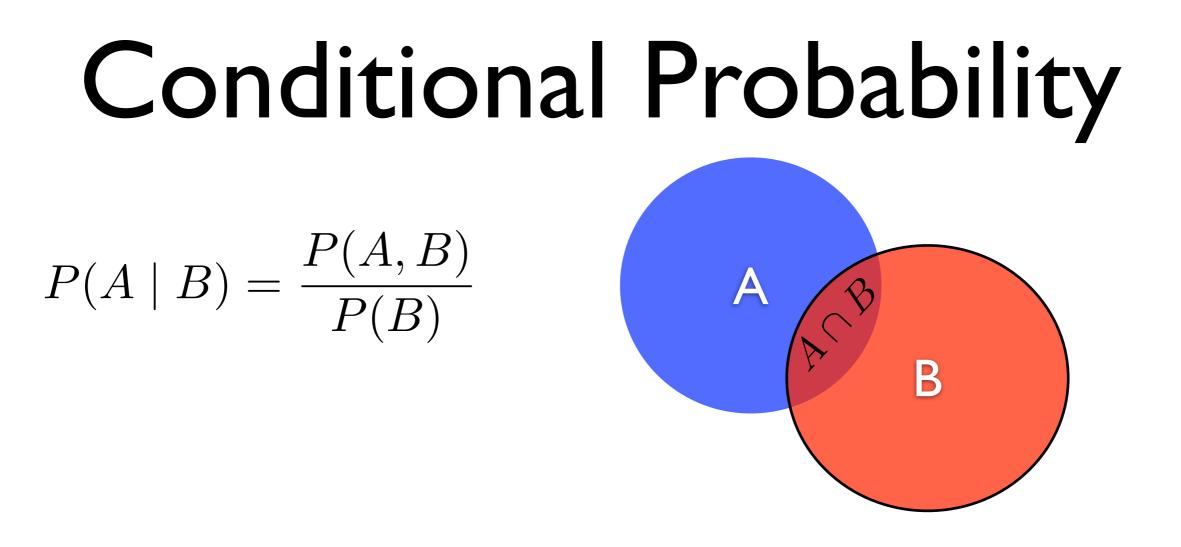
Review Slides

Introduction to Natural Language Processing Computer Science 585—Fall 2009 University of Massachusetts Amherst

David Smith

Final Exam

- Wednesday, Dec. 16, 10:30, CS 142
- At least 2/3 from course's second half
- Focus on modeling techniques, such as:
 - Log-linear models
 - Sequence labeling, e.g. for information extraction
 - Formal semantics, simple λ -expressions
 - Word clustering
 - Simple machine translation algorithms: IBM Model-1, ITG



$P(A, B) = P(B)P(A \mid B) = P(A)P(B \mid A)$

 $P(A_1, A_2, ..., A_n) = P(A_1)P(A_2 | A_1)P(A_3 | A_1, A_2)$ Chain rule $\cdots P(A_n | A_1, ..., A_{n-1})$

Independence

P(A, B) = P(A)P(B) \Leftrightarrow $P(A \mid B) = P(A) \land P(B \mid A) = P(B)$

In coding terms, knowing B doesn't help in decoding A, and vice versa.

Another View of Markov Models

 $p(w_1, w_2, \dots, w_n) = p(w_1)p(w_2 \mid w_1)p(w_3 \mid w_1, w_2)$ $p(w_4 \mid w_1, w_2, w_3) \cdots p(w_n \mid p_1, \dots, p_{n-1})$

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Markov independence assumption

 $p(w_i \mid w_1, \dots, w_{i-1}) \approx p(w_i \mid w_{i-1})$

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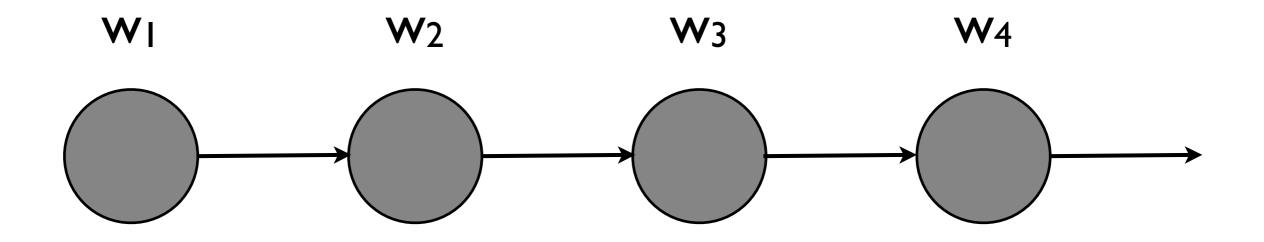
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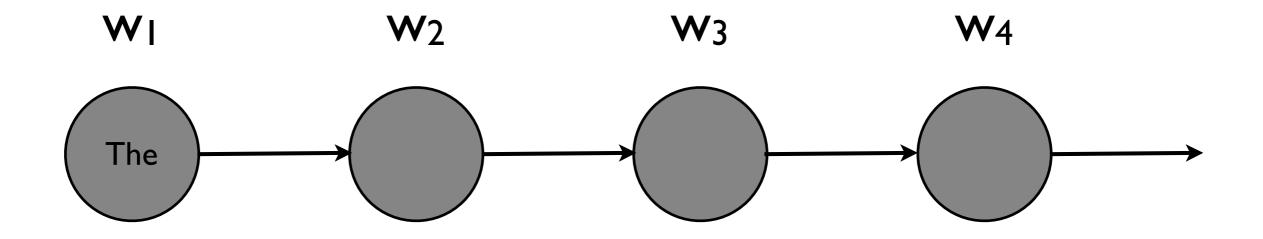
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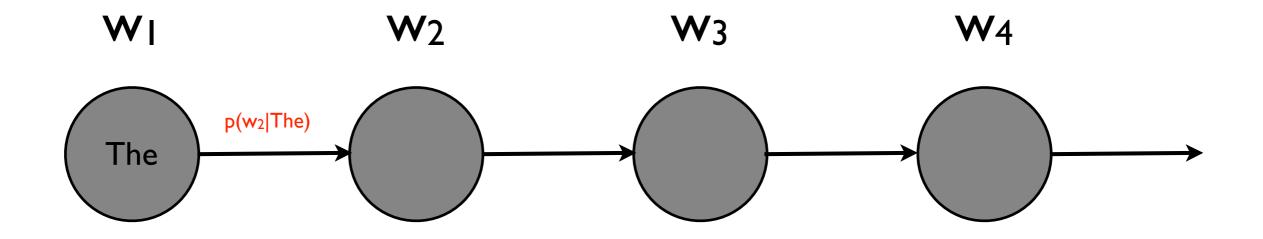
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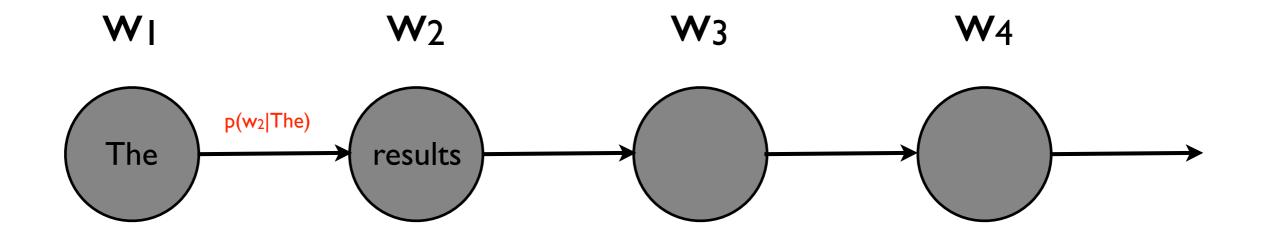
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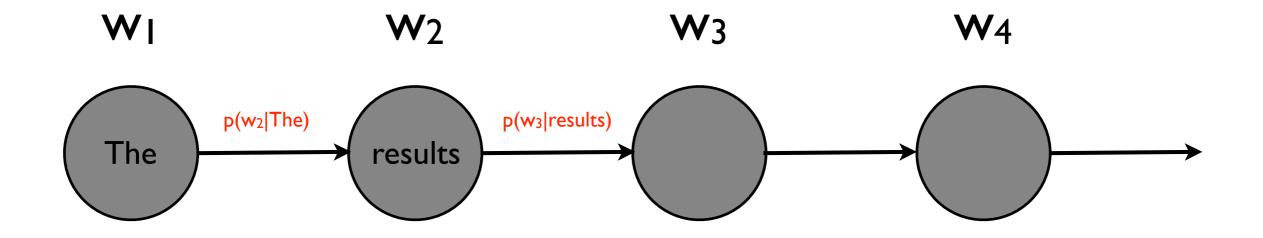
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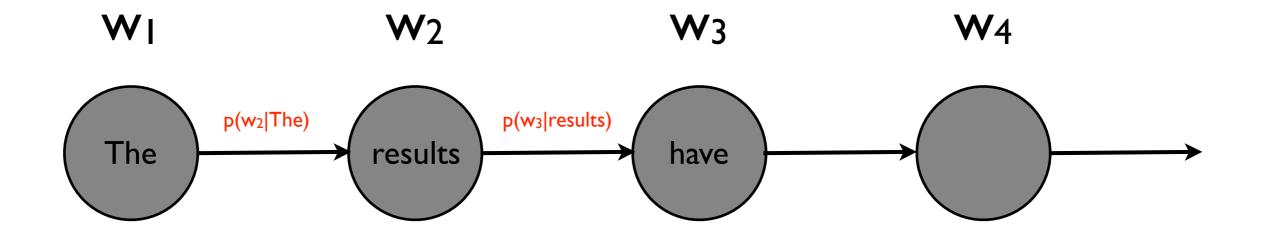


