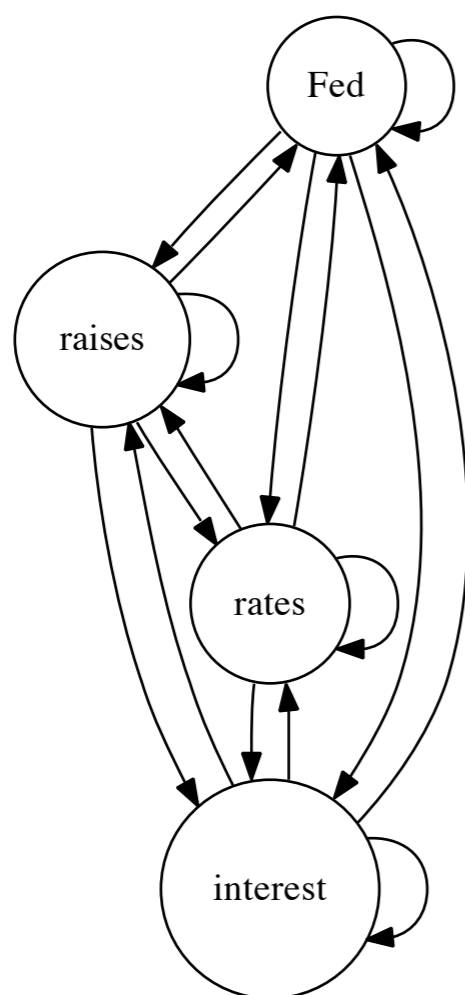


# Hidden Markov Models: Maxing and Summing

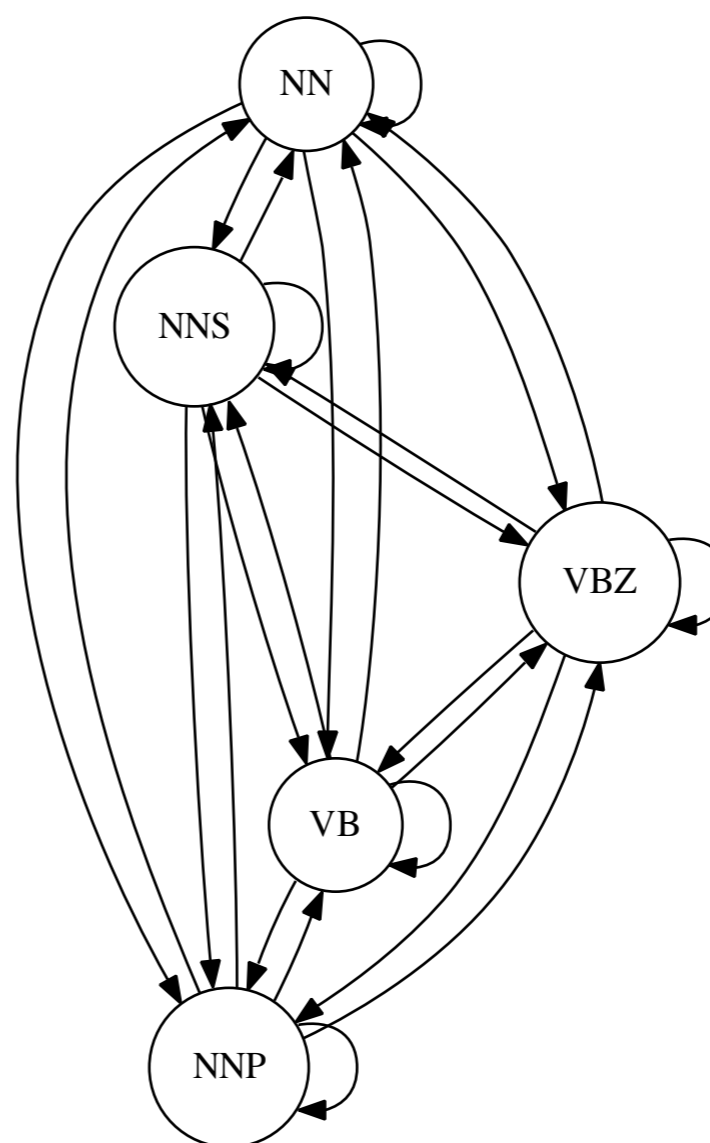
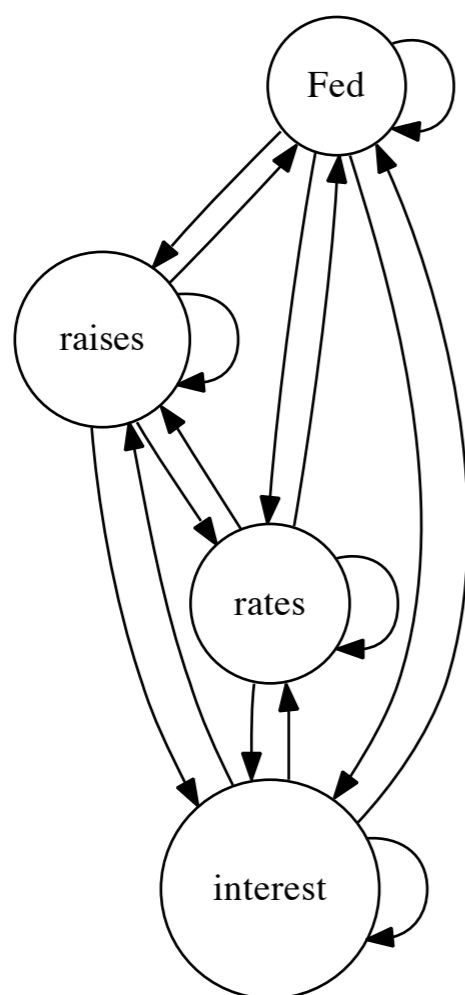
Introduction to Natural Language Processing  
Computer Science 585—Fall 2009  
University of Massachusetts Amherst

David Smith

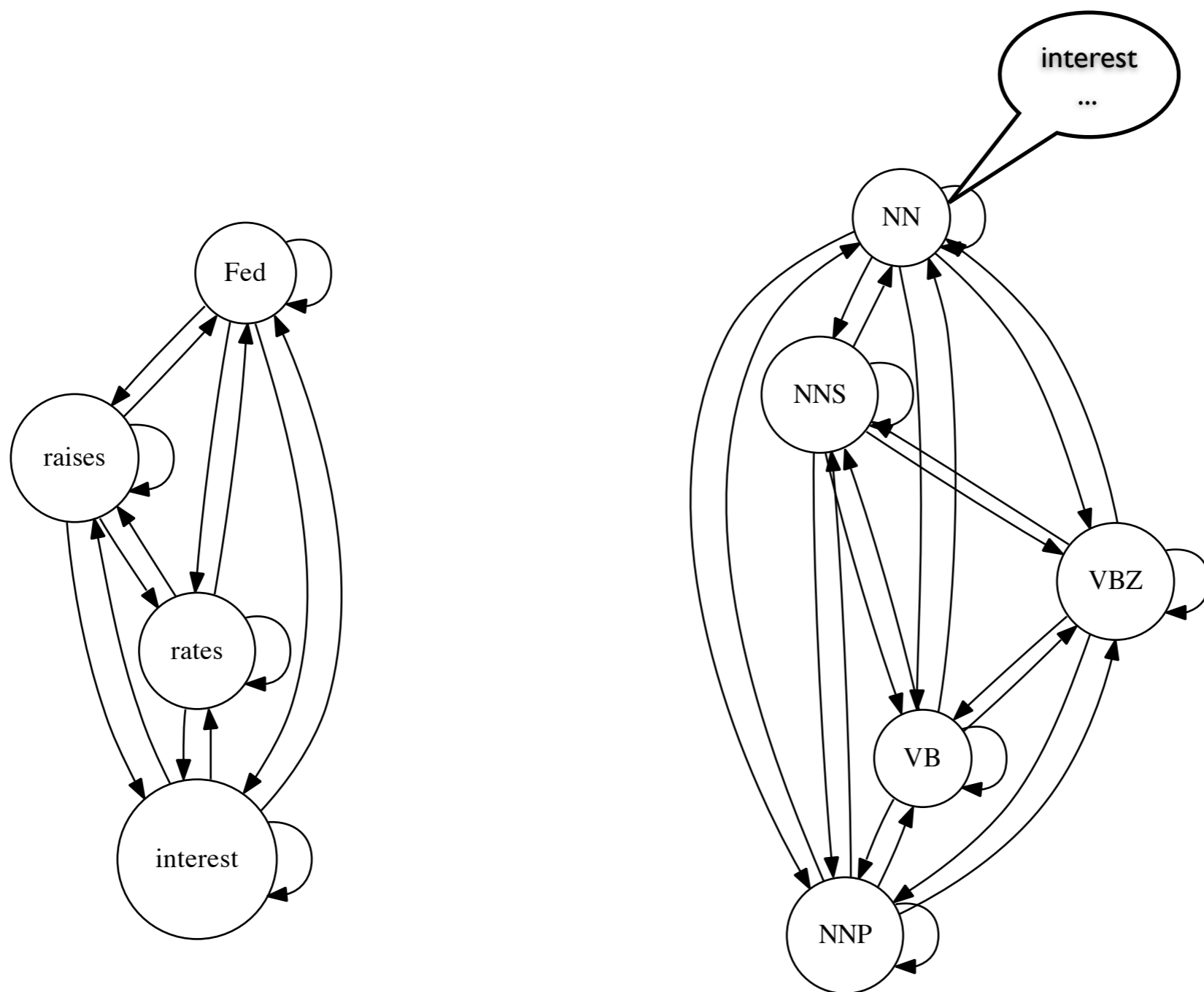
# Markov vs. Hidden Markov Models



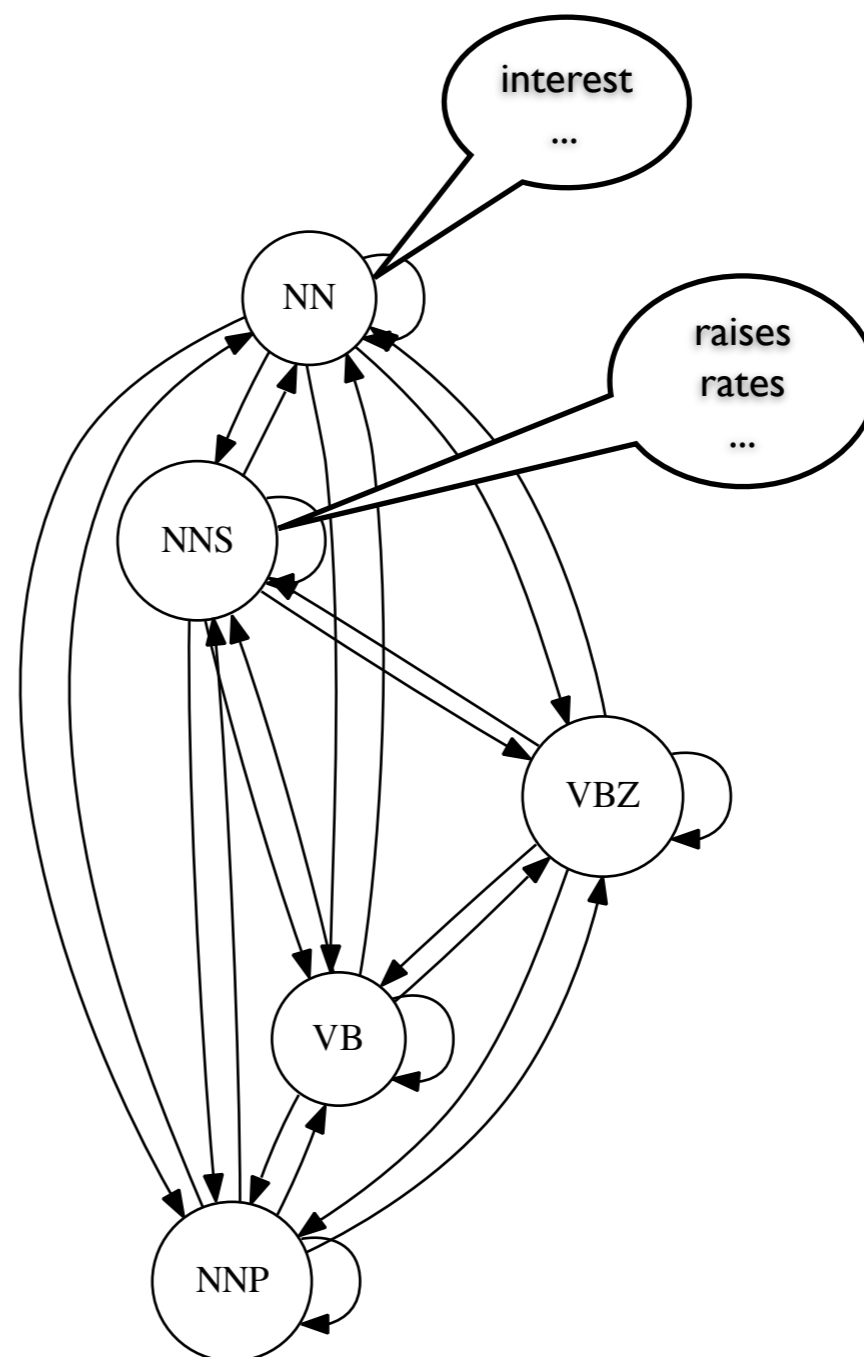
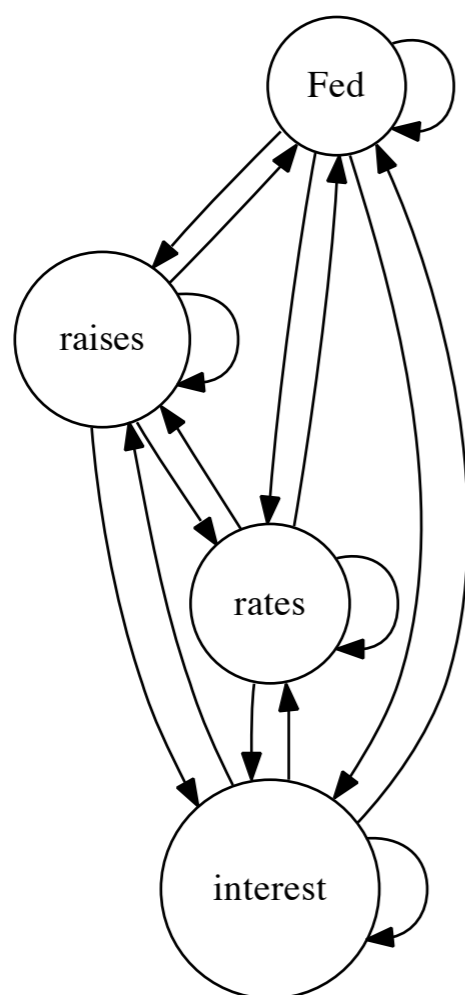
# Markov vs. Hidden Markov Models