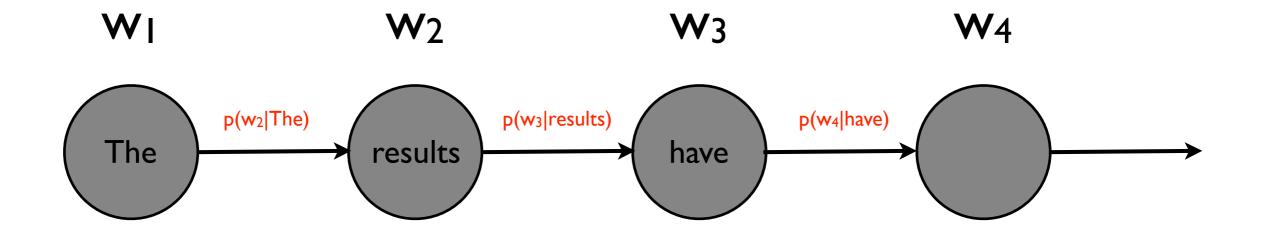


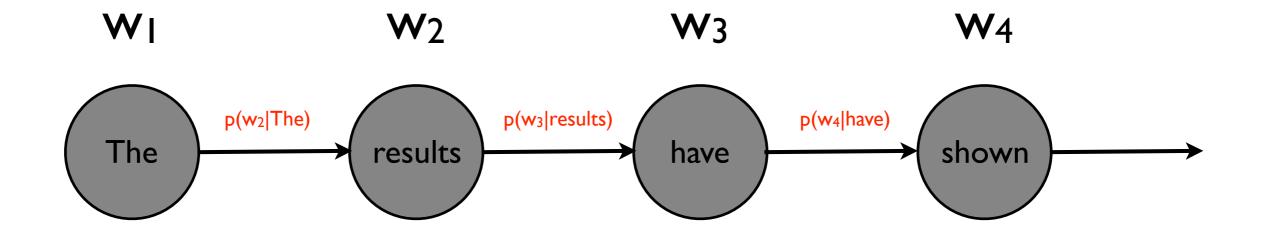


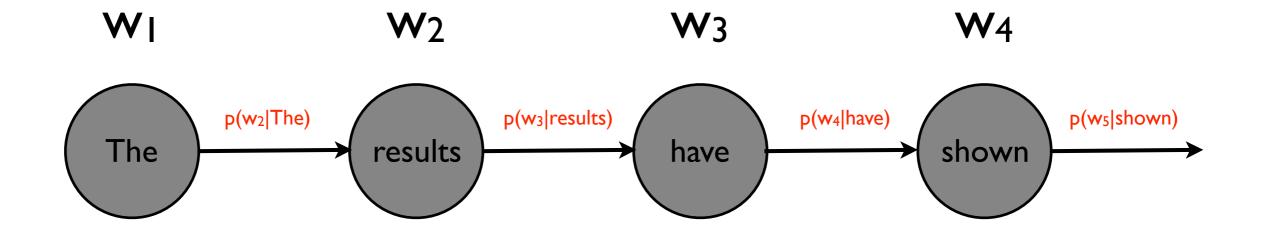


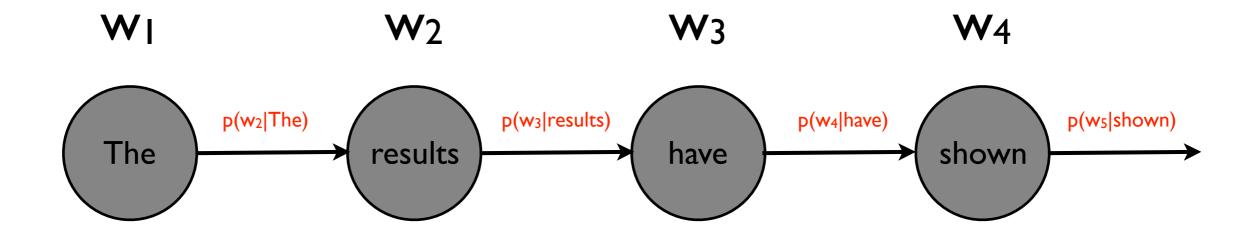


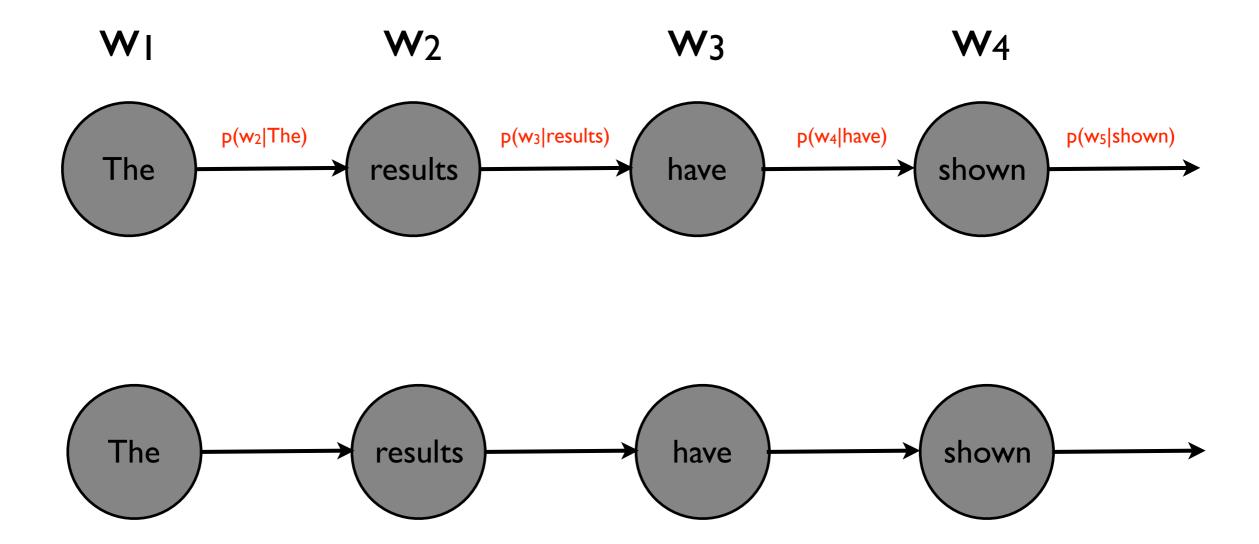


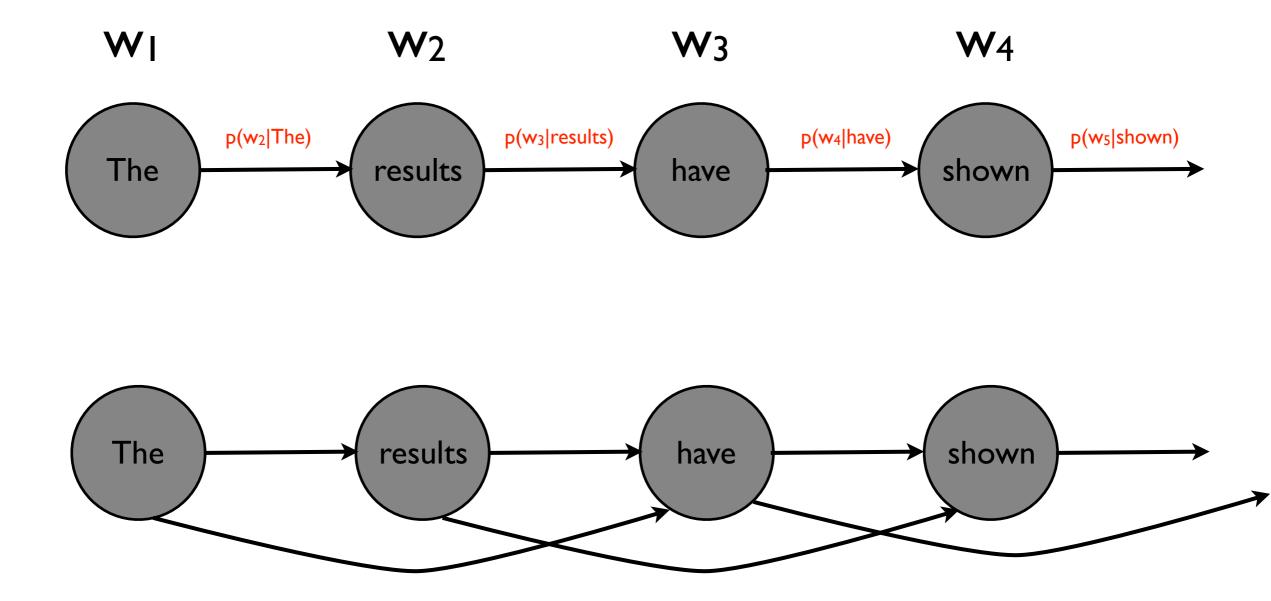


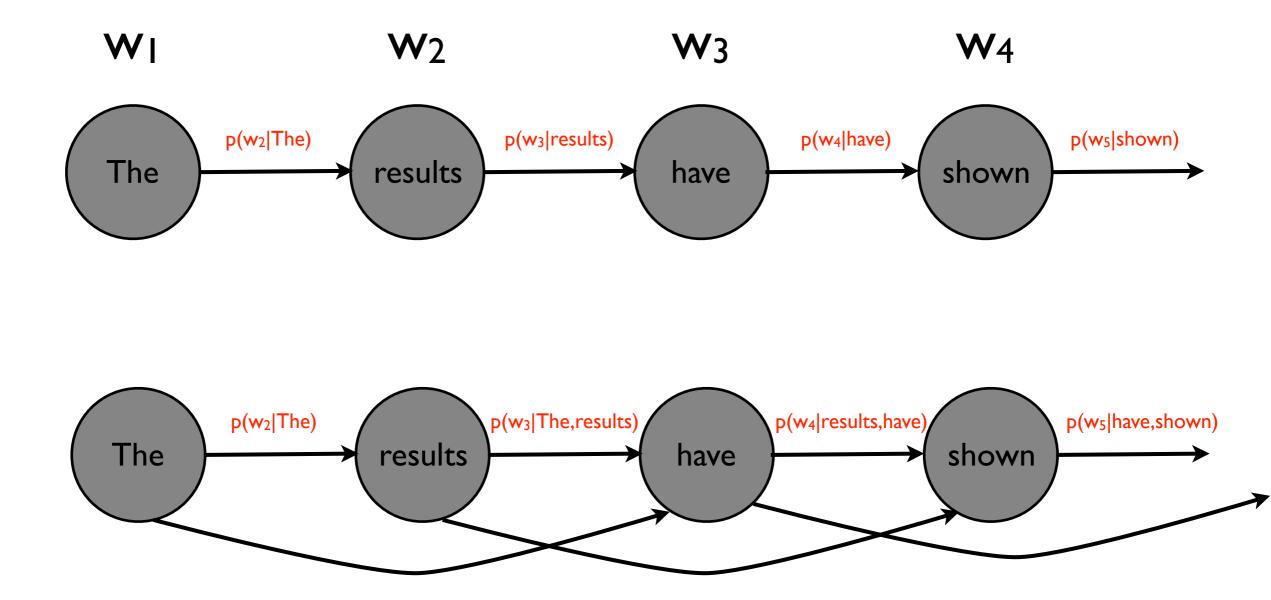


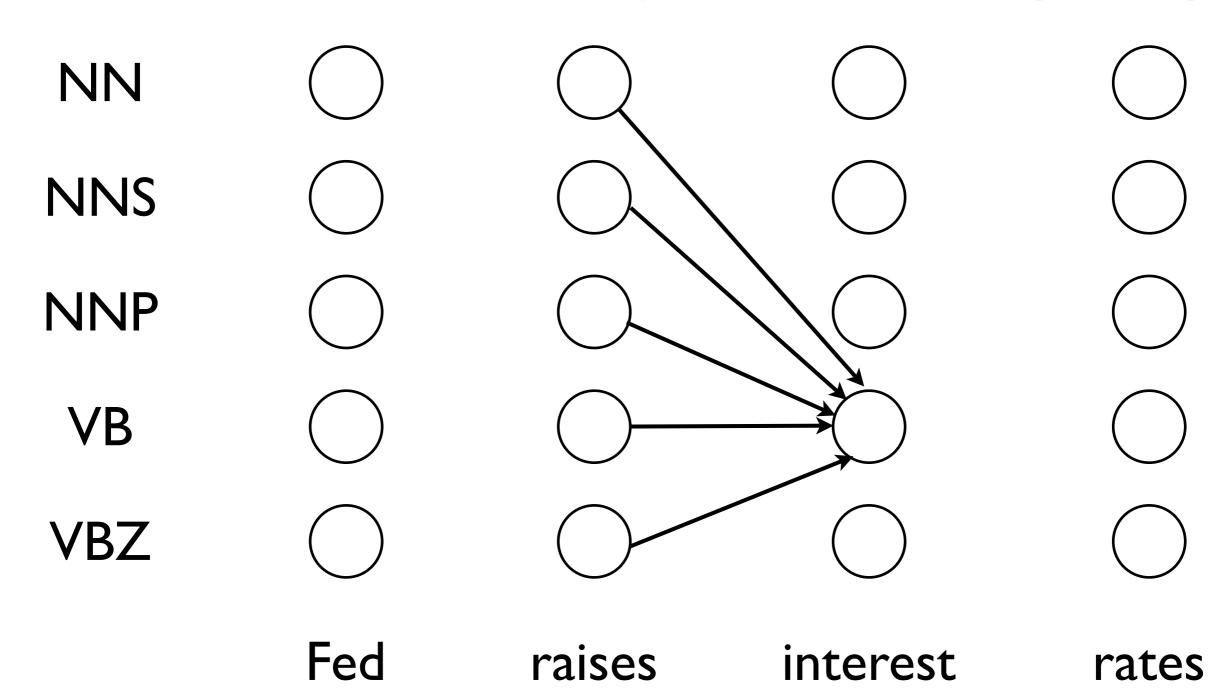




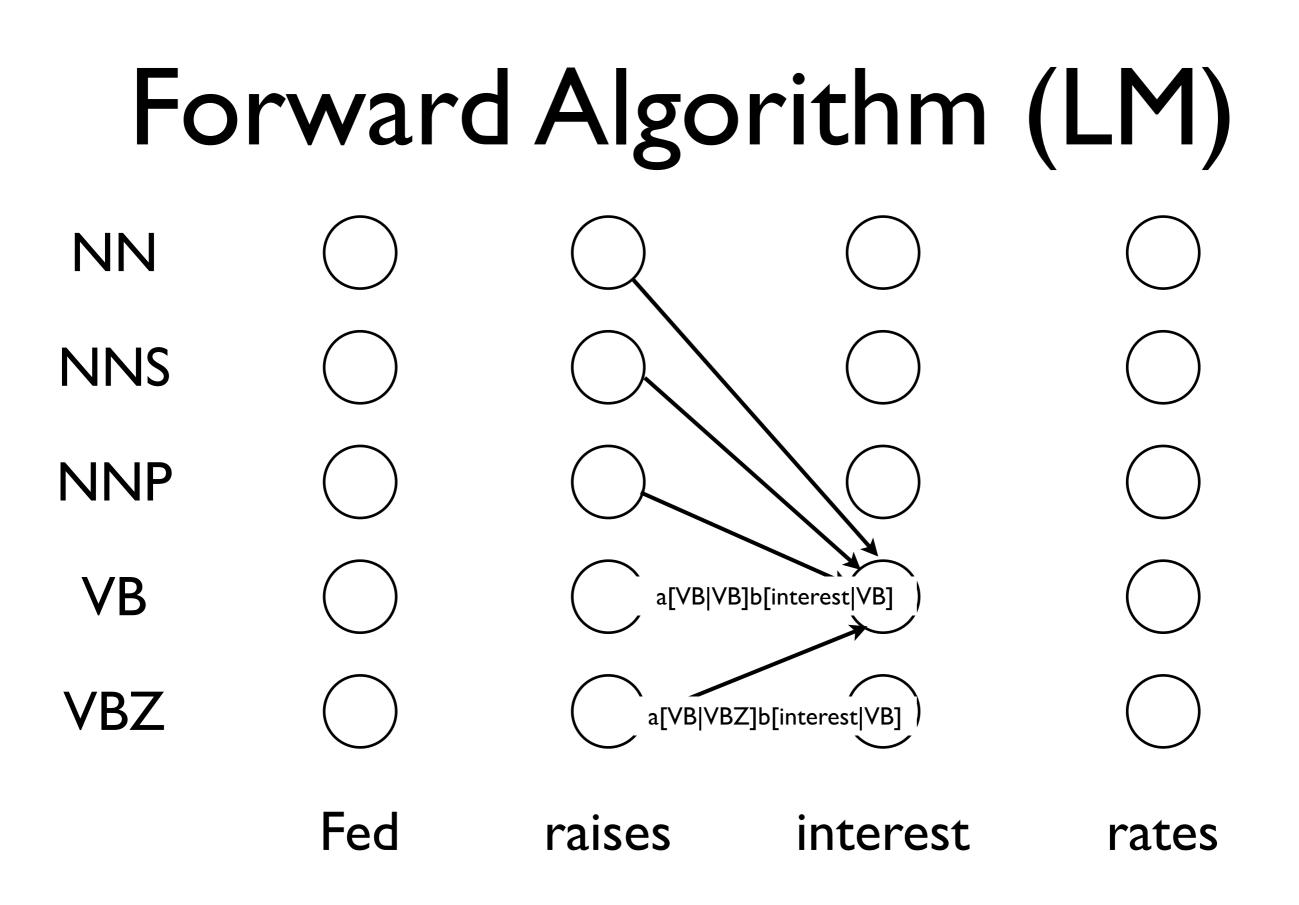


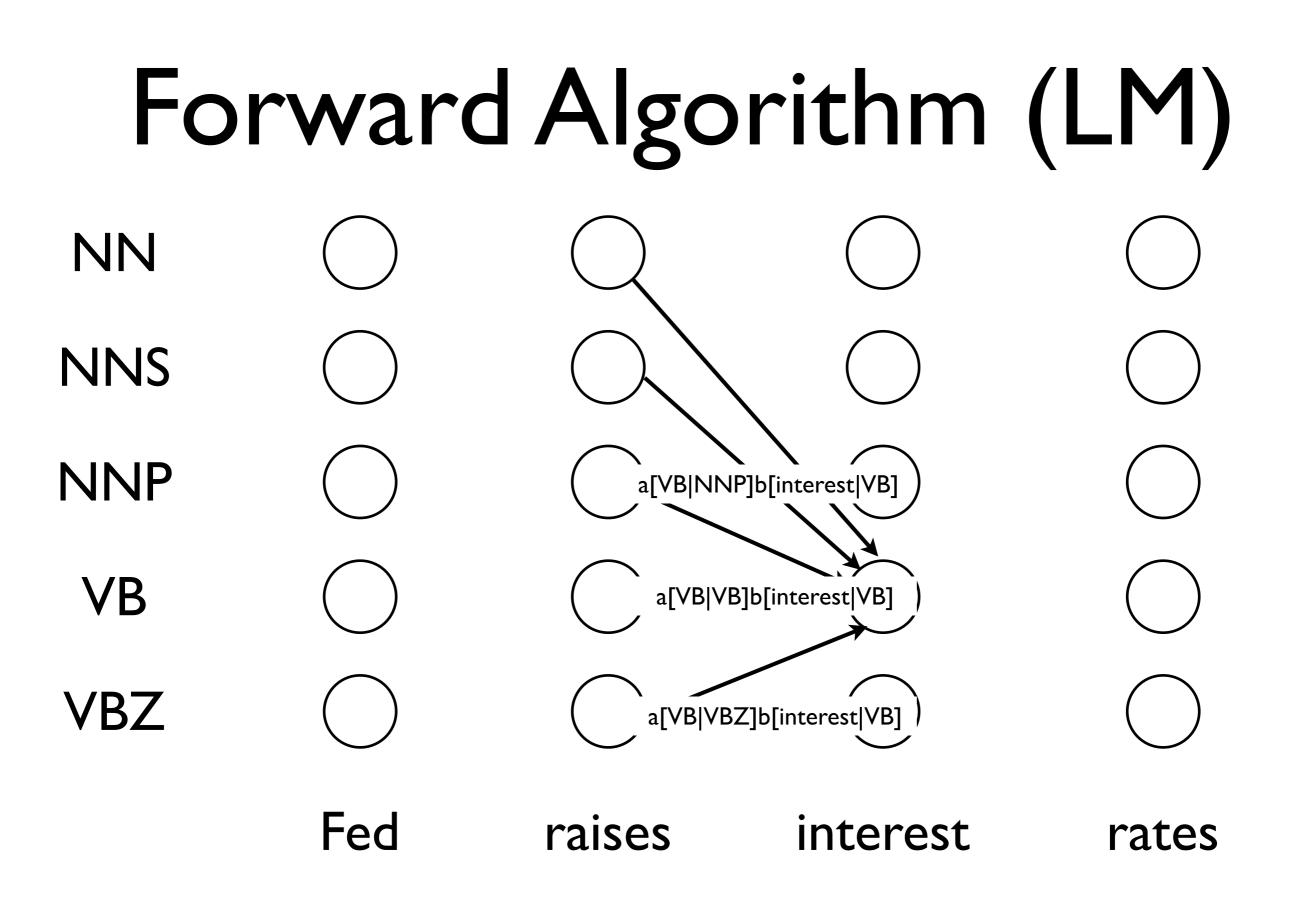


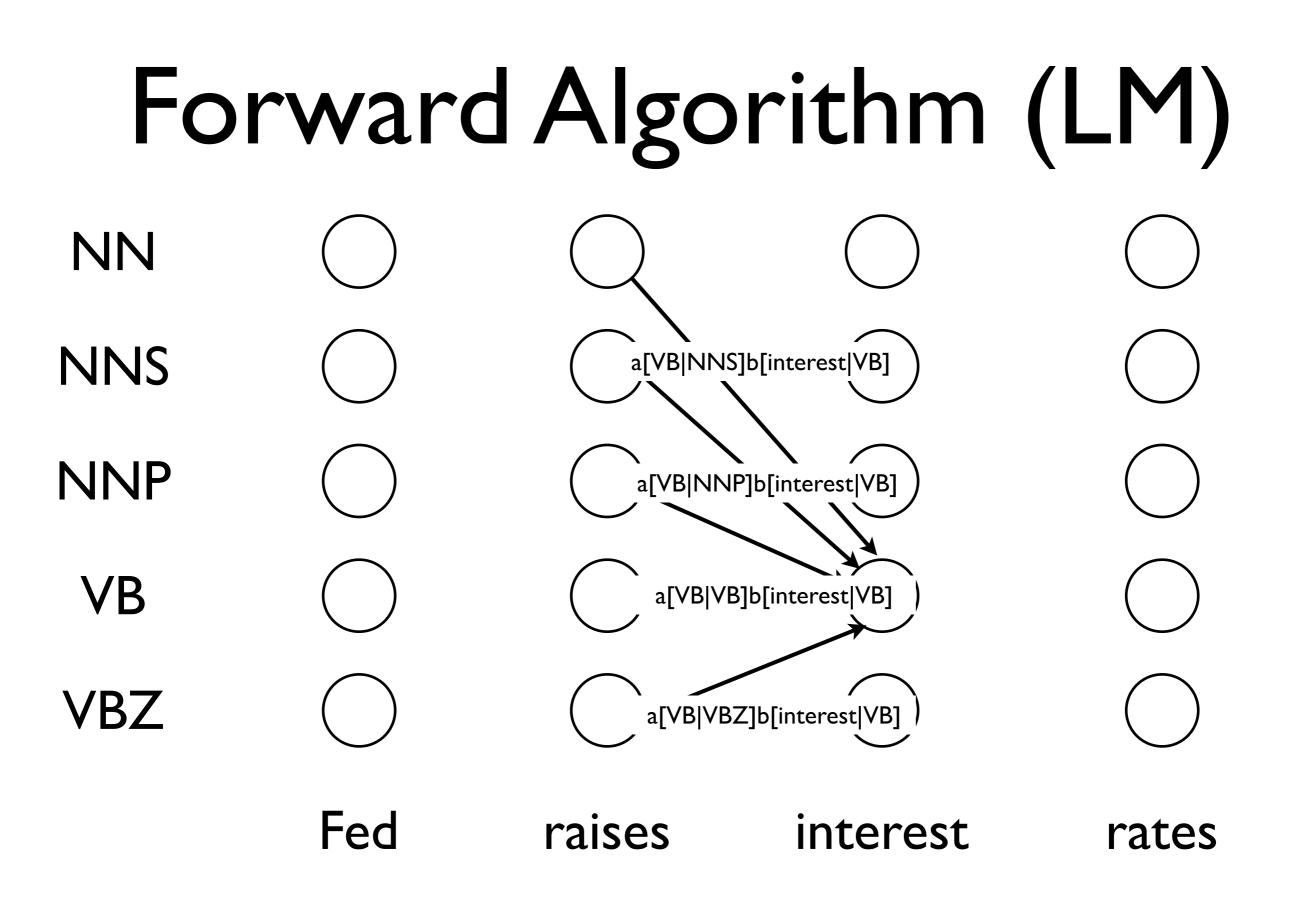


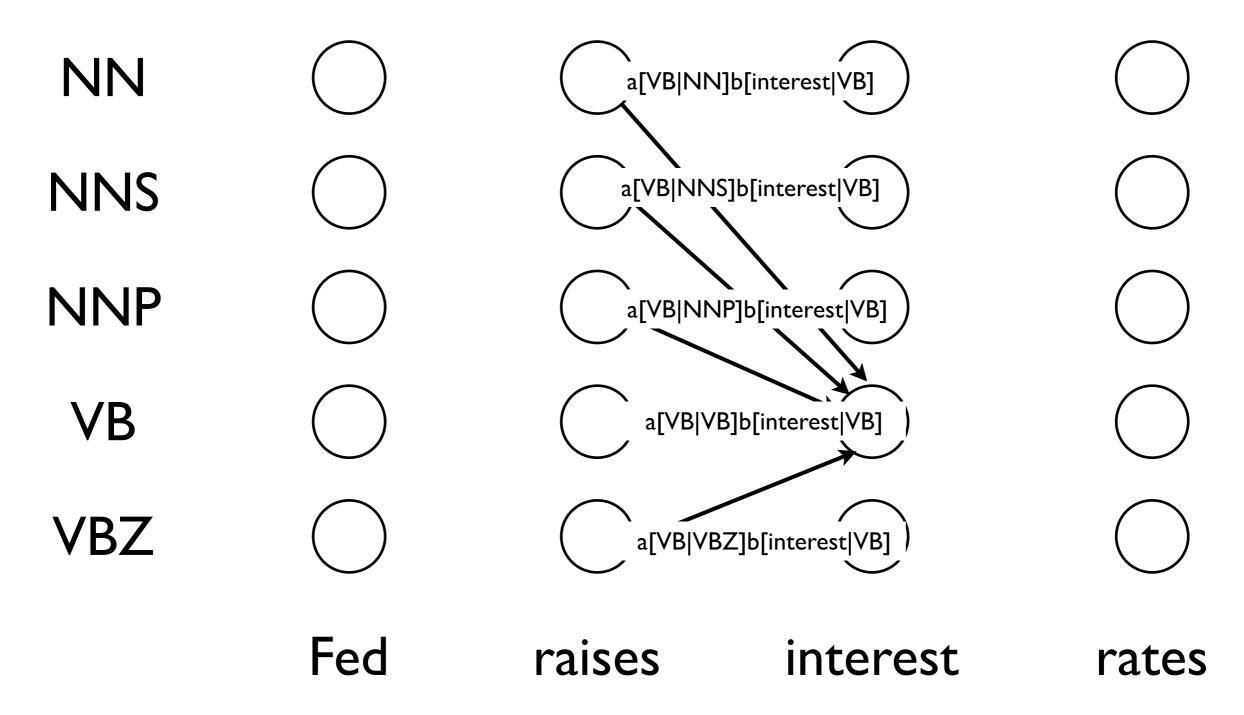


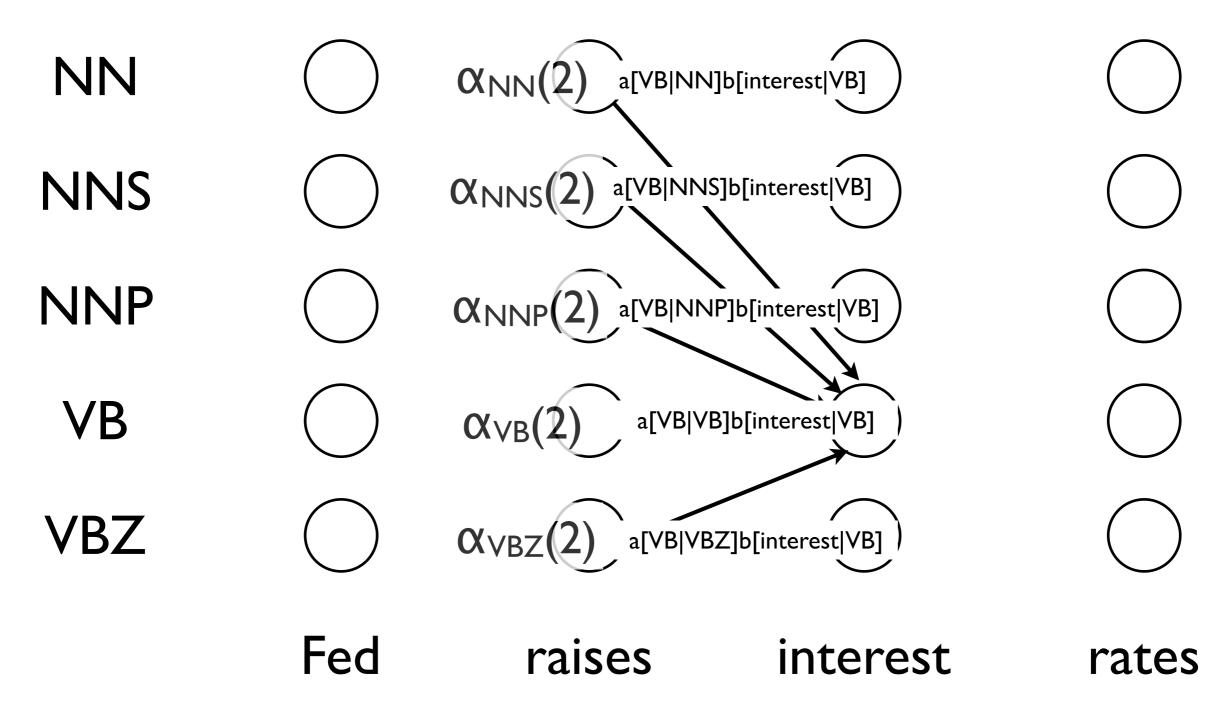
Forward Algorithm (LM) NN **NNS** NNP **VB** VBZ a[VB|VBZ]b[interest|VB] Fed raises interest rates