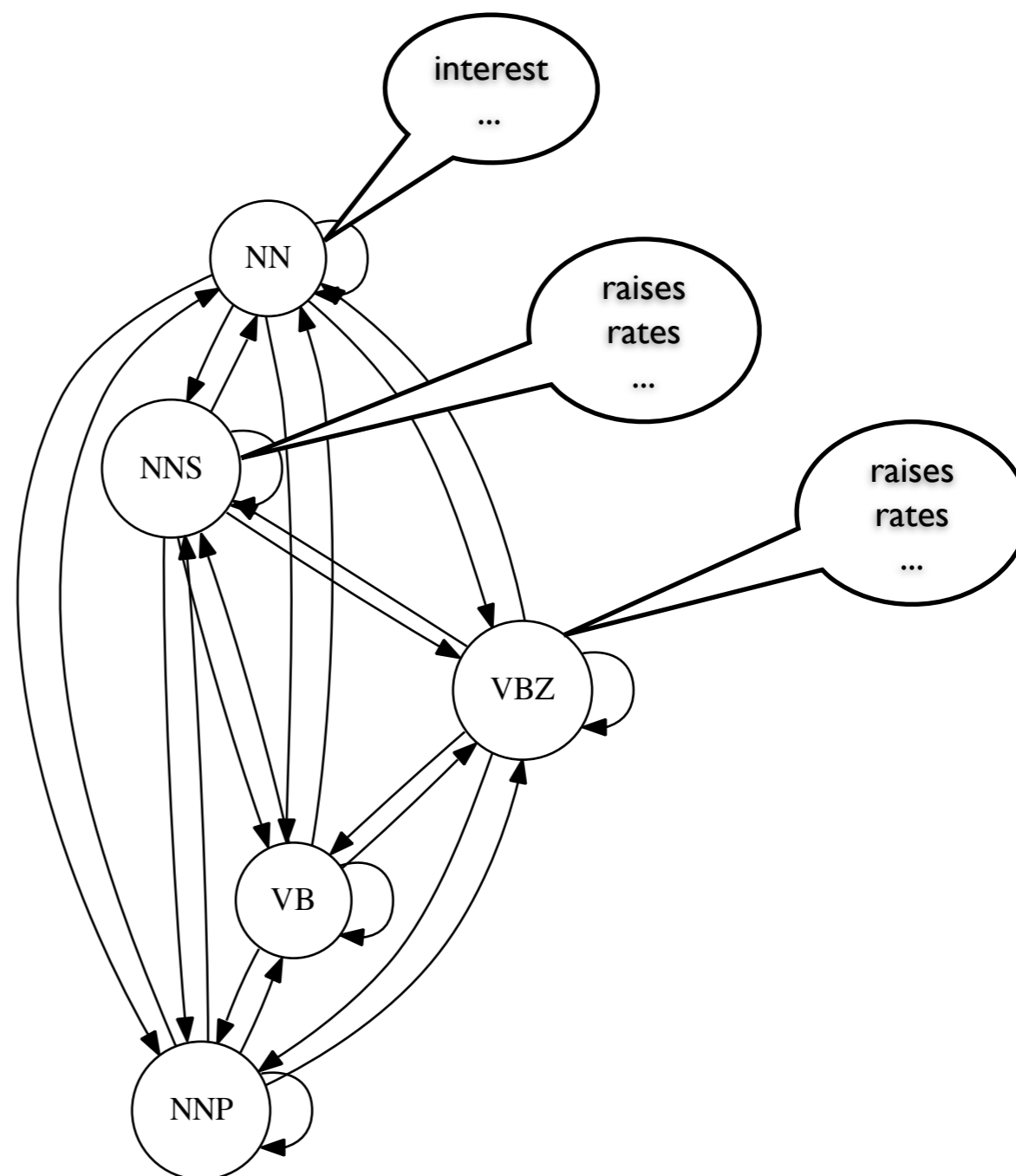
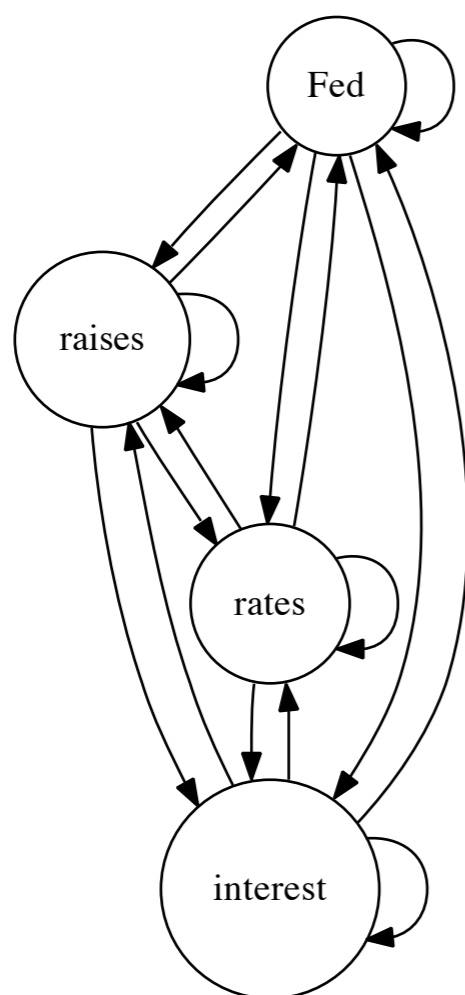
# Markov vs. Hidden Markov Models



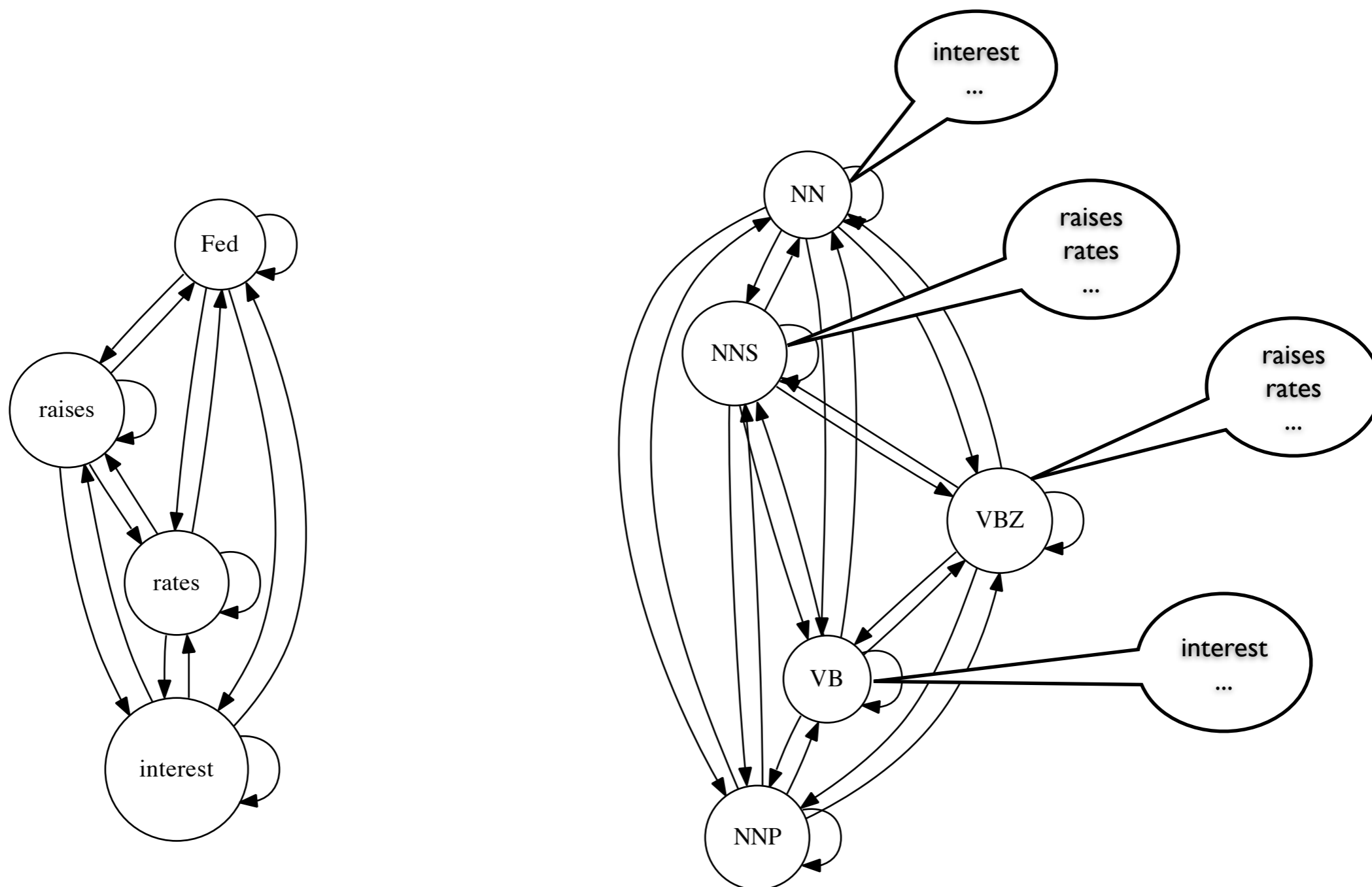
# Markov vs. Hidden Markov Models



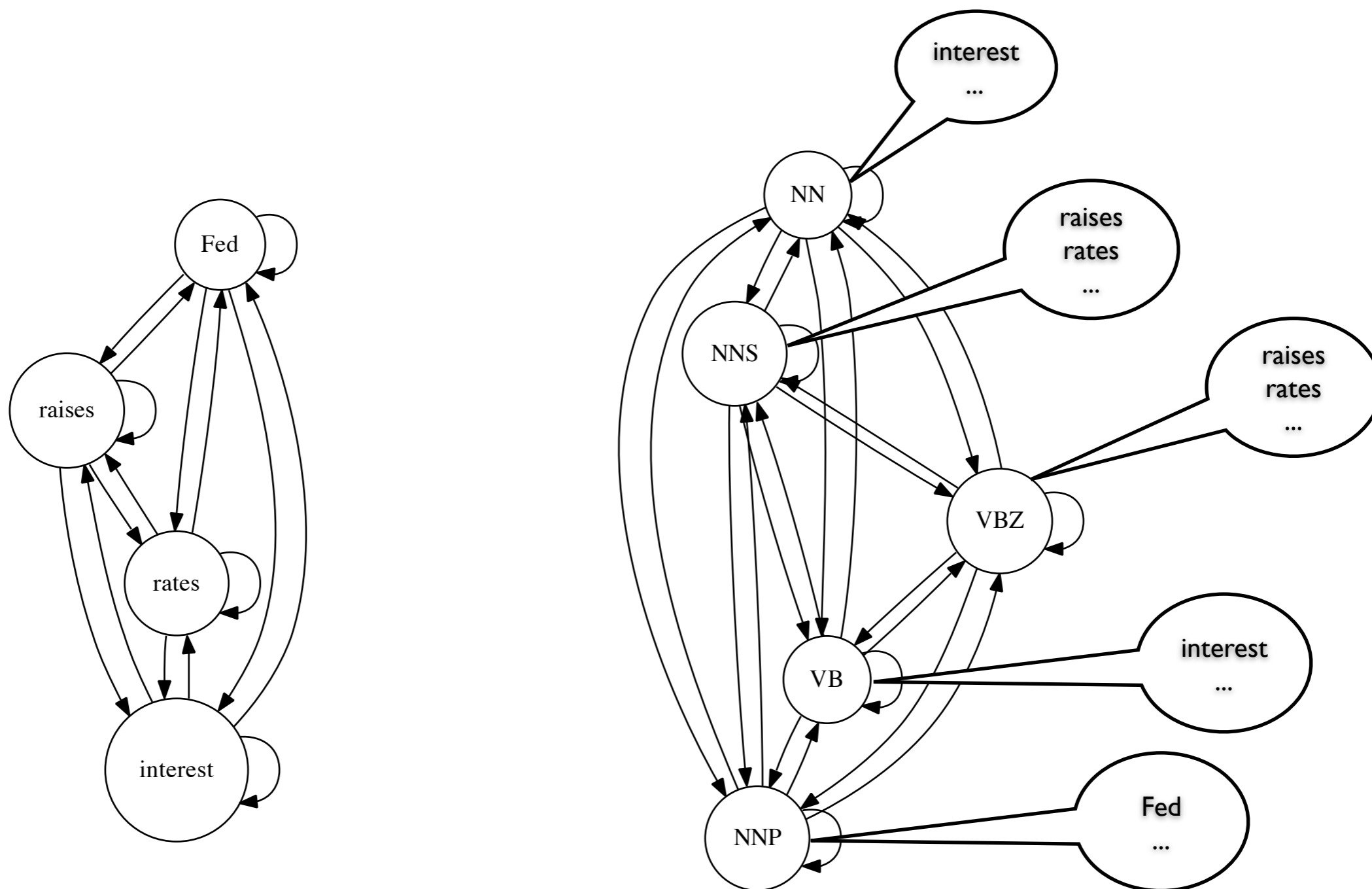
# Markov vs. Hidden Markov Models



# Markov vs. Hidden Markov Models



# Markov vs. Hidden Markov Models





# Unrolled into a Trellis

NN	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
NNS	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
NNP	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
VB	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
VBZ	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	Fed	raises	interest	rates

# HMM Inference Problems

- Given an observation sequence, find the most likely state sequence (**tagging**)
- Compute the probability of observations when state sequence is hidden (**language modeling**)
- Given observations and (optionally) a their corresponding states, find parameters that maximize the probability probability of the observations (**parameter estimation**)

# Tagging

Given an observation sequence, find the most likely state sequence.

$$\arg \max_X P(X | O, \mu) = \arg \max_X \frac{P(X, O | \mu)}{P(O | \mu)} = \arg \max_X P(X, O | \mu)$$

$$\arg \max_{x_1, x_2, \dots, x_T} P(x_1, x_2, \dots, x_T, O | \mu)$$

Last time: Use dynamic programming to find highest-probability sequence (i.e. best path, like Dijkstra's algorithm)

# Language Modeling

Compute the probability of observations when state sequence is hidden.

$$P(X, O \mid \mu) = P(O \mid X, \mu)P(X \mid \mu)$$

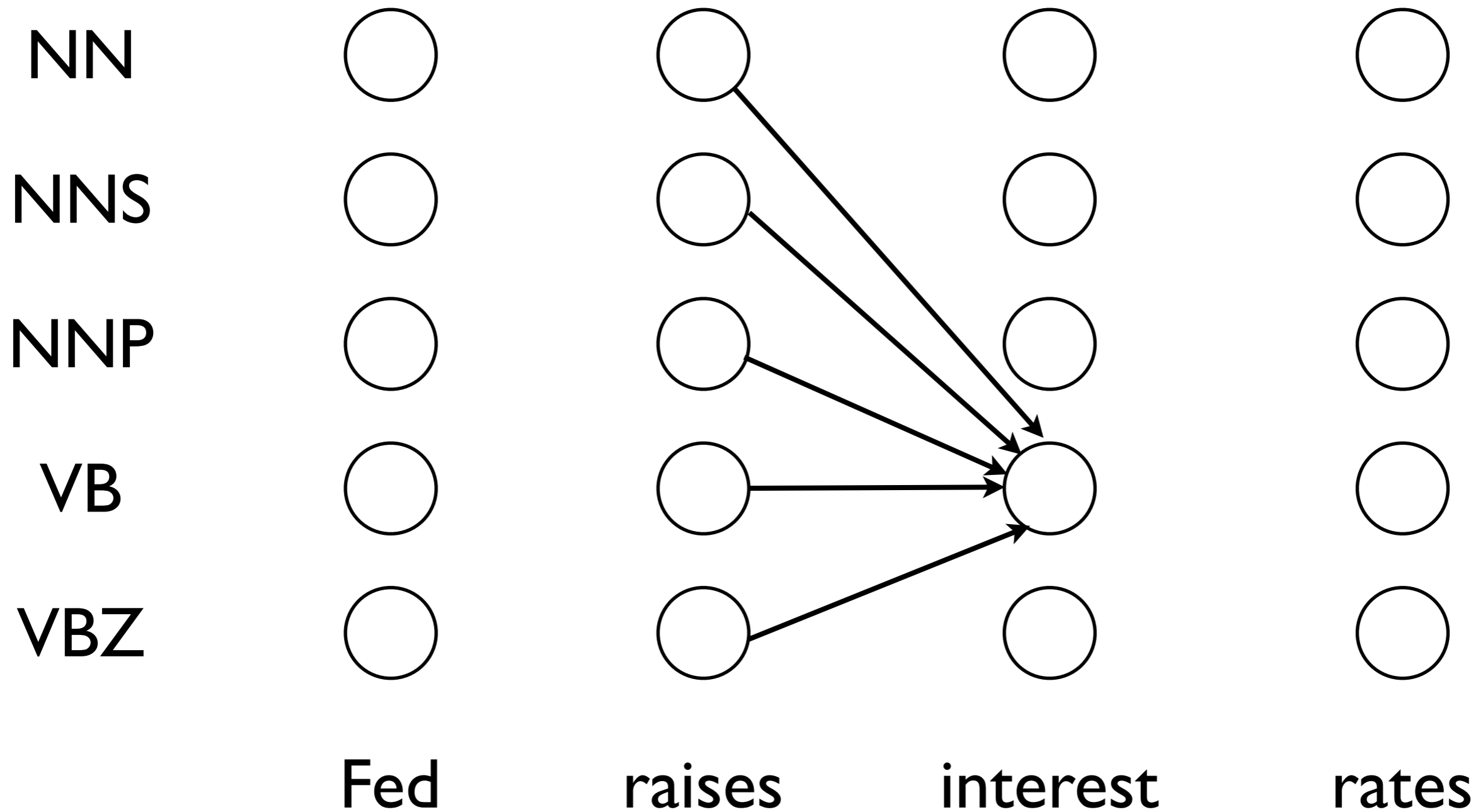
Therefore

$$P(O \mid \mu) = \sum_X P(O \mid X, \mu)P(X \mid \mu)$$

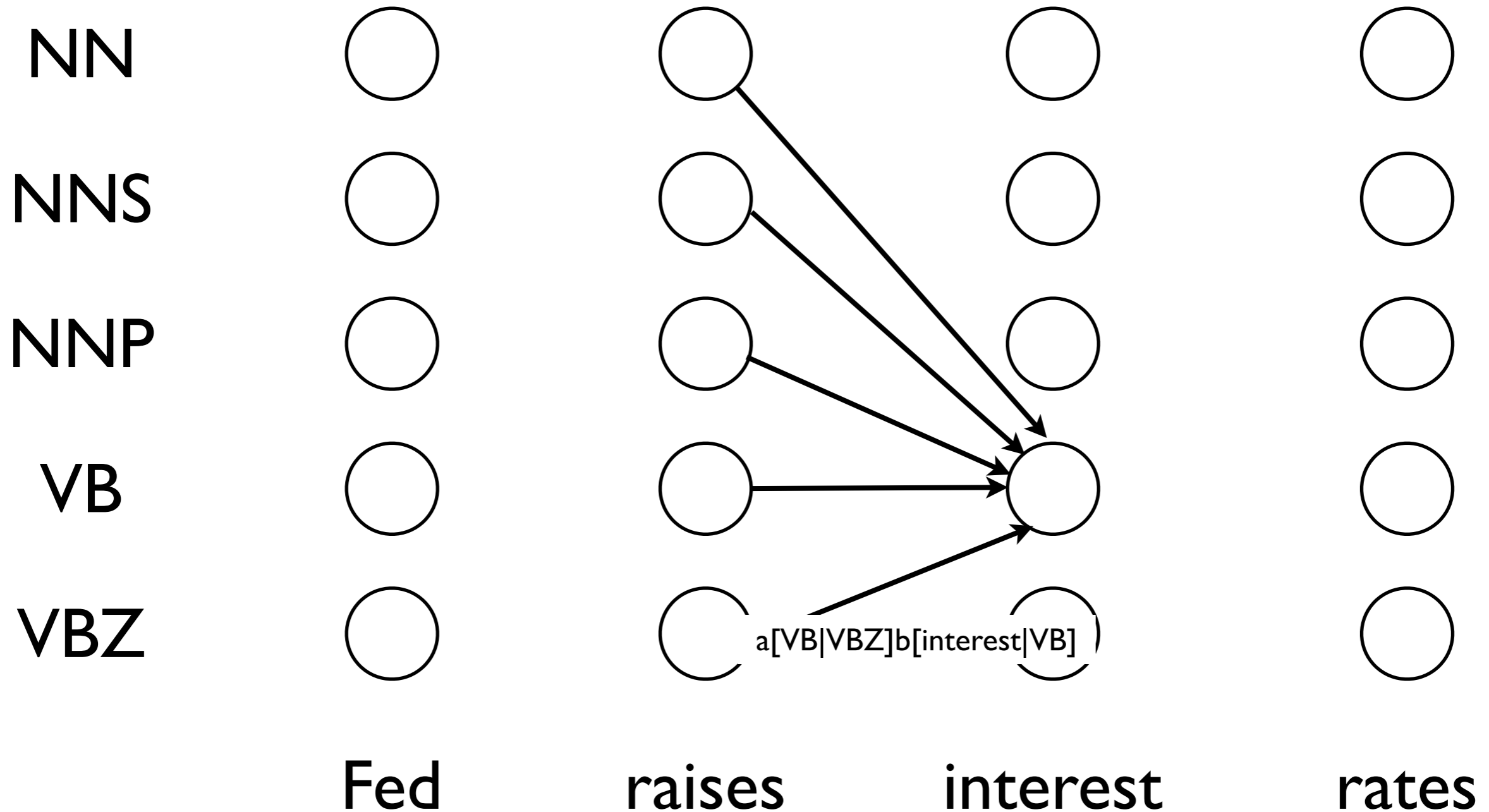
$$\sum_{x_1, x_2, \dots, x_T} P(x_1, x_2, \dots, x_T, O \mid \mu)$$