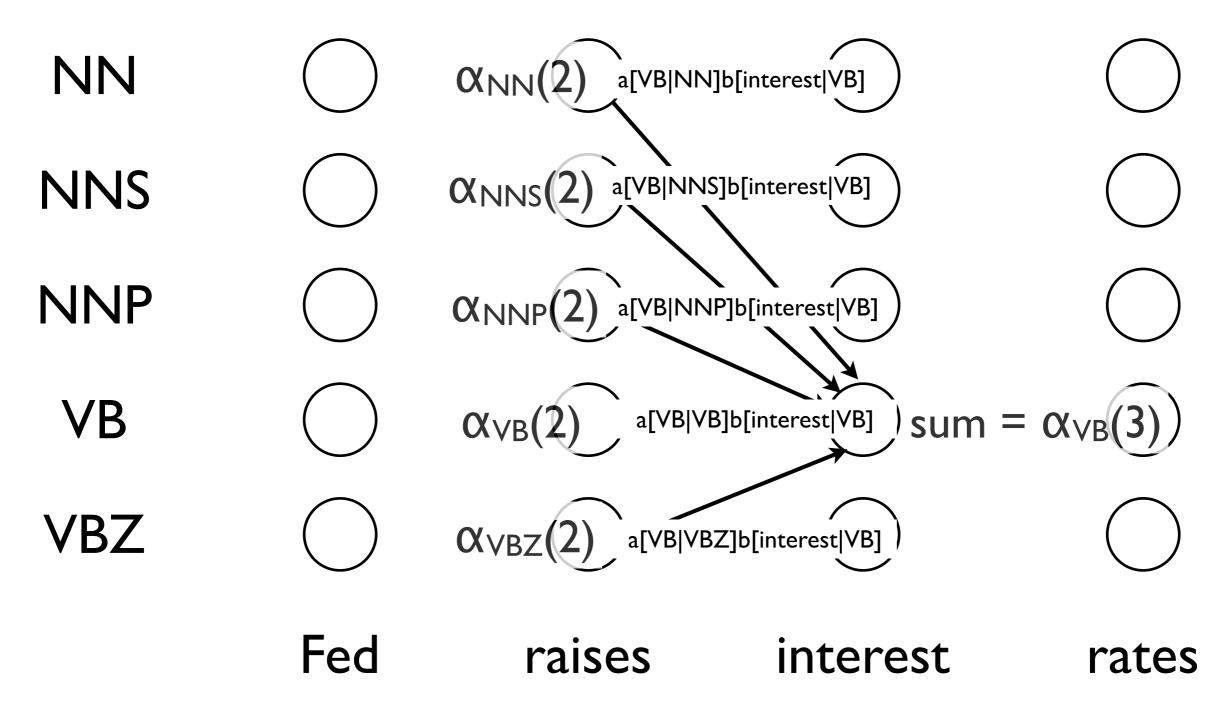












• What we want:

 $p(\odot | w_1, w_2, ..., w_n) > p(\odot | w_1, w_2, ..., w_n) ?$

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- What we know how to build:
 - A language model for each class
 - $p(w_1, w_2, ..., w_n | \odot)$