Suspiciously similar to  $\max_{x_1, x_2, \dots, x_T} P(x_1, x_2, \dots, x_T, O \mid \mu)$

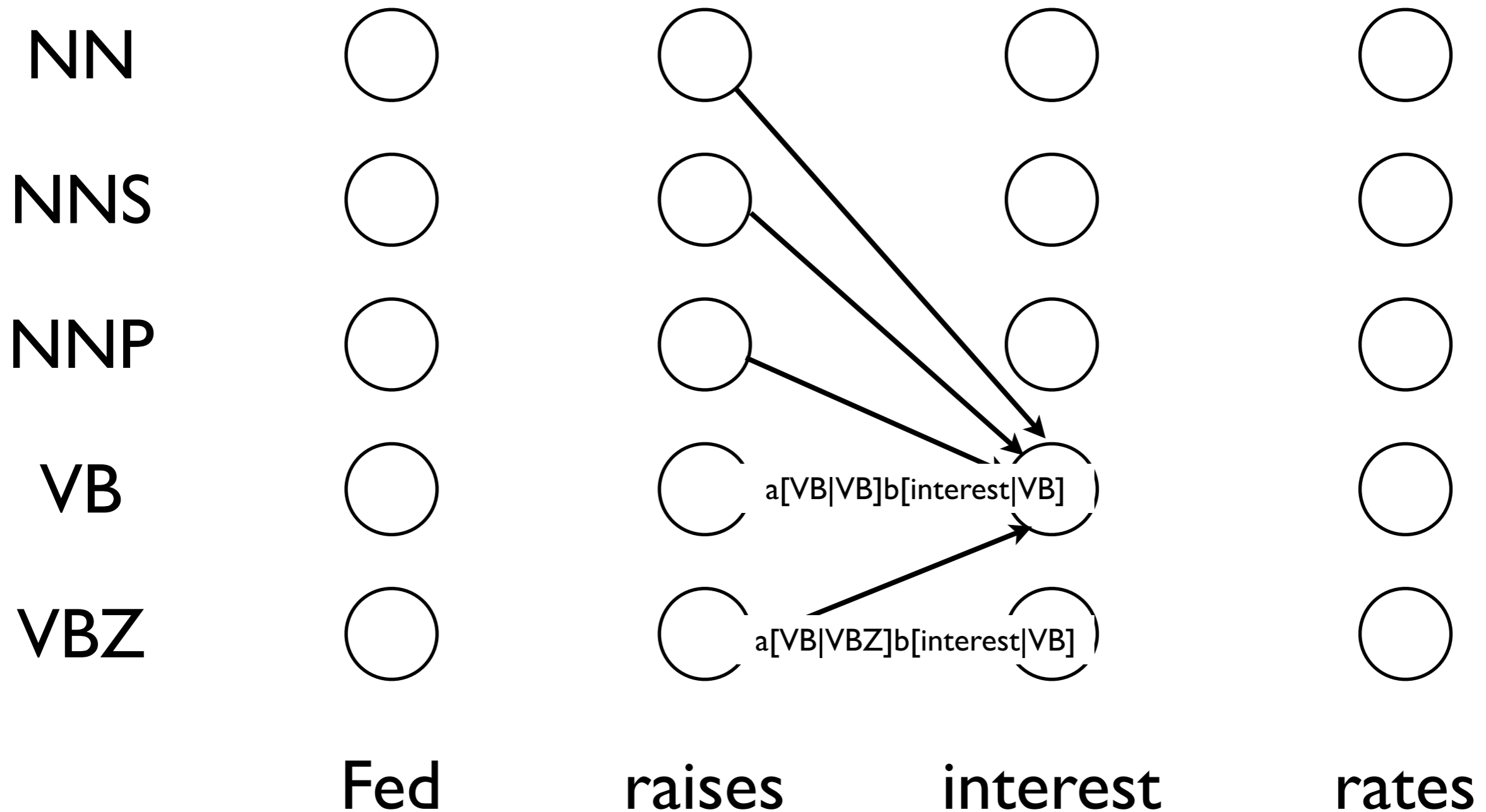
# Viterbi Algorithm (Tagging)



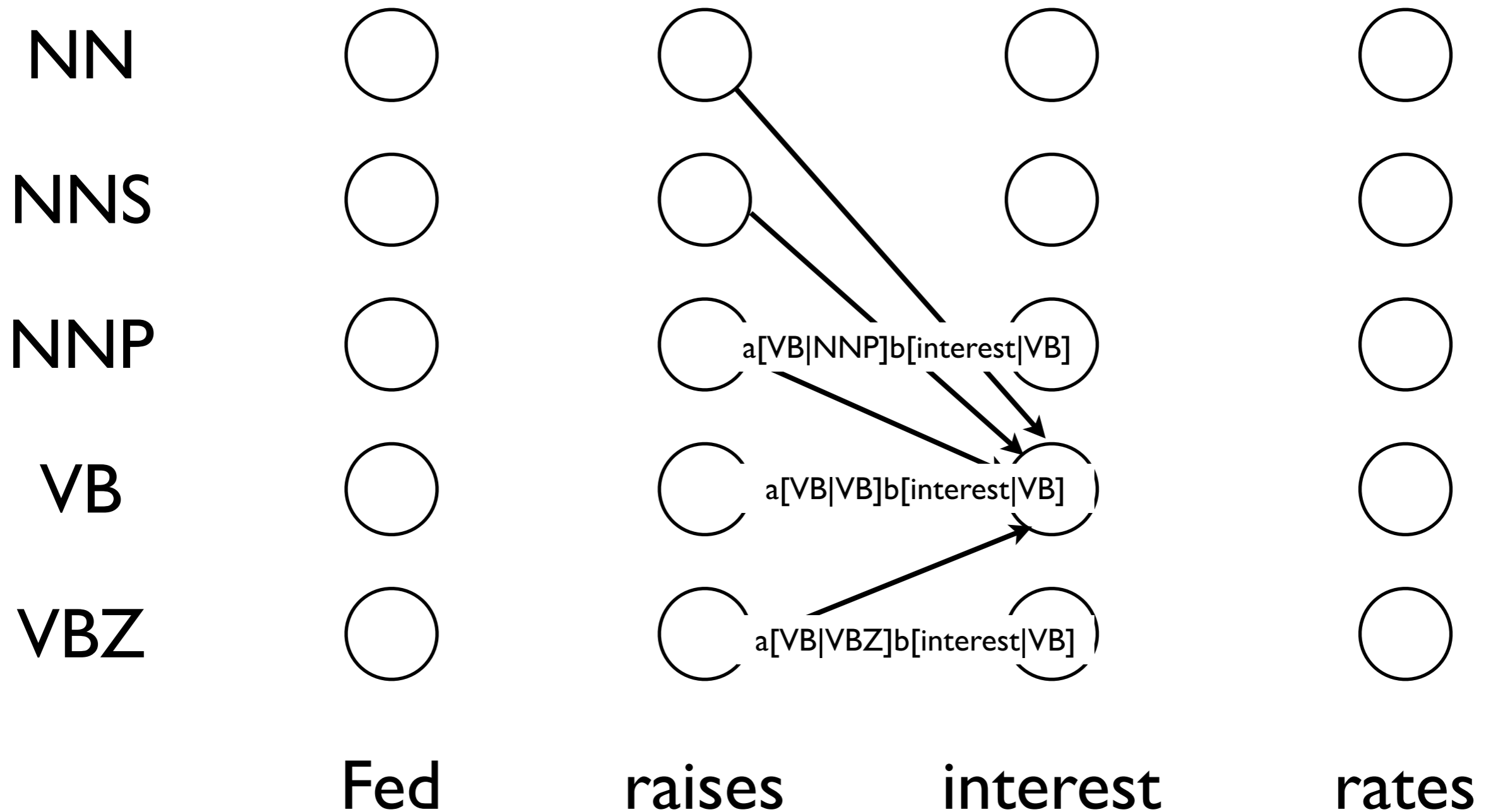
# Viterbi Algorithm (Tagging)



# Viterbi Algorithm (Tagging)

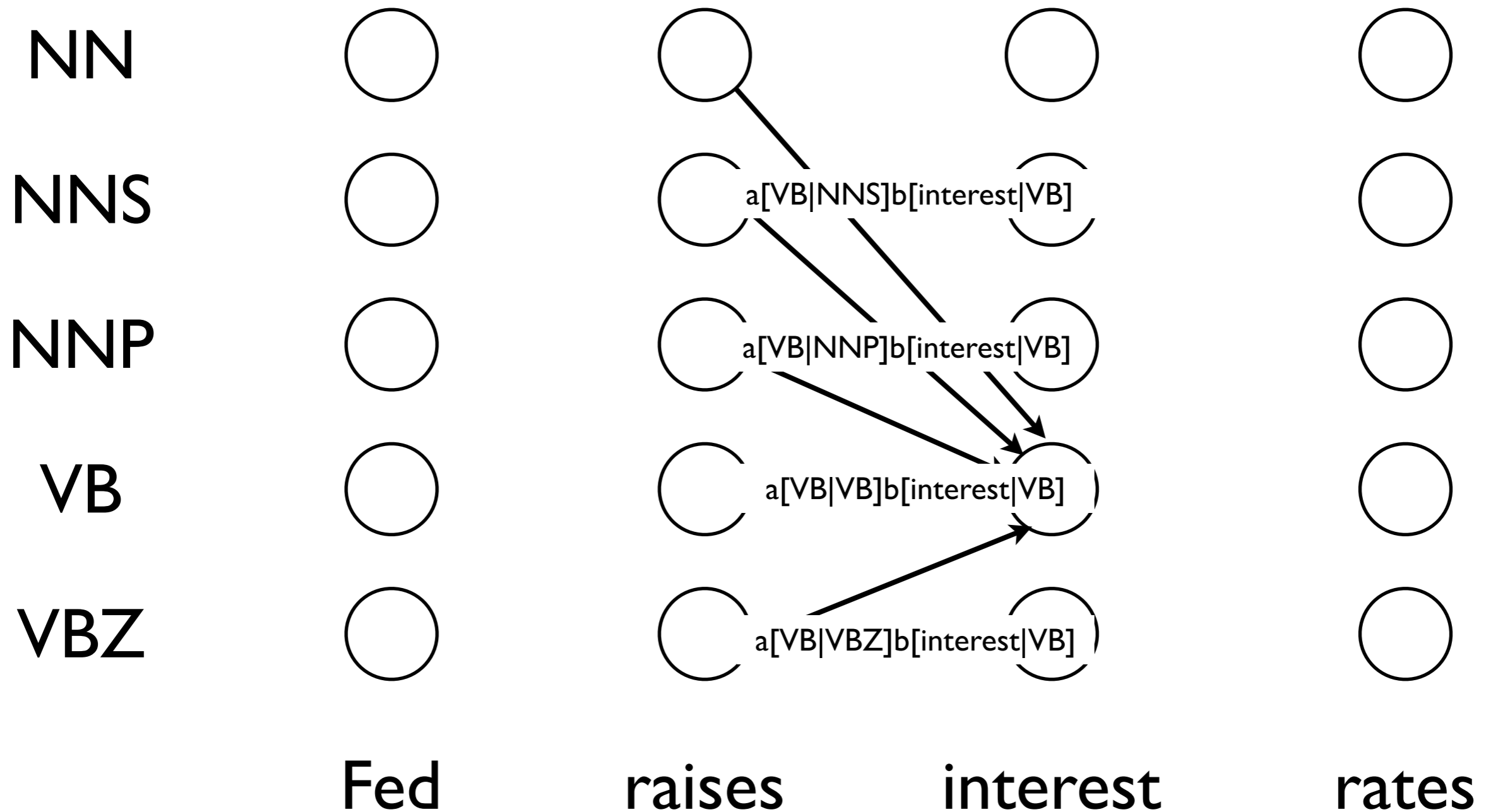


# Viterbi Algorithm (Tagging)

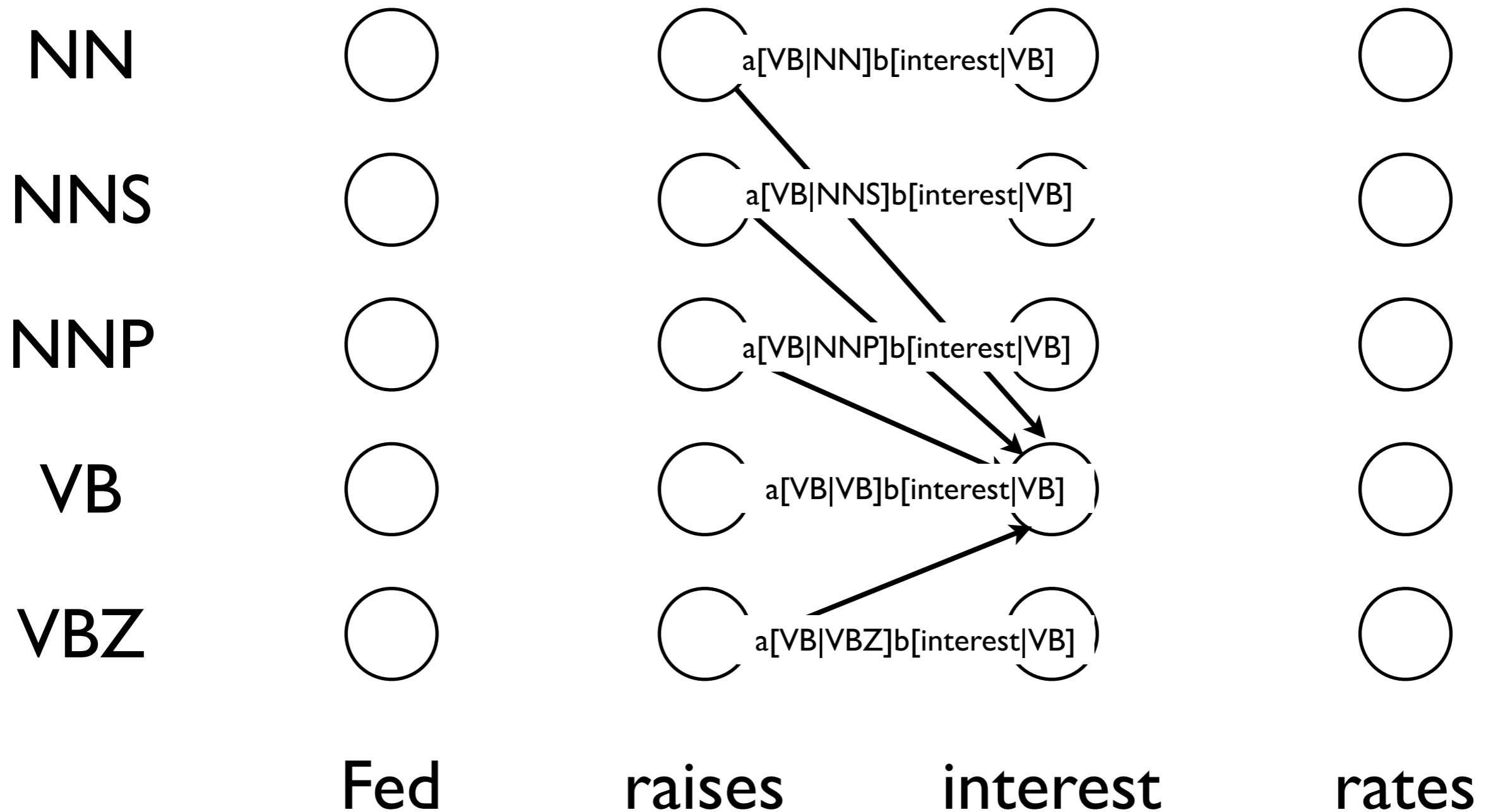




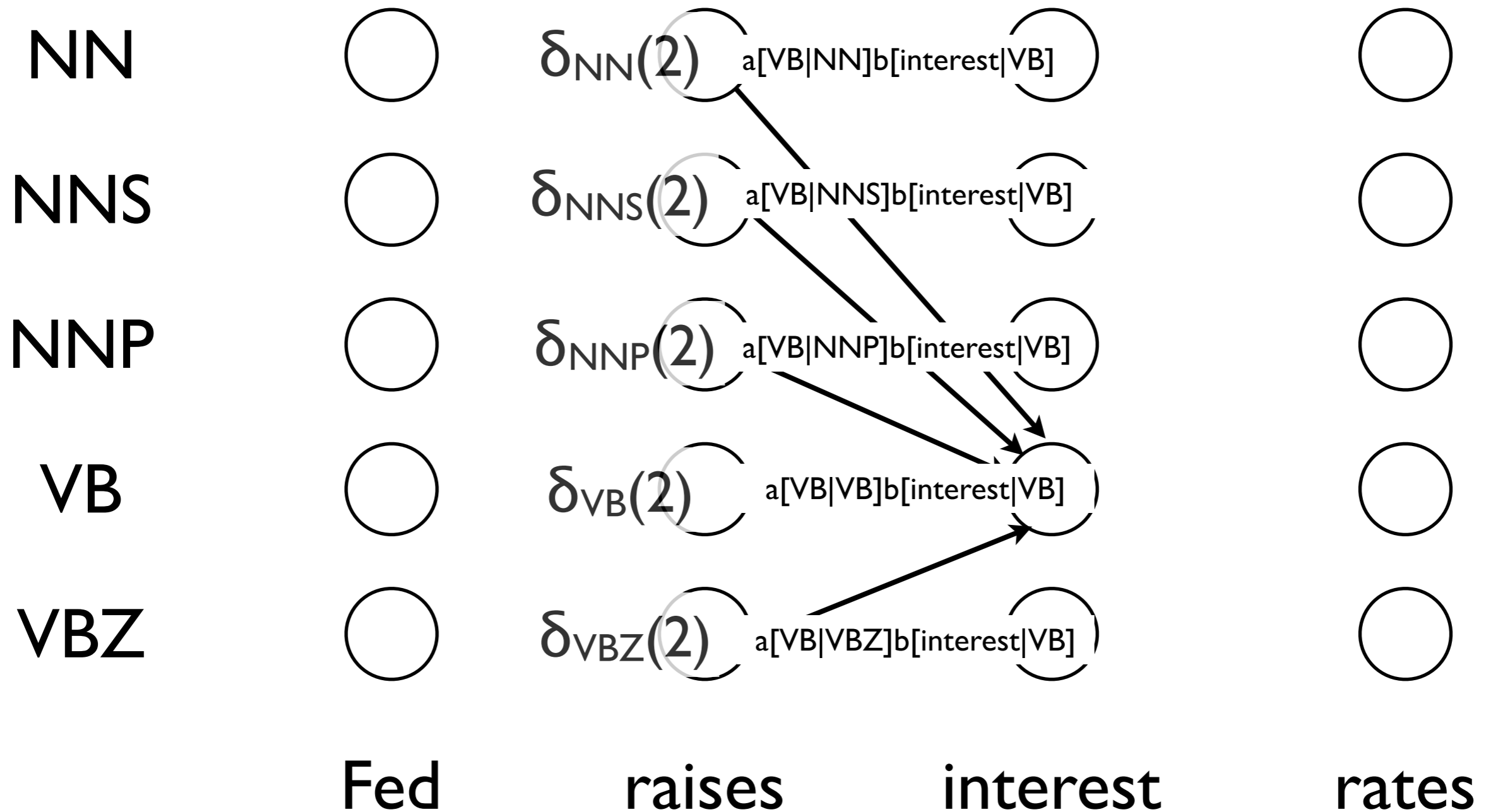
# Viterbi Algorithm (Tagging)



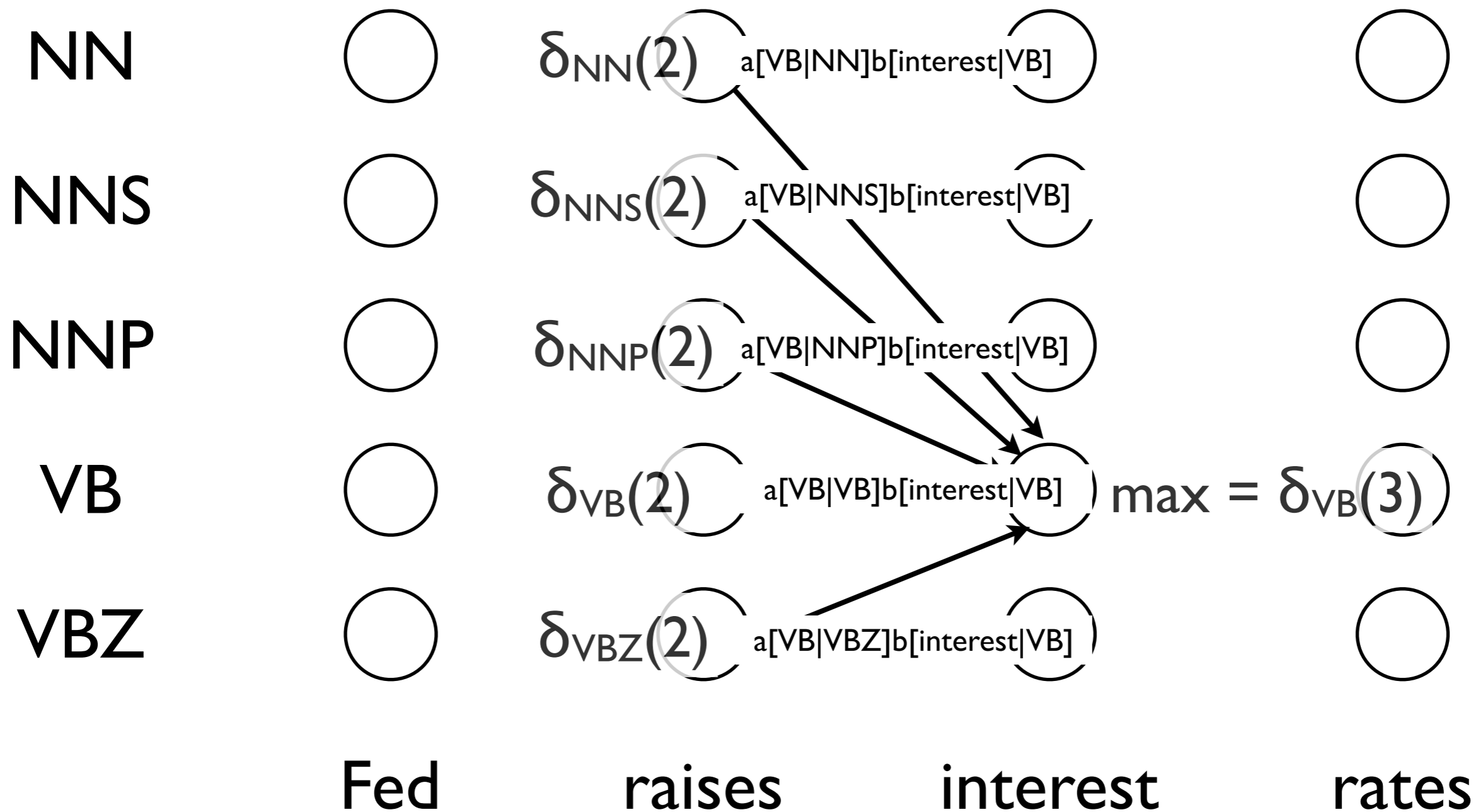
# Viterbi Algorithm (Tagging)



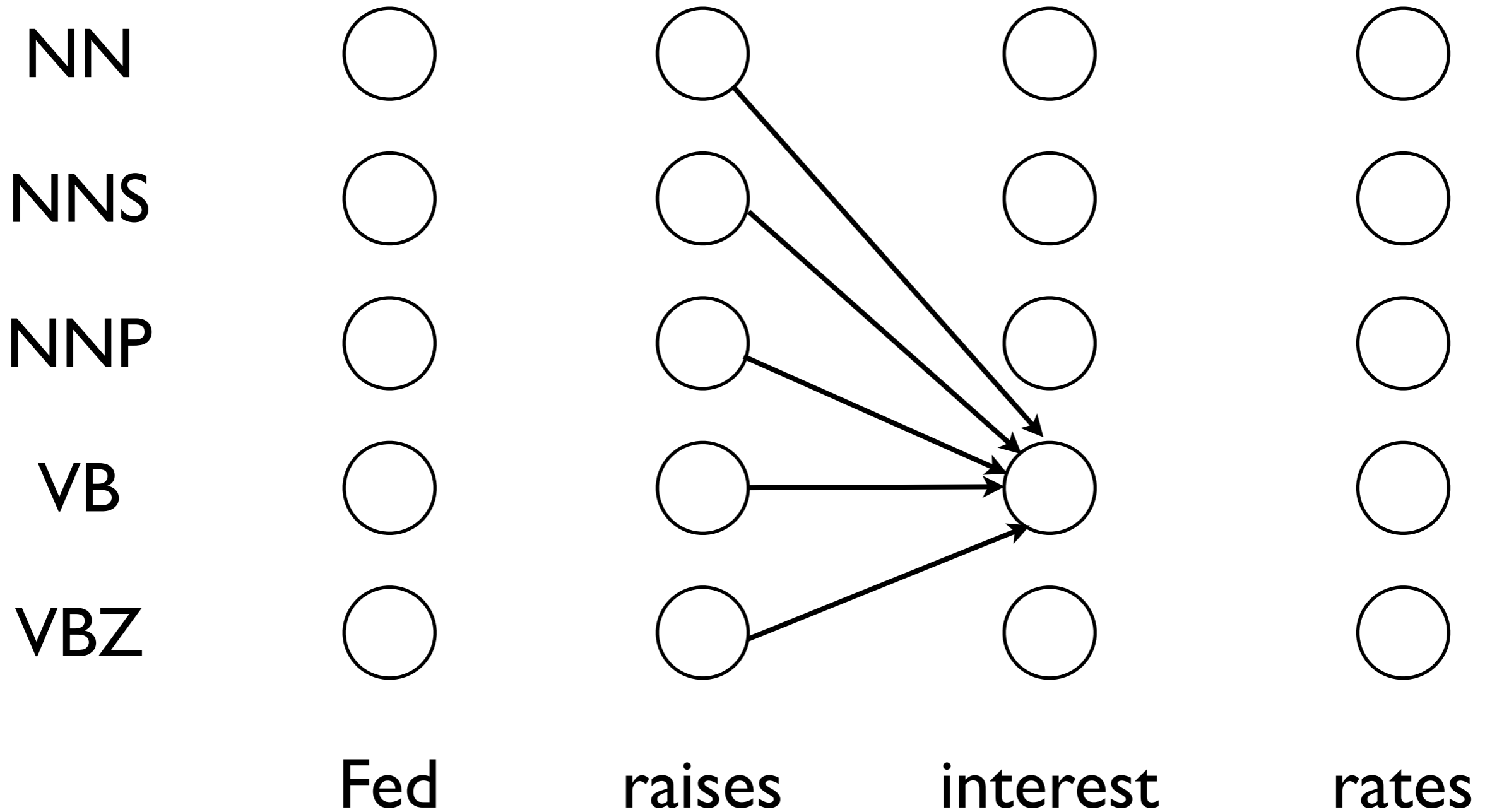
# Viterbi Algorithm (Tagging)



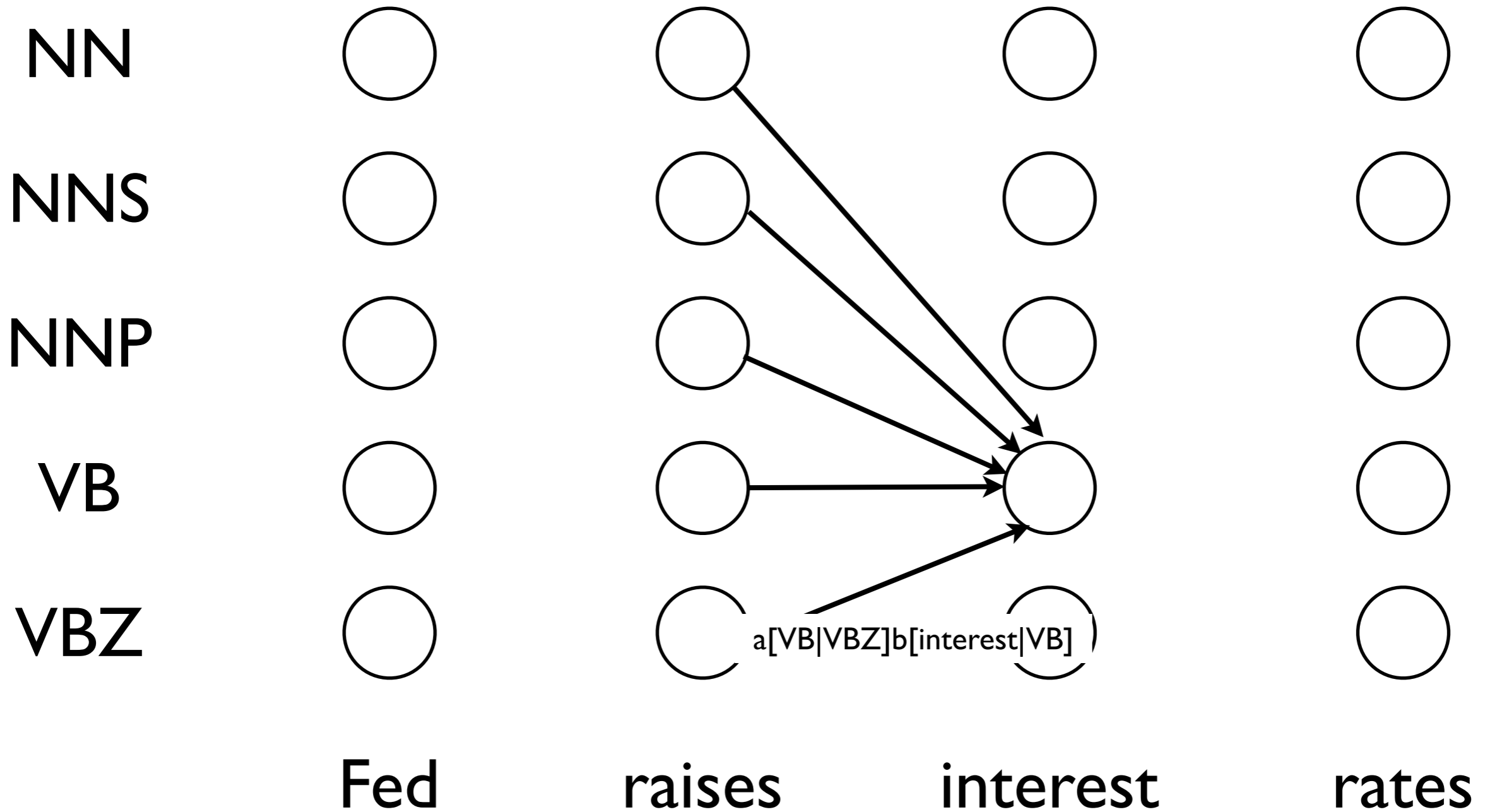
# Viterbi Algorithm (Tagging)