 - $p(w_1, w_2, ..., w_n \mid \Im)$

Bayes' Theorem

By the definition of conditional probability: $P(A, B) = P(B)P(A \mid B) = P(A)P(B \mid A)$

we can show: $P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$

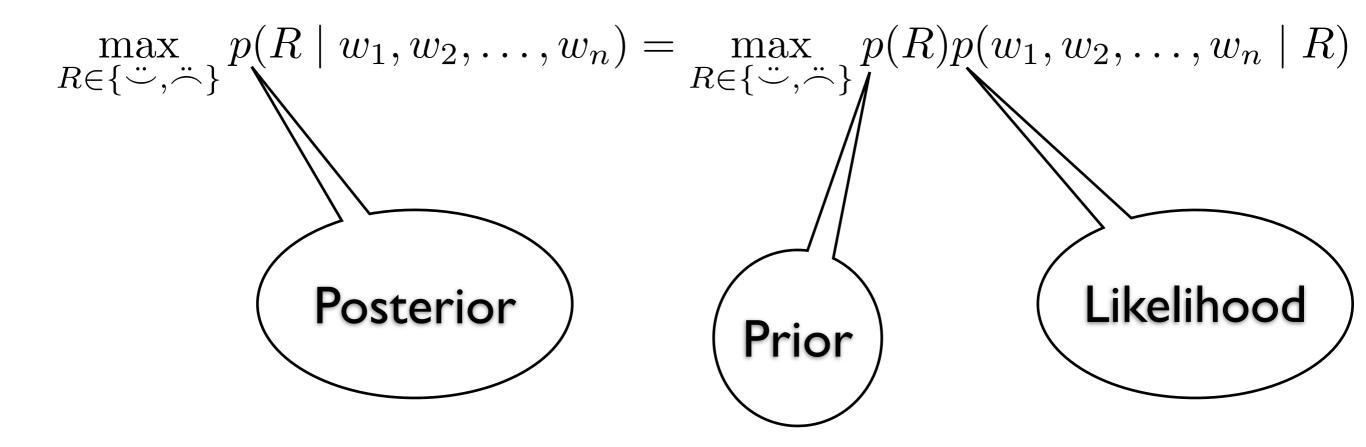
Seemingly trivial result from 1763; interesting consequences...