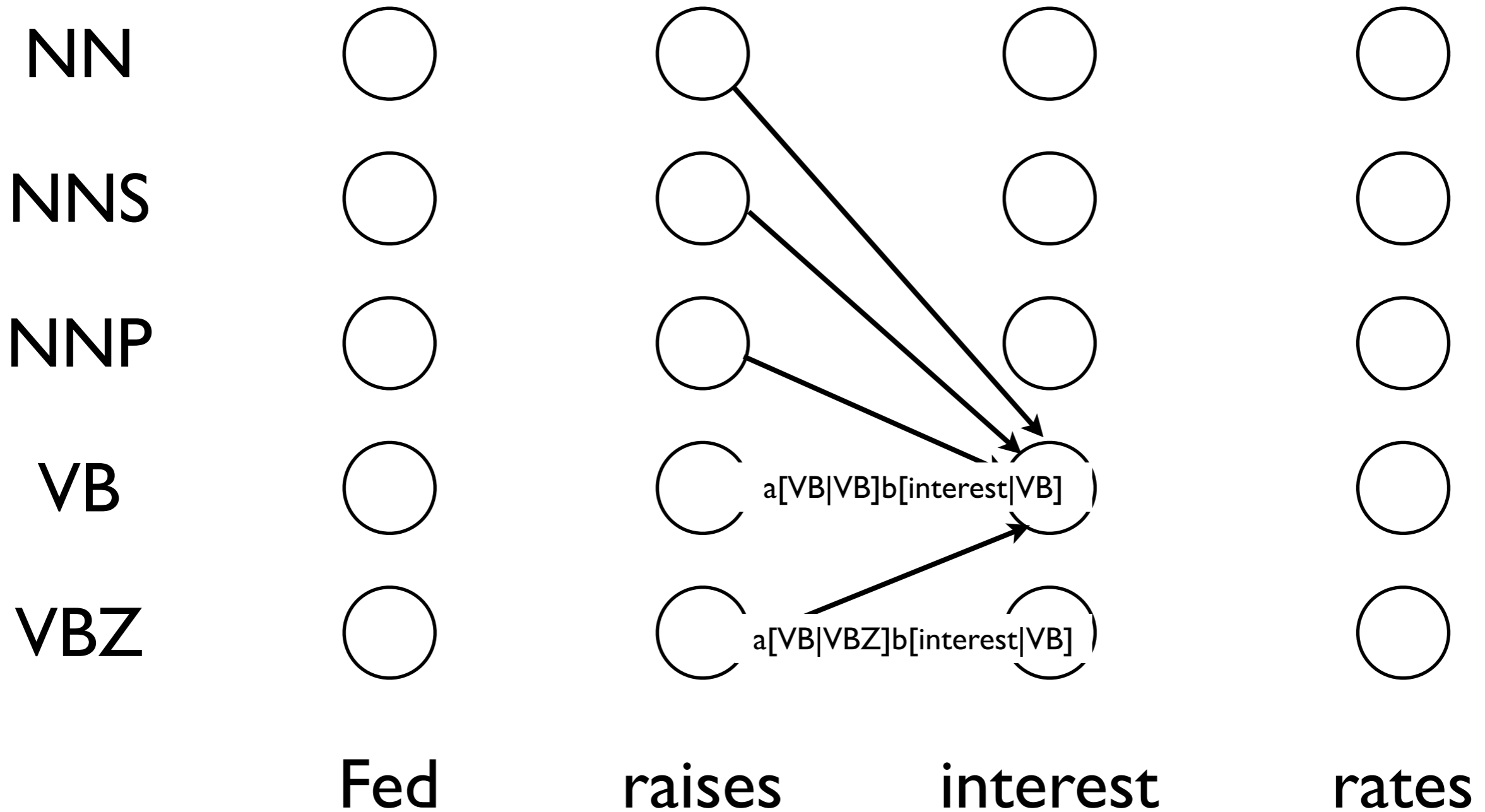
# Forward Algorithm (LM)



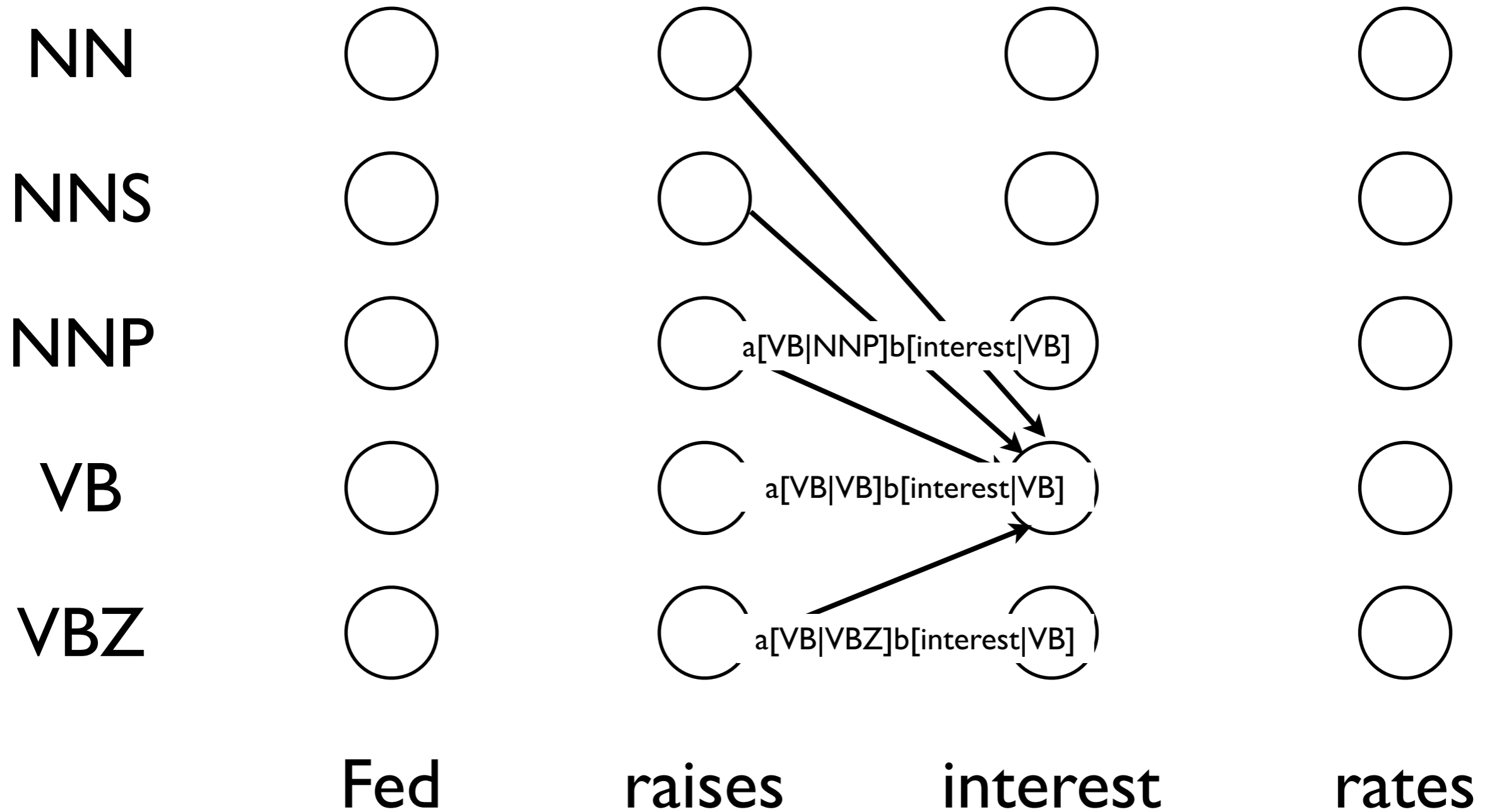
# Forward Algorithm (LM)



# Forward Algorithm (LM)

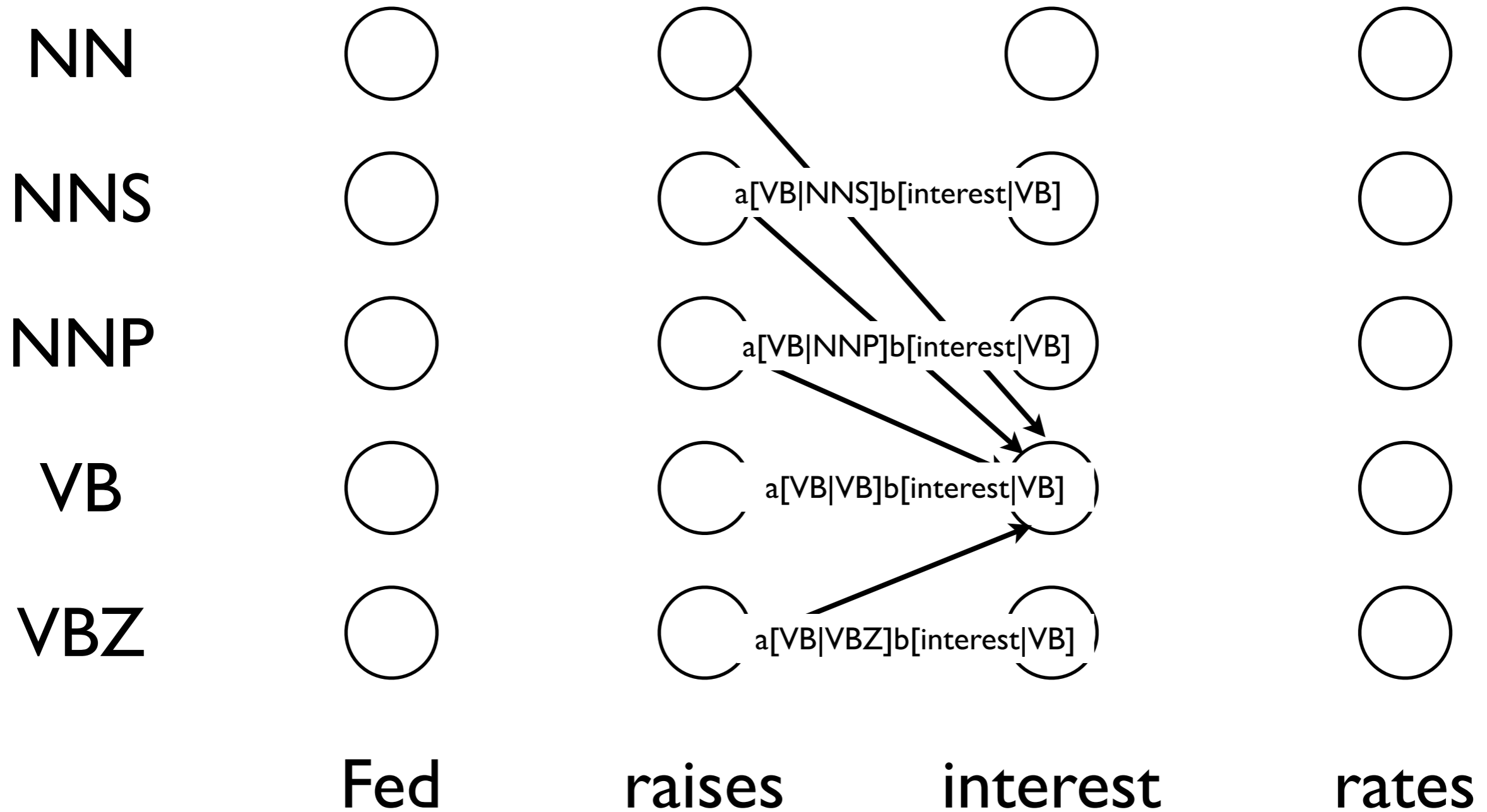


# Forward Algorithm (LM)

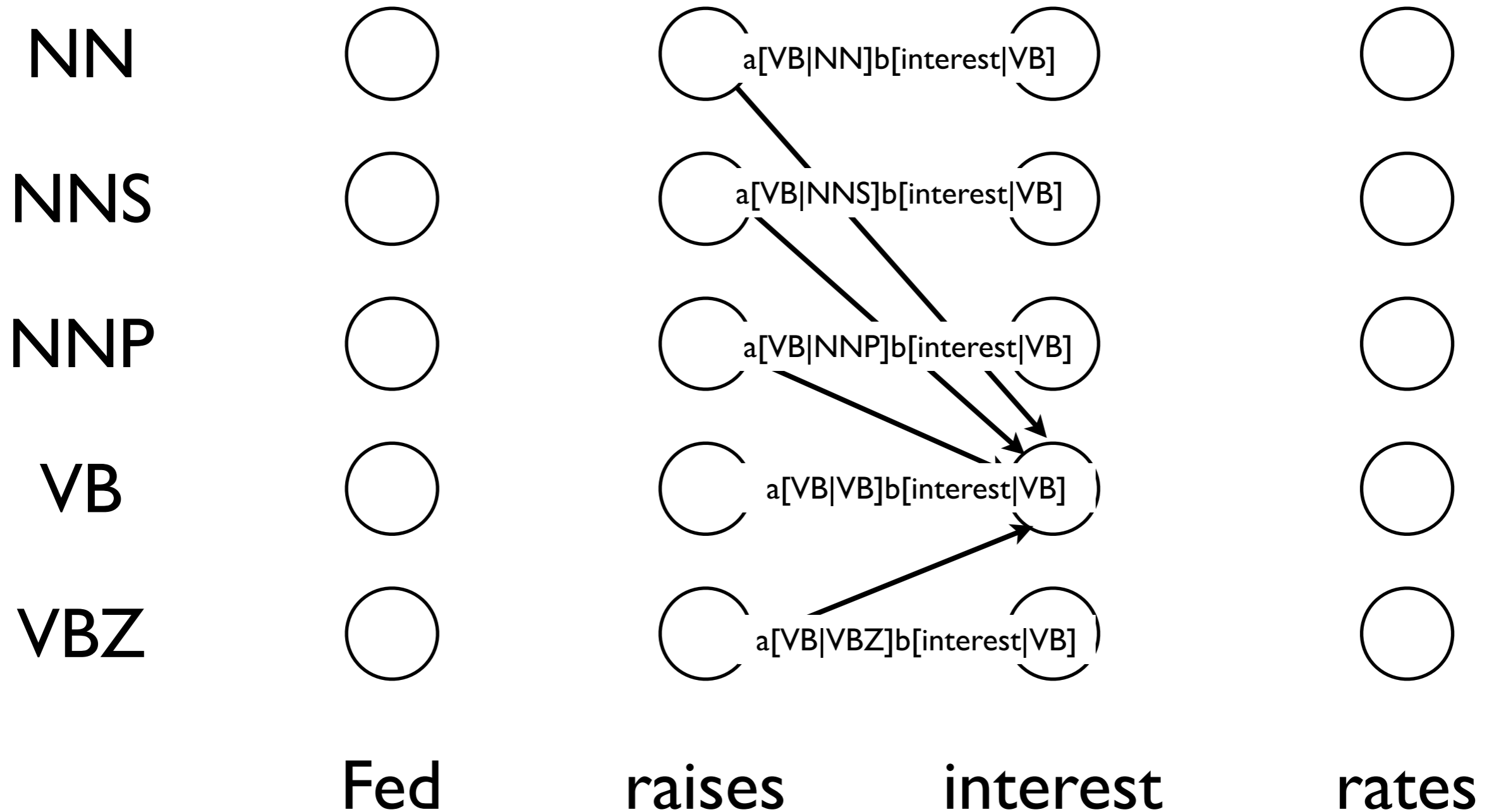




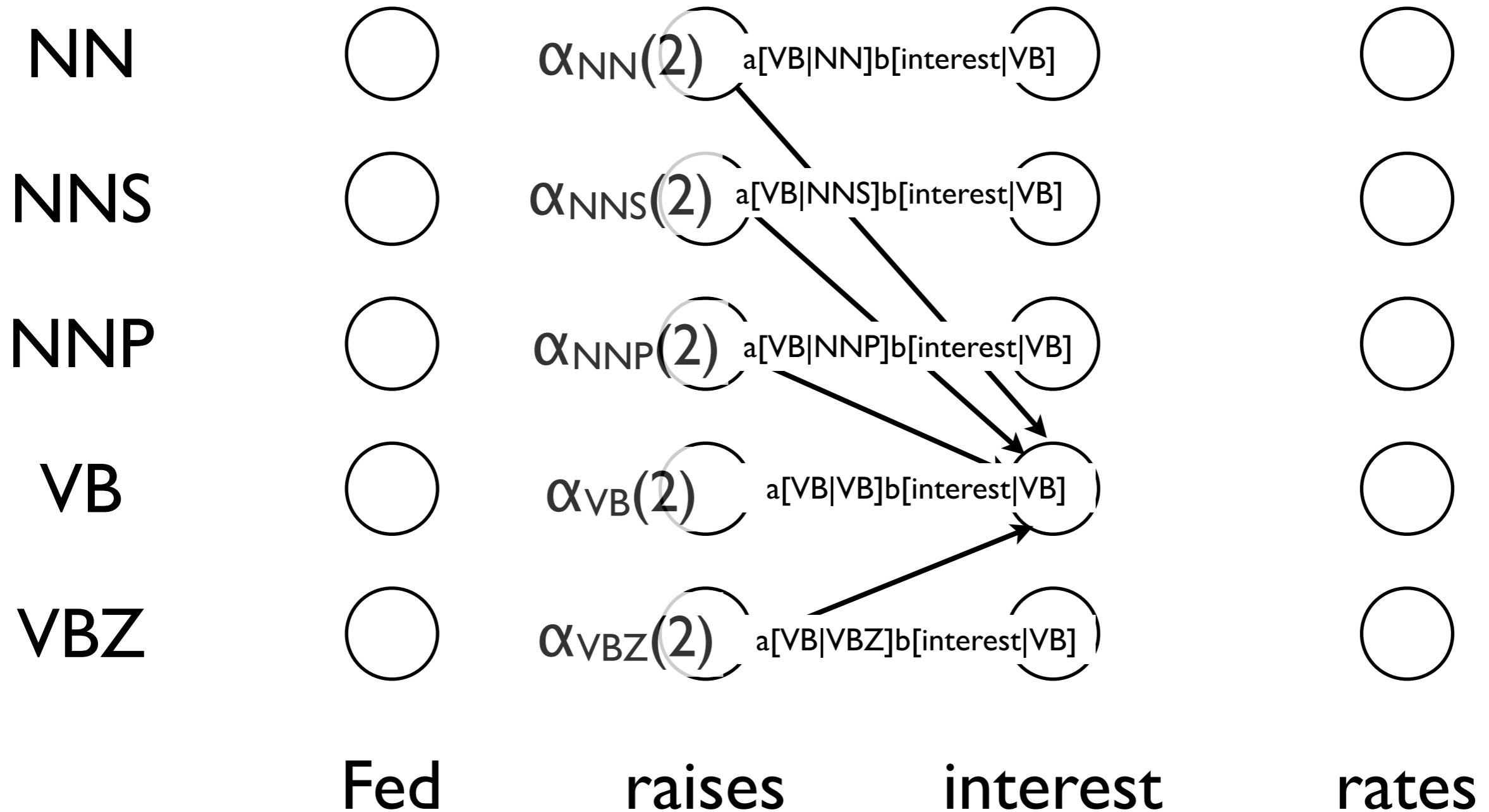
# Forward Algorithm (LM)



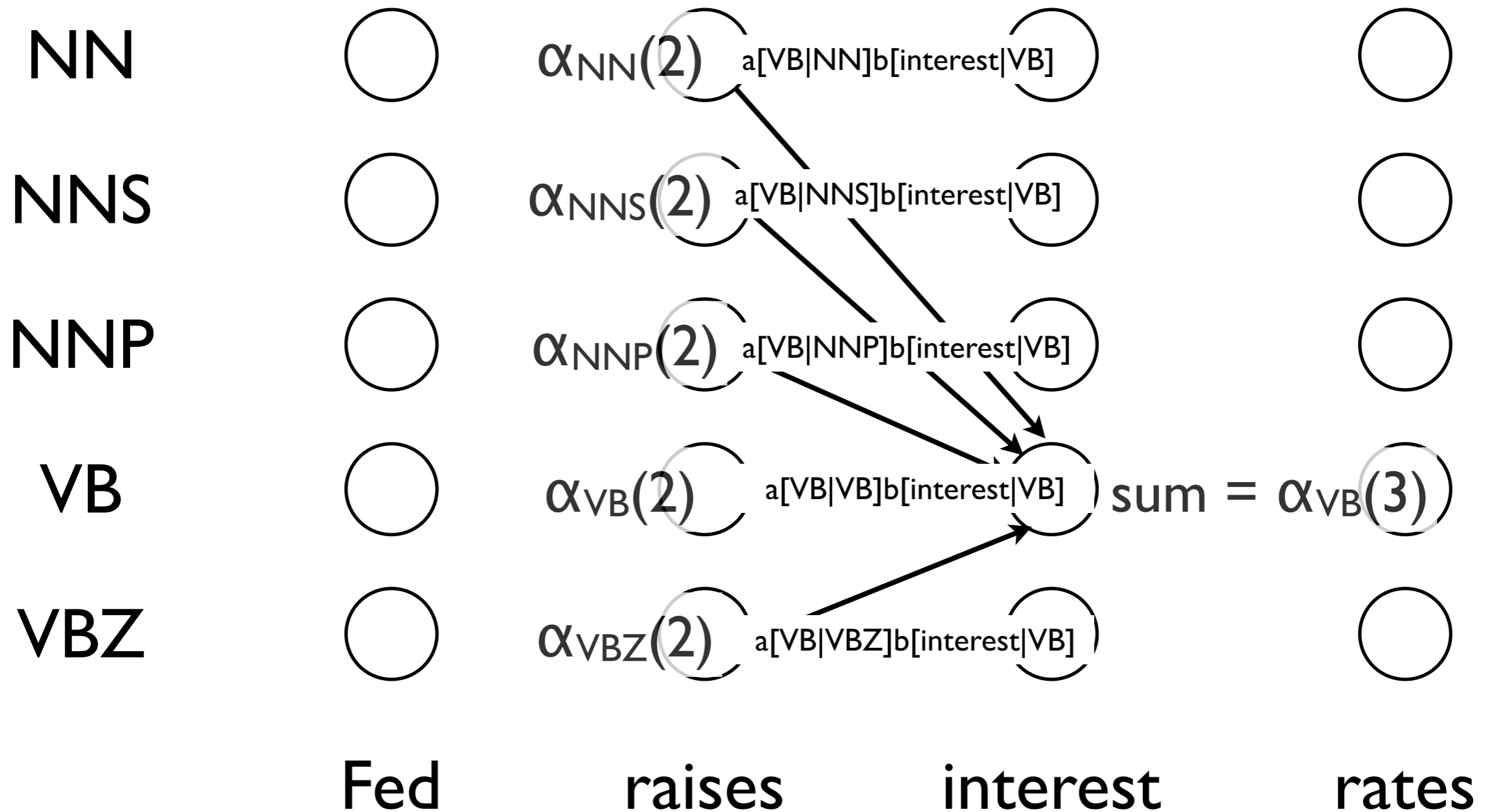
# Forward Algorithm (LM)



# Forward Algorithm (LM)



# Forward Algorithm (LM)



# What Do These Greek Letters Mean?

$$\delta_j(t) = \max_{x_1 \cdots x_{t-1}} P(x_1 \cdots x_{t-1}, o_1 \cdots o_{t-1}, x_t = j \mid \mu)$$

$$\begin{aligned} \alpha_j(t) &= \sum_{x_1 \cdots x_{t-1}} P(x_1 \cdots x_{t-1}, o_1 \cdots o_{t-1}, x_t = j \mid \mu) \\ &= P(o_1 \cdots o_{t-1}, x_t = j \mid \mu) \end{aligned}$$

# What Do These Greek Letters Mean?

Probability of the best path from the beginning to word  $t$  such that word  $t$  has tag  $j$

$$\delta_j(t) = \max_{x_1 \cdots x_{t-1}} P(x_1 \cdots x_{t-1}, o_1 \cdots o_{t-1}, x_t = j \mid \mu)$$

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Probability of all paths from the beginning to word  $t$  such that word  $t$  has tag  $j$

$$\begin{aligned} \alpha_j(t) &= \sum_{x_1 \cdots x_{t-1}} P(x_1 \cdots x_{t-1}, o_1 \cdots o_{t-1}, x_t = j \mid \mu) \\ &= P(o_1 \cdots o_{t-1}, x_t = j \mid \mu) \end{aligned}$$

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$$\begin{aligned} \alpha_j(t) &= \sum_{x_1 \cdots x_{t-1}} P(x_1 \cdots x_{t-1}, o_1 \cdots o_{t-1}, x_t = j \mid \mu) \\ &= P(o_1 \cdots o_{t-1}, x_t = j \mid \mu) \end{aligned}$$

NOT  
the probability of tag  $j$   
at time  $t$



# HMM Language Modeling

- Probability of observations, summed over all possible ways of tagging that

observation:

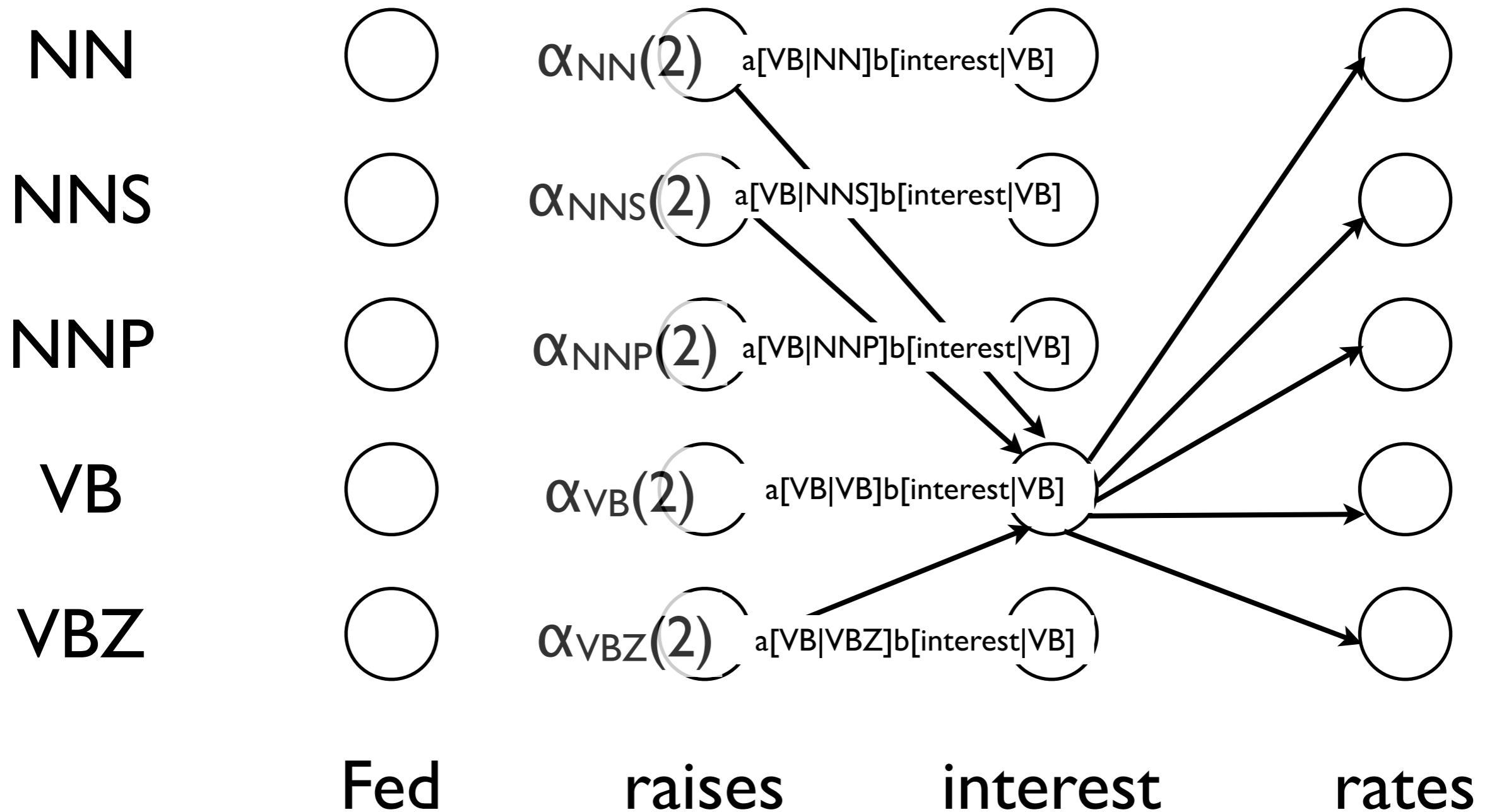
$$\sum_i \alpha_i(T)$$

- This is the sum of all path probabilities in the trellis

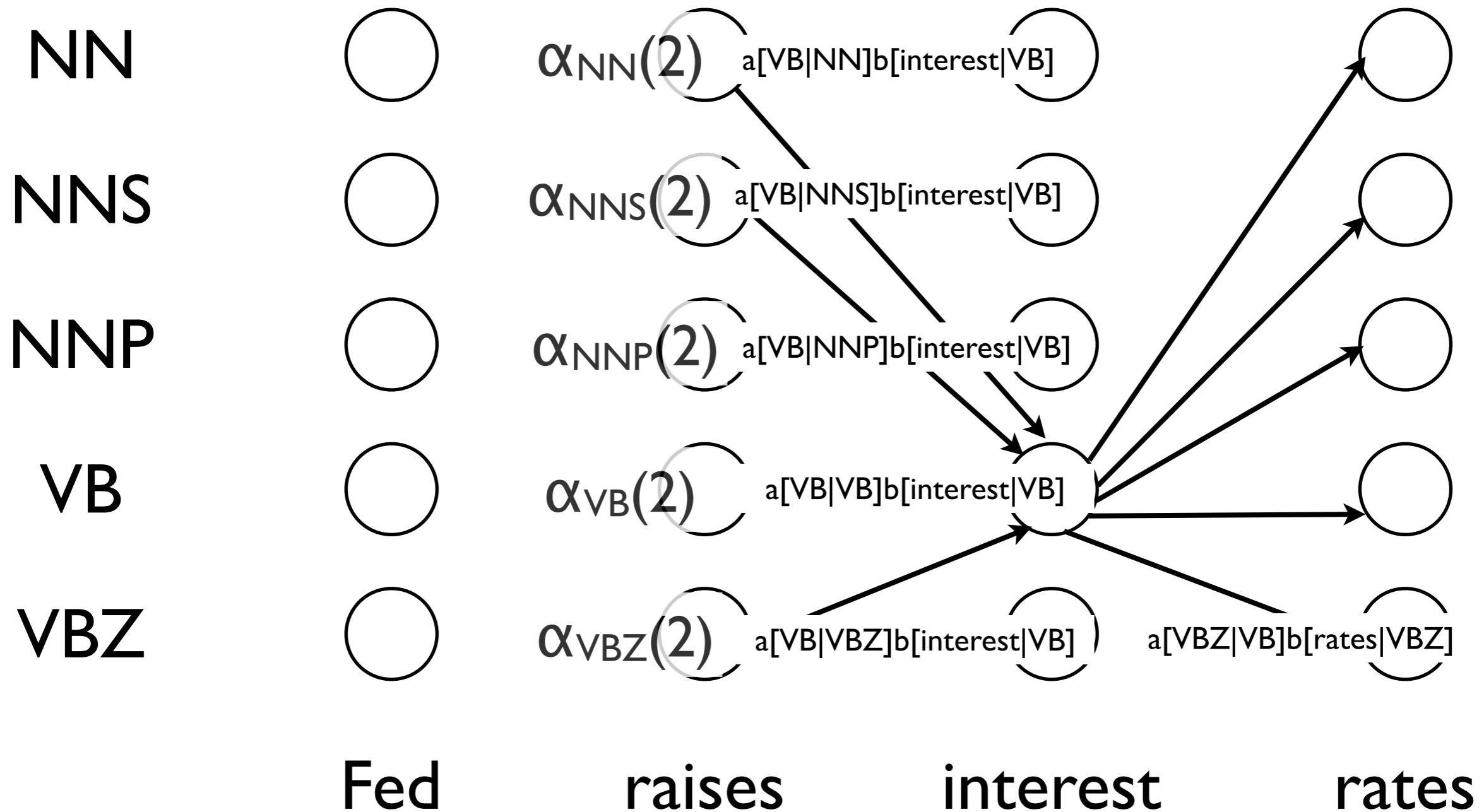
# HMM Parameter Estimation

- Supervised
  - Train on tagged text, test on plain text
  - Maximum likelihood (can be smoothed):
    - $a[\text{VBZ} | \text{NN}] = C(\text{NN}, \text{VBZ}) / C(\text{NN})$
    - $b[\text{rates} | \text{VBZ}] = C(\text{VBZ}, \text{rates}) / C(\text{VBZ})$
- Unsupervised
  - Train and test on plain text
  - What can we do?