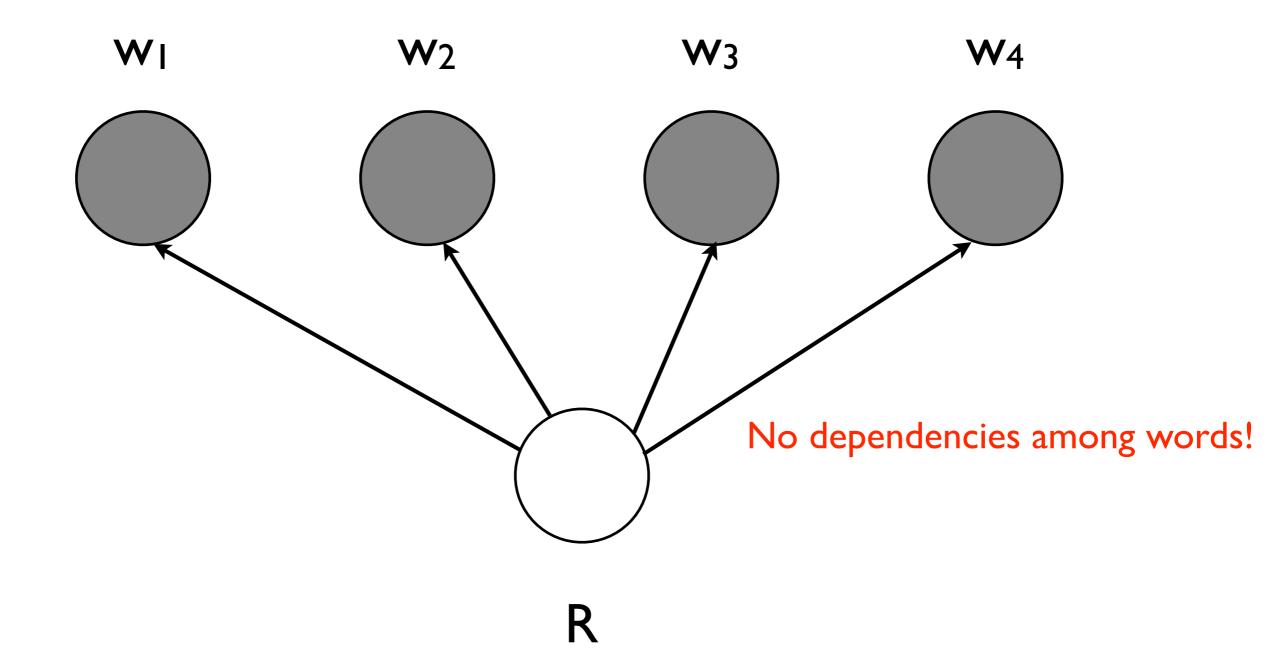
REV. T. BAYES

A "Bayesian" Classifier

$$p(R \mid w_1, w_2, \dots, w_n) = \frac{p(R)p(w_1, w_2, \dots, w_n \mid R)}{p(w_1, w_2, \dots, w_n)}$$



Naive Bayes Classifier



NB on Movie Reviews

- Train models for positive, negative
- For each review, find higher posterior
- Which word probability ratios are highest?

>>> classifier.show_most_informative_features(5)

classifier.show_most_informative_featur	'es(5)		
Most Informative Features			
contains(outstanding) = True	pos : neg	=	14.1 : 1.0
contains(mulan) = True	pos : neg	=	8.3 : 1.0
contains(seagal) = True	neg : pos	=	7.8 : 1.0
contains(wonderfully) = True	pos : neg	=	6.6 : 1.0
contains(damon) = True	pos : neg	=	6.1 : 1.0

What's Wrong With NB?

- What happens for word dependencies are strong?
- What happens when some words occur only once?
- What happens when the classifier sees a new word?

Generative vs. Conditional

- What is the most likely label for a given input?
- How likely is a given label for a given input?
- What is the most likely input value?
- How likely is a given input value?
- How likely is a given input value with a given label?
- What is the most likely label for an input that might have one of two values (but we don't know which)?

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Sequence Labeling

- Inputs: $x = (x_1, ..., x_n)$
- Labels: $y = (y_1, ..., y_n)$
- Typical goal: Given x, predict y
- Example sequence labeling tasks
 - Part-of-speech tagging
 - Named-entity-recognition (NER)
 - Label people, places, organizations

NER Example:

Red Sox and Their Fans Let Loose



Fans of the slugger David Ortiz in Boston's Copley Square.

By PETE THAMEL Published: October 31, 2007

BOSTON, Oct. 30 — Jonathan Papelbon turned Boston's World Series victory parade into a full-scale dance party Tuesday as the Red Sox put an exclamation point on the 2007 season.

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SAVE

First Solution: Maximum Entropy Classifier

- Conditional model p(y|x).
 - Do not waste effort modeling p(x), since x is given at test time anyway.
 - Allows more complicated input features, since we do not need to model dependencies between them.
- Feature functions f(x,y):
 - $-f_1(x,y) = \{ word is Boston & y=Location \}$
 - f₂(x,y) = { first letter capitalized & y=Name }
 - $-f_3(x,y) = \{ x \text{ is an HTML link & y=Location} \}$

First Solution: MaxEnt Classifier

- How should we choose a classifier?
- Principle of maximum entropy
 - We want a classifier that:
 - Matches feature constraints from training data.
 - Predictions maximize entropy.
- There is a unique, exponential family distribution that meets these criteria.

First Solution: MaxEnt Classifier

- Problem with using a maximum entropy classifier for sequence labeling:
- It makes decisions at each position independently!

$$P(\mathbf{y}, \mathbf{x}) = \prod_{t} P(y_t \mid y_{t-1}) P(x \mid y_t)$$

- Defines a generative process.
- Can be viewed as a weighted finite state machine.

- HMM problems: (ON BOARD)
 - Probability of an input sequence.
 - Most likely label sequence given an input sequence.
 - Learning with known label sequences.
 - Learning with unknown label sequences?

- How can represent we multiple features in an HMM?
 - Treat them as conditionally independent given the class label?
 - The example features we talked about are not independent.
 - Try to model a more complex generative process of the input features?
 - We may lose tractability (i.e. lose a dynamic programming for exact inference).

• Let's use a conditional model instead.

Third Solution: MEMM

- Use a series of maximum entropy classifiers that know the previous label.
- Define a Viterbi algorithm for inference.

$$P(\mathbf{y} | \mathbf{x}) = \prod_{t \in \mathbf{x}} P_{\mathbf{y}_{t}} (y_{t} | \mathbf{x})$$
$$P(\mathbf{y} | \mathbf{x}) = \prod_{t}^{\mathbf{y}_{t}} P(y_{t} | y_{t-1}, \mathbf{x})$$

Third Solution: MEMM

- Combines the advantages of maximum entropy and HMM!
- But there is a problem...

Problem with MEMMs: Label Bias

- In some state space configurations, MEMMs essentially completely ignore the inputs.
- Example (ON BOARD).
- This is not a problem for HMMs, because the input sequence is generated by the model.

Fourth Solution: Conditional Random Field

- Conditionally-trained, undirected graphical model.
- For a standard linear-chain structure:

$$P(\mathbf{y}, \mathbf{x}) = \frac{1}{2} \prod_{t} \Psi_{k}(y_{t}, y_{t-1}, \mathbf{x})$$
Bigram model:

$$\Psi_{t}(y_{t}, y_{t-1}, \mathbf{x}) = \exp_{t} \left[\sum_{t} \lambda_{k} f(y_{t}, y_{t-1}, \mathbf{x}) \right]$$
Bigram model:

$$\Psi_{t}(y_{t}, y_{t-1}, \mathbf{x}) = \exp_{t} \left[\sum_{k} \lambda_{k} f(y_{t}, y_{t-1}, \mathbf{x}) \right]$$
Dot-product of

$$\Psi_{k}(y_{t}, y_{t-1}, \mathbf{x}) \left[\sum_{k} \lambda_{k} f(y_{t}, y_{t-1}, \mathbf{x}) \right]$$
Dot-product of
weights and features

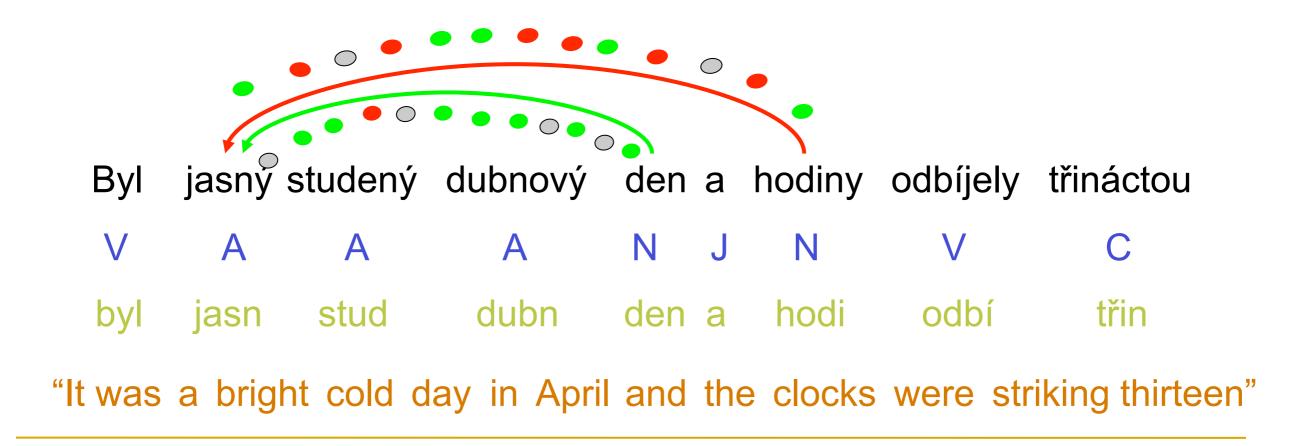
$$Z = \sum_{\mathbf{y}'} \prod_{t} \Psi(y'_{t}, y'_{t-1}, \mathbf{x})$$
Normalize over all
possible outputs
using forward alg.