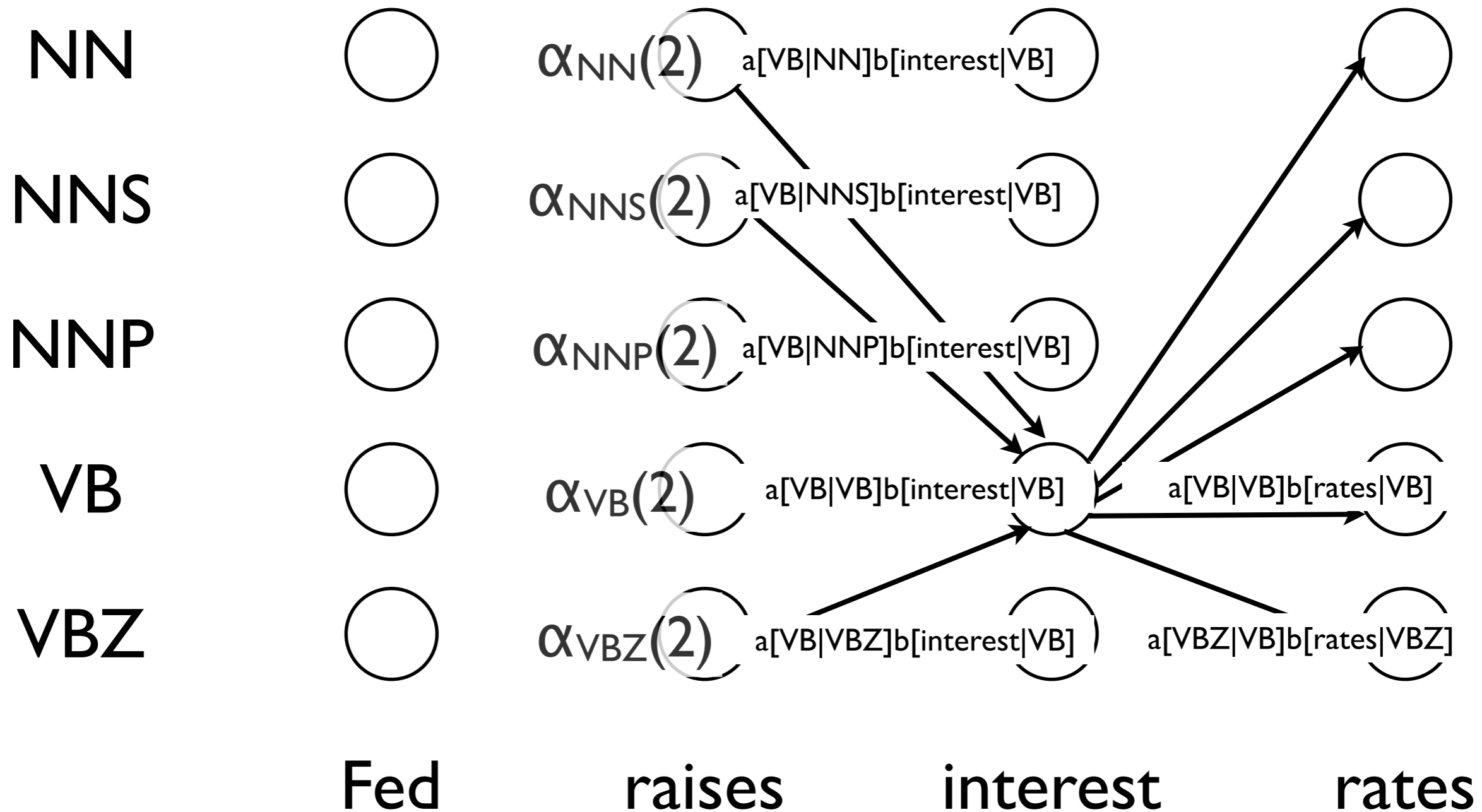
# Forward-Backward Algorithm



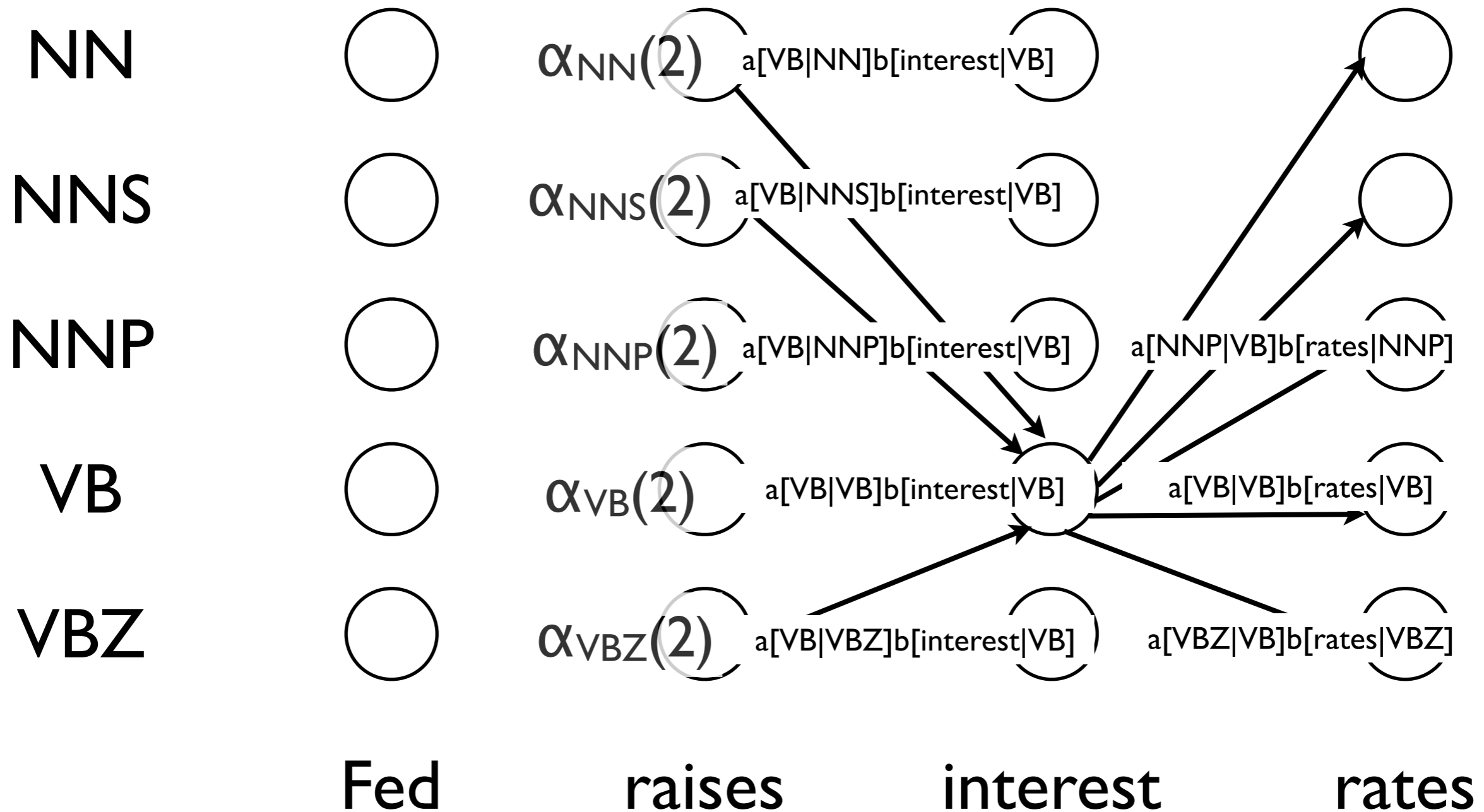
# Forward-Backward Algorithm



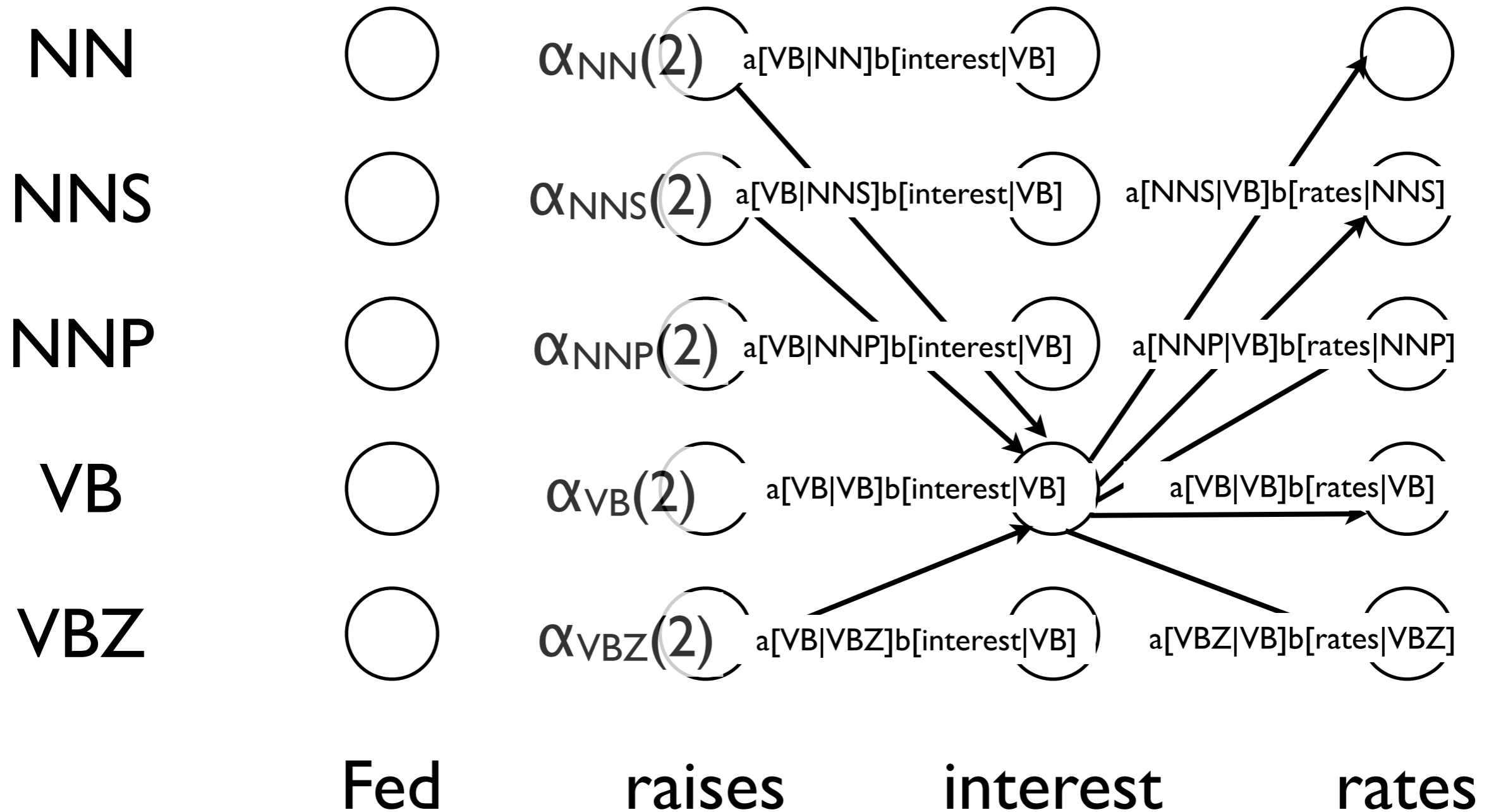
# Forward-Backward Algorithm



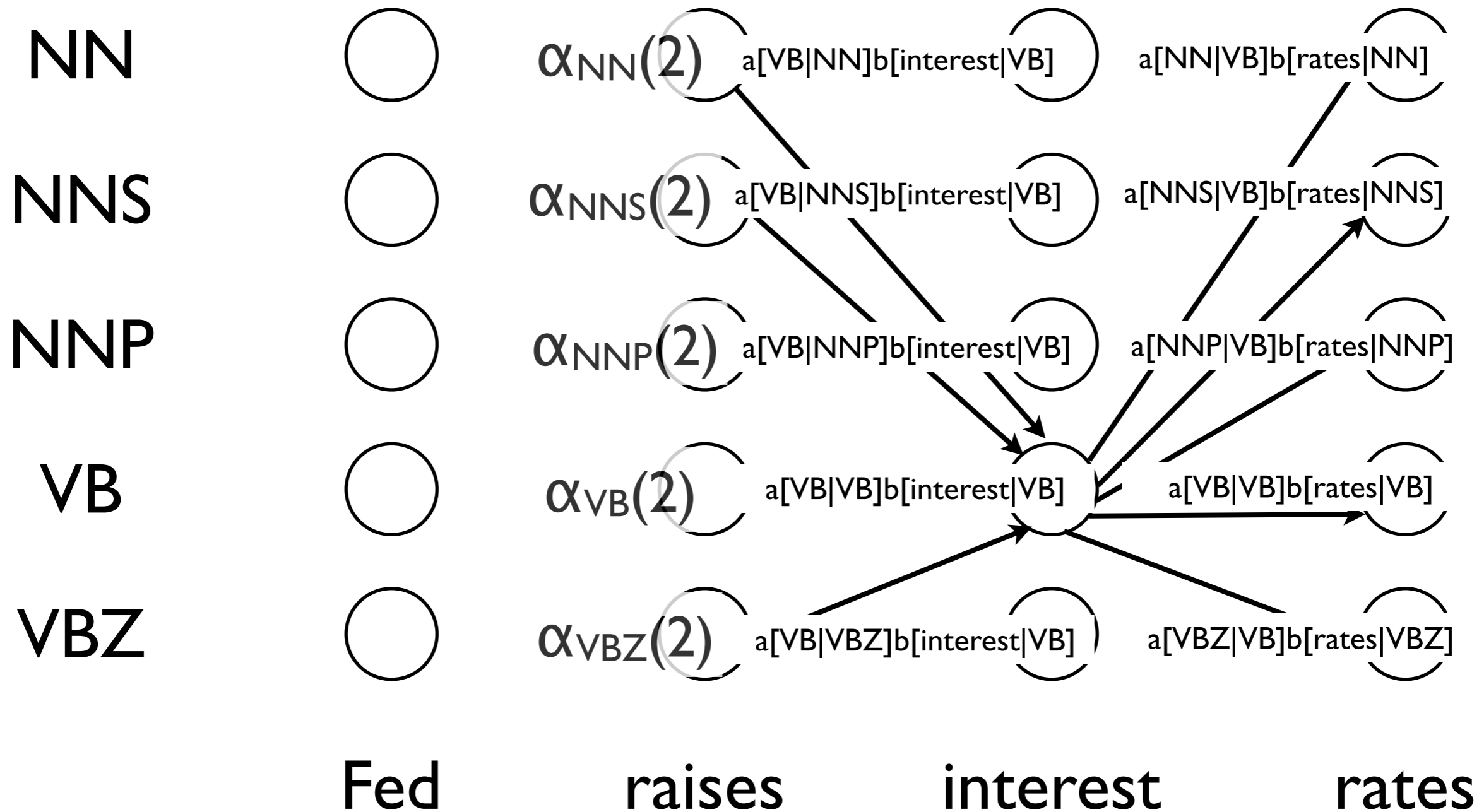
# Forward-Backward Algorithm



# Forward-Backward Algorithm

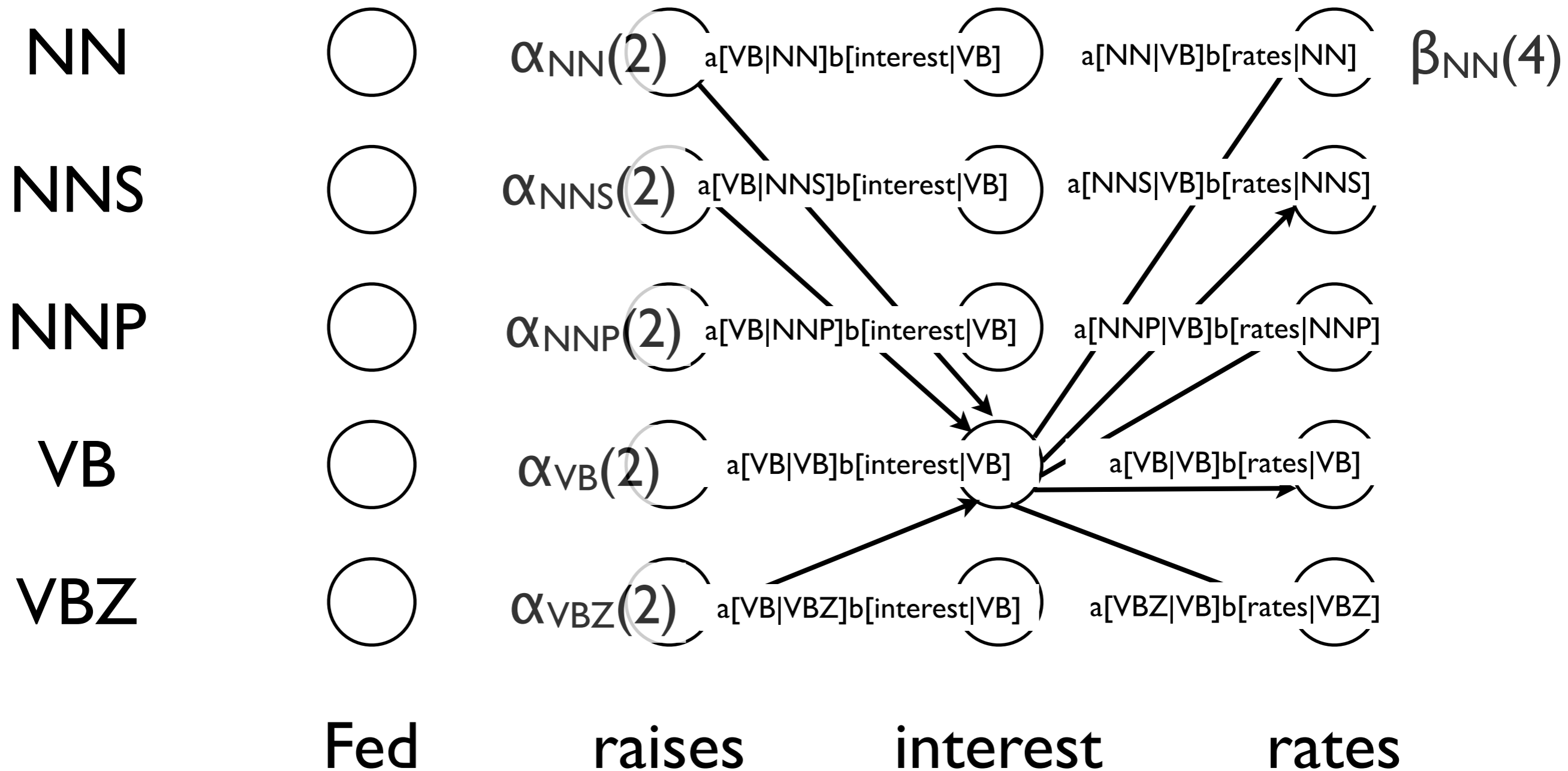


# Forward-Backward Algorithm

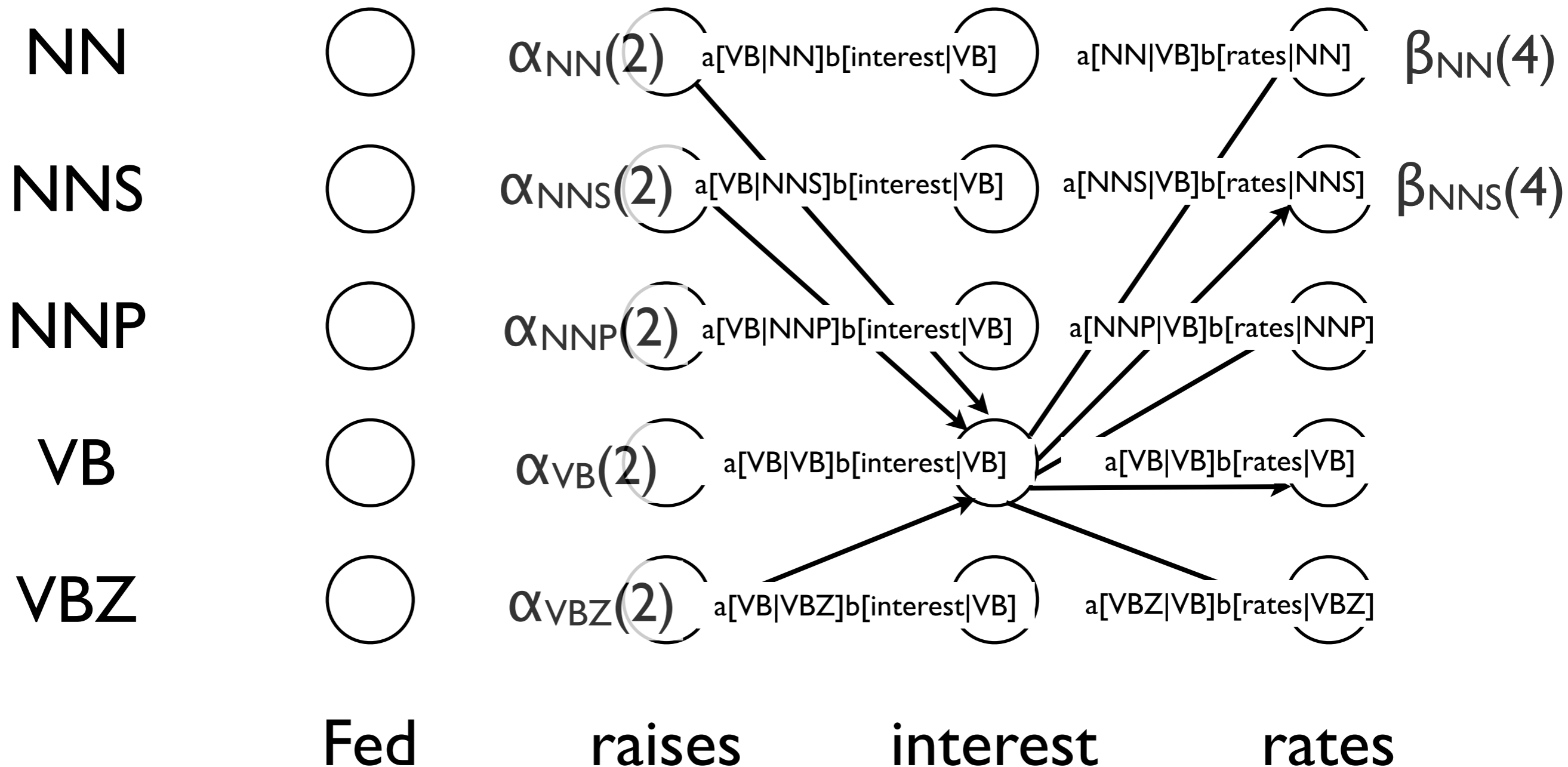




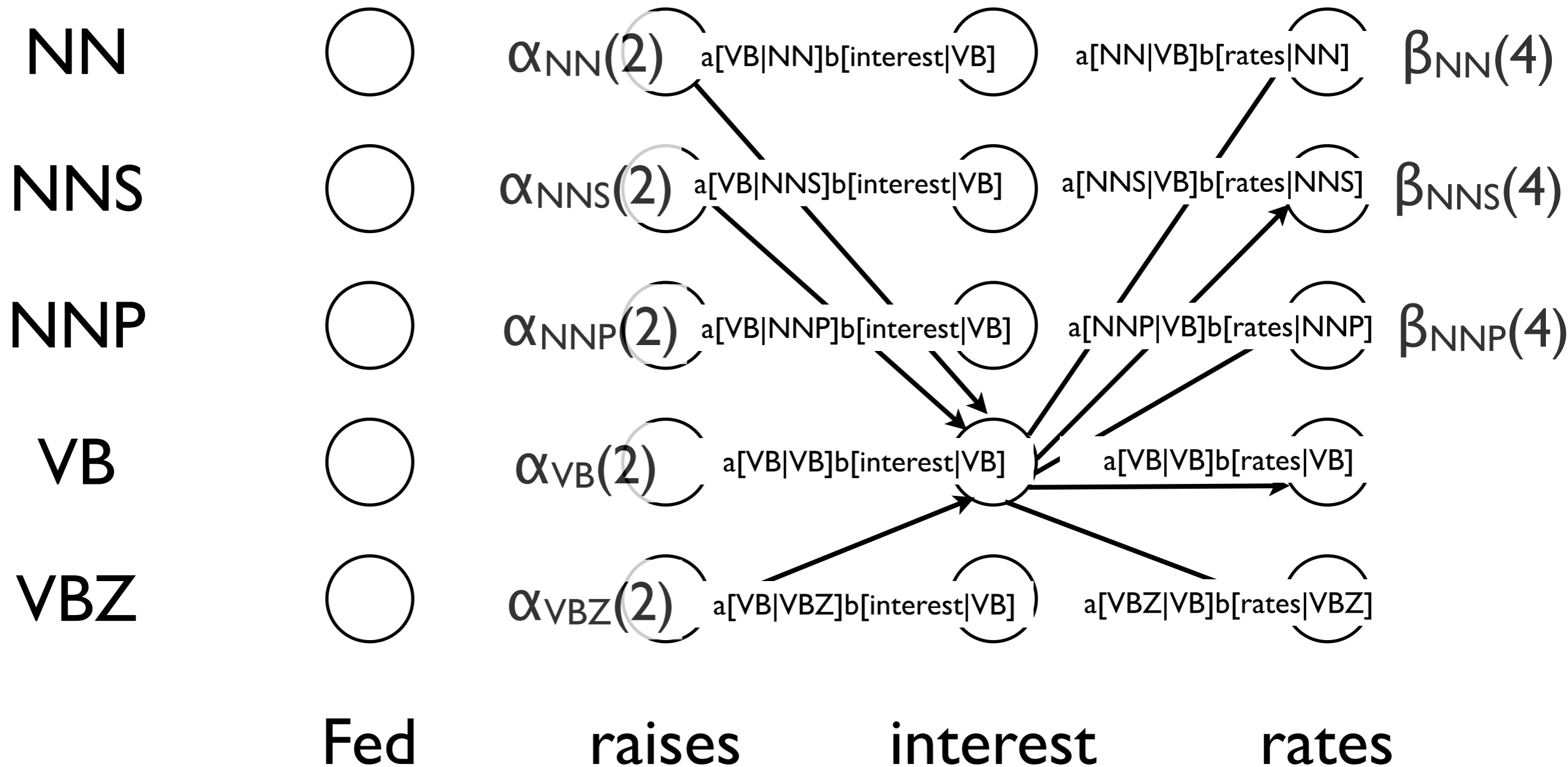
# Forward-Backward Algorithm



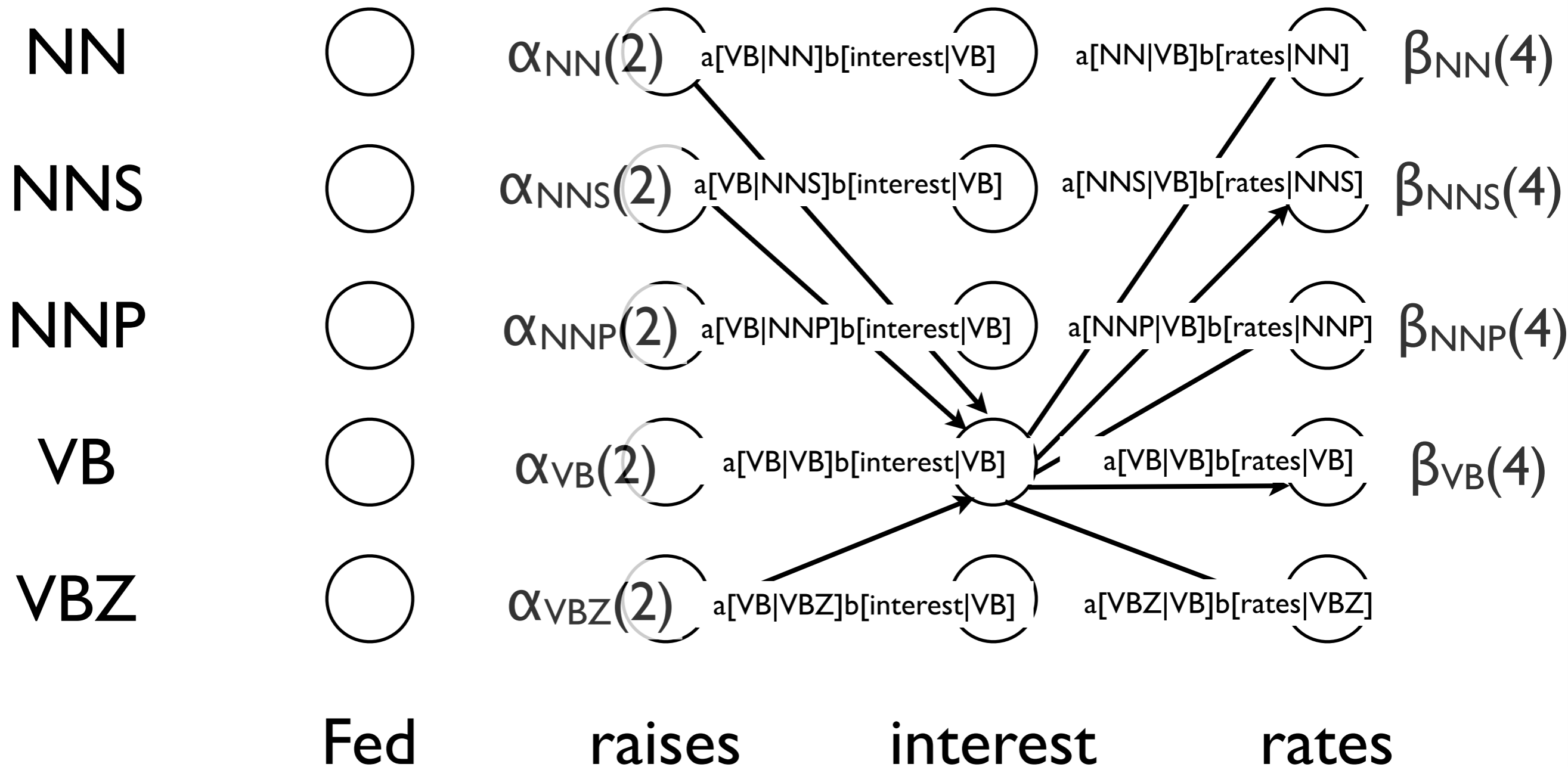
# Forward-Backward Algorithm



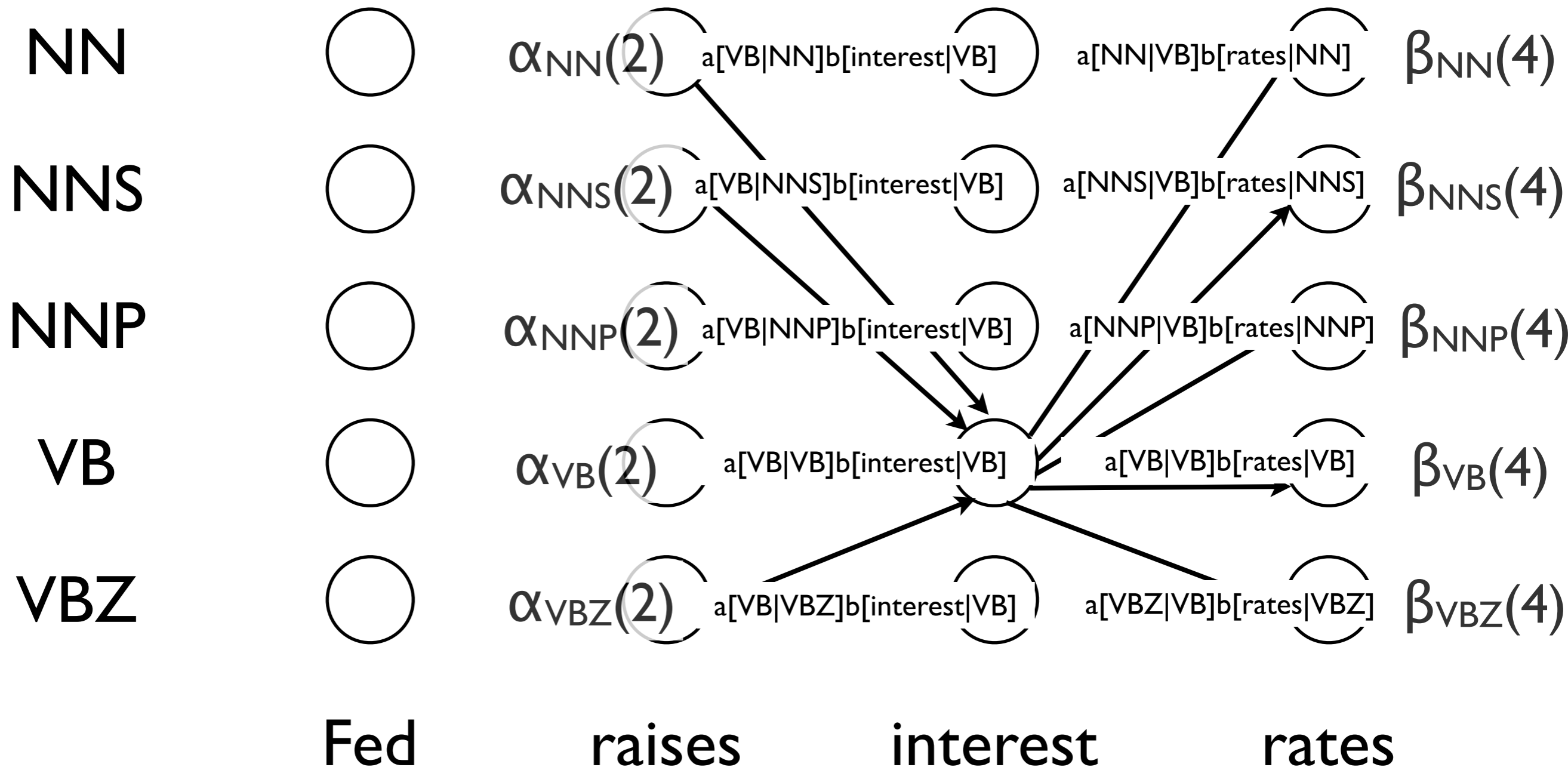
# Forward-Backward Algorithm



# Forward-Backward Algorithm



# Forward-Backward Algorithm



# Forward-Backward Algorithm

$$P(o_1 \cdots o_{t-1}, x_t = j \mid \mu) = \alpha_j(t)$$

$$P(o_t \cdots o_T \mid x_t = j, \mu) = \beta_j(t)$$

$$P(o_1 \cdots o_T, x_t = j \mid \mu) = \alpha_j(t)\beta_j(t)$$

$$P(x_t = j \mid O, \mu) = \frac{P(x_t = j, O \mid \mu)}{P(O \mid \mu)} = \frac{j(t) \ j(t)}{\#(T)}$$