Fourth Solution: CRF

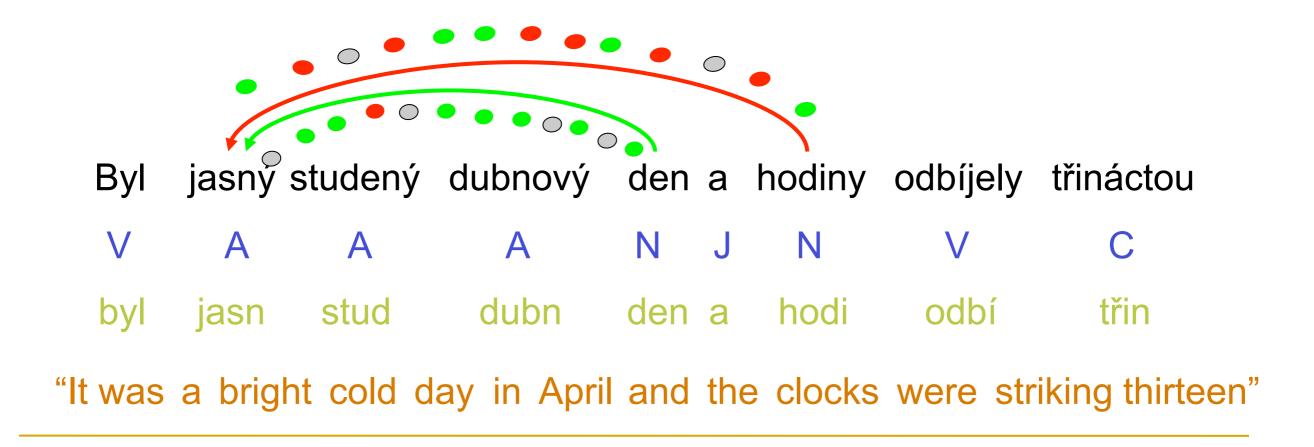
- Have the advantages of MEMMs, but avoid the label bias problem.
- CRFs are globally normalized, whereas MEMMs are locally normalized.
- Widely used and applied. CRFs give state-the-art results in many domains.

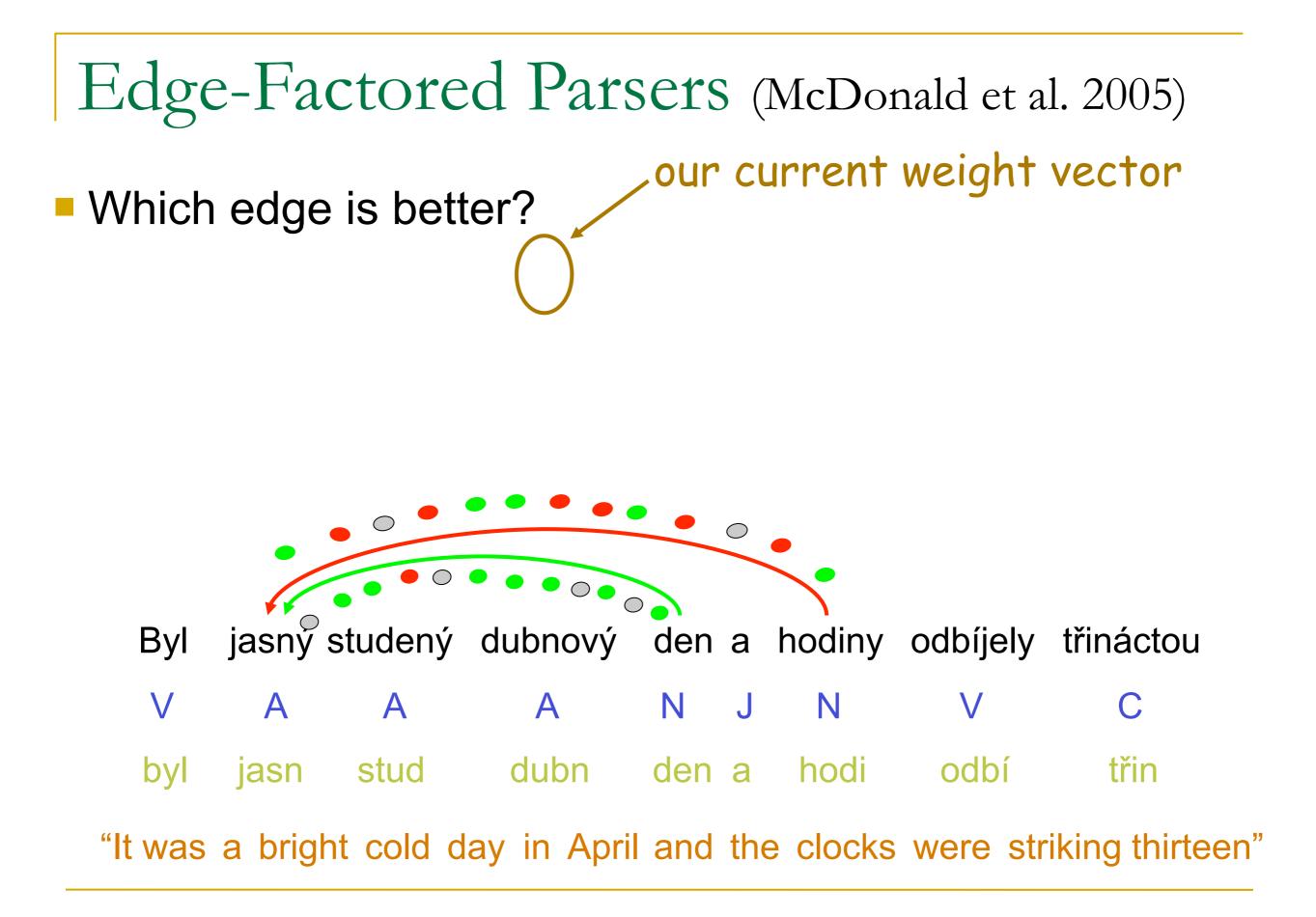
Example Applications

- CRFs have been applied to:
 - Part-of-speech tagging
 - Named-entity-recognition
 - Table extraction
 - Gene prediction
 - Chinese word segmentation
 - Extracting information from research papers.
 - Many more...



Which edge is better?