$$\begin{aligned} P(x_t = i, x_{t+1} = j \mid O, \mu) &= \frac{P(x_t = i, x_{t+1} = j, O \mid \mu)}{P(O \mid \mu)} \\ &= \frac{i(t)a[j \mid i]b[o_t \mid j] \ j(t+1)}{\#(T)} \end{aligned}$$

# Expectation Maximization (EM)

- Iterative algorithm to maximize likelihood of observed data in the presence of hidden data (e.g., tags)
- Choose an initial model  $\mu$
- **Expectation step:** find the expected value of hidden variables given current  $\mu$
- **Maximization step:** choose new  $\mu$  to maximize probability of hidden and observed data
- Guaranteed to increase likelihood
- Not guaranteed to find global maximum

# Supervised vs. Unsupervised

Supervised	Unsupervised
Annotated training text	Plain text
Simple count/normalize	EM
Fixed tag set	Set during training
Training reads data once	Training needs multiple passes



# Logarithms for Precision

$$P(Y) = p(y_1)p(y_2) \cdots p(y_T)$$

$$\log P(Y) = \log p(y_1) + \log p(y_2) \cdots + \log p(y_T)$$

Increased dynamic range of  $[0, 1]$  to  $[-\infty, 0]$

# Semirings

	$\oplus$	$\otimes$	0	1
Real	+	x	0	1
Max	max	x	0	1
Log	log+	+	$-\infty$	0
“Tropical”	max	+	$-\infty$	0
Shortest path	min	+	$\infty$	0
Boolean	$\vee$	$\wedge$	F	T