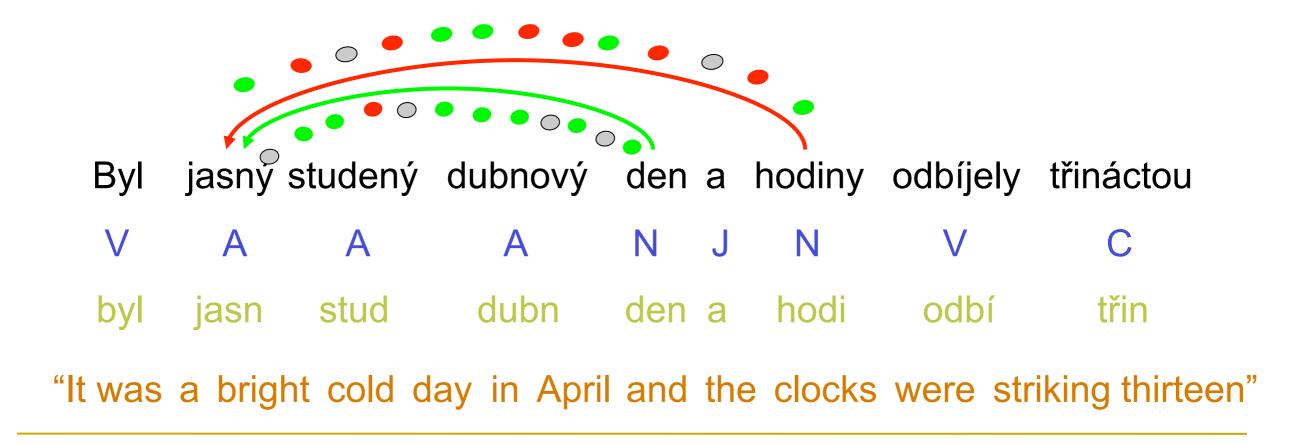




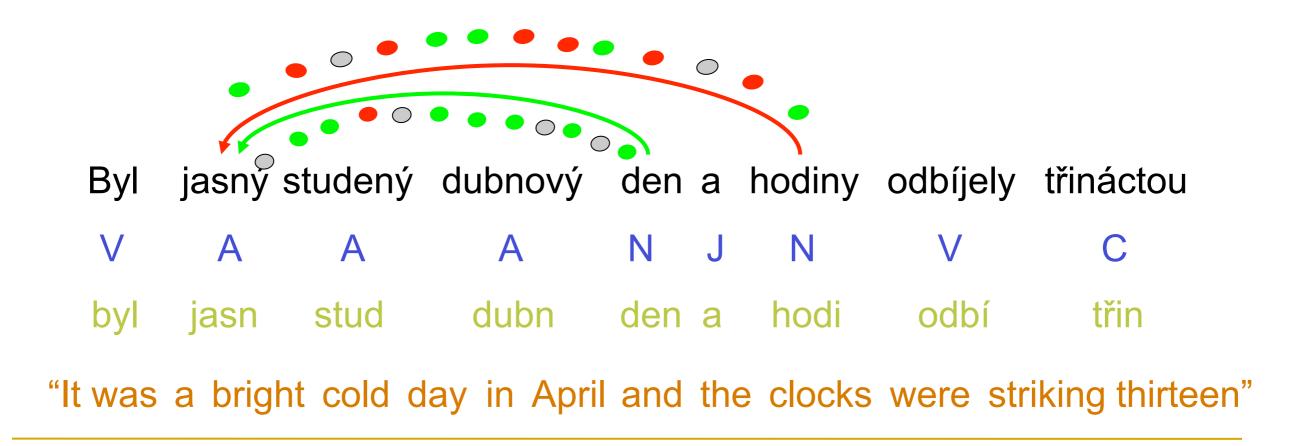
our current weight vector

Which edge is better?

Score of an edge $e = \theta$ features(e)



- Our current weight vector
 Which edge is better?
- Score of an edge $e = \{\theta\}$ features(e)



Recipe for Conditional Training of p(y | x)

I. Gather constraints/features from training data

- $\alpha_{iy} = \tilde{E}[f_{iy}] = \sum_{\substack{\alpha_{iy} = -\tilde{F}[f, 1] = \\ \alpha_{iy} = \tilde{E}[f_{iy}] = \\ \alpha_{iy} = \tilde{E}[f_{iy}] = \sum_{\substack{\gamma = -\tilde{F}[f, 1] = \\ \gamma_{ij}, y_{j} \in D}} f_{iy}(x_{j}, y_{j})$ 2. Initialize
- 3. Classify trainin $E_{\Theta}[f_{iy}] = \sum_{E_{\Theta}[f_{iy}]} \sum_{e \in D} \sum_{e \in D} p_{\Theta}(y'|x_i) f_{iy}(x_i, y')$ calculate expectations $E_{\Theta}[f_{iy}] = \sum_{e \in D} \sum_{e \in D} \sum_{g'} p_{\Theta}(y'|x_j) f_{iy}(x_j, y')$ $\tilde{E}[f_{iy}] - \sum_{e \in D} \sum_{g'} p_{\Theta}(y'|x_j) f_{iy}(x_j, y')$ 4. Gradient is $E[f_i \tilde{E}[f_{iy}] - E_{\Theta}[f_{iy}]$
- 5. Take a step in the direction of the gradient
- 6. Repeat from 3 until convergence

43

Recipe for Conditional Training of p(y | x)

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Where have we seen expected counts before?

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Where have we seen expected counts before?

EM!

Gradient-Based Training

- $\lambda := \lambda + rate * Gradient(F)$
- After all training examples? (batch)
- After every example? (on-line)
- Use second derivative for faster learning?
- A big field: numerical optimization

Overfitting

- If we have too many features, we can choose weights to model the training data perfectly
- If we have a feature that only appears in spam training, not ham training, it will get weight ∞ to maximize p(spam | feature) at 1.
- These behaviors
 - Overfit the training data
 - Will probably do poorly on test data

Solutions to Overfitting

- Throw out rare features.
 - Require every feature to occur > 4 times, and > 0 times with ling, and > 0 times with spam.
- Only keep, e.g., 1000 features.
 - Add one at a time, always greedily picking the one that most improves performance on held-out data.
- Smooth the observed feature counts.
- Smooth the weights by using a prior.
 - max $p(\lambda|data) = max p(\lambda, data) = p(\lambda)p(data|\lambda)$
 - decree $p(\lambda)$ to be high when most weights close to 0

Smoothing with Priors

- What if we had a prior expectation that parameter values wouldn't be very large?
- We could then balance evidence suggesting large (or infinite) parameters against our prior expectation.
- The evidence would never totally defeat the prior, and parameters would be smoothed (and kept finite)
- We can do this explicitly by changing the optimization objective to maximum posterior likelihood:

 $\log P(y, \lambda \mid x) = \log P(\lambda) + \log P(y \mid x, \lambda)$

Posterior Prior Likelihood

Three major kinds of objects

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 - Roughly, the semantic values of sentences

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 - Values of NPs, e.g., objects like this slide
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(First Order) Logic Some Preliminaries

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- 3. Functions of various types
 - Functions from booleans to booleans (and, or, not)
 - A function from entity to boolean is called a "predicate" – e.g., frog(x), green(x)
 - Functions might return other functions!

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 - Functions might return other functions!
 - Function might take other functions as arguments!

- Gilly swallowed <u>a</u> goldfish
 - First attempt: swallowed(Gilly, goldfish)

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- Or using one of our quantifier predicates:
 - exists(λg goldfish(g), λg swallowed(Gilly,g))
 - Equivalently: exists(goldfish, swallowed(Gilly))
 - "In the set of goldfish there exists one swallowed by Gilly"

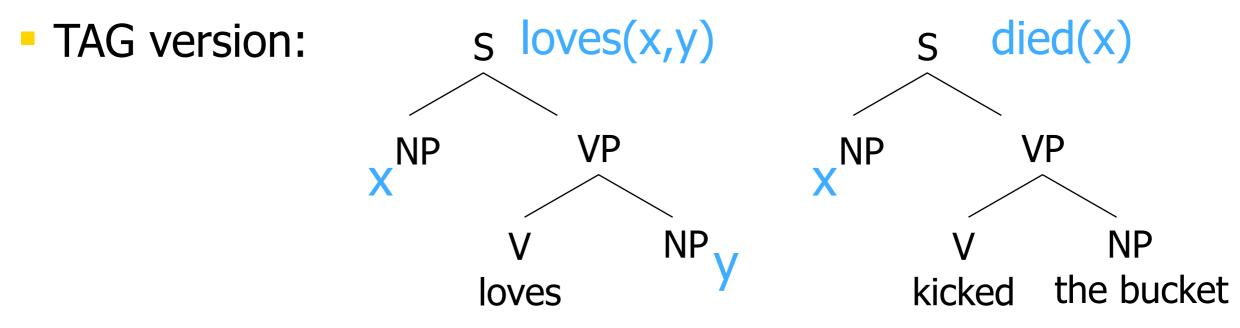
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 - Equivalently: exists(goldfish, swallowed(Gilly))
 - "In the set of goldfish there exists one swallowed by Gilly"
- Here goldfish is a predicate on entities
 - This is the same semantic type as red
 - But note: goldfish is noun and red is adjective

- Add a "sem" feature to each context-free rule
 - S \rightarrow NP loves NP
 - $S[sem=loves(x,y)] \rightarrow NP[sem=x] loves NP[sem=y]$
 - Meaning of S depends on meaning of NPs

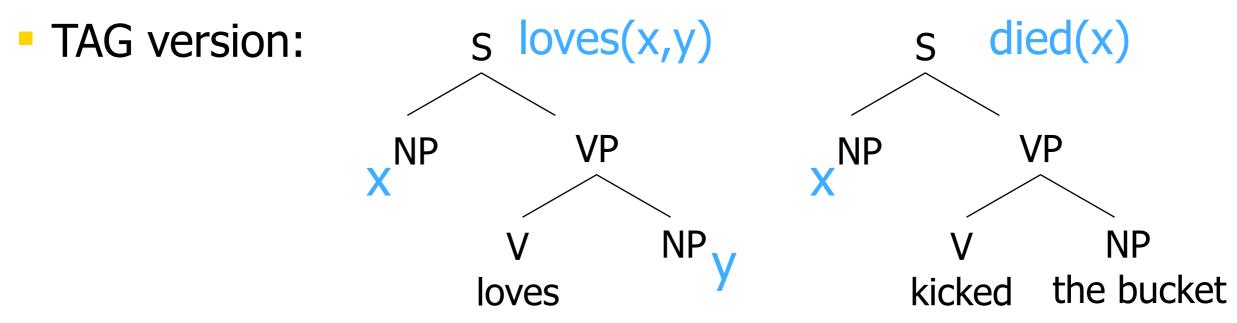
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- TAG version:
 S loves(x,y)
 NP VP
 V VP
 V NP
 V NP

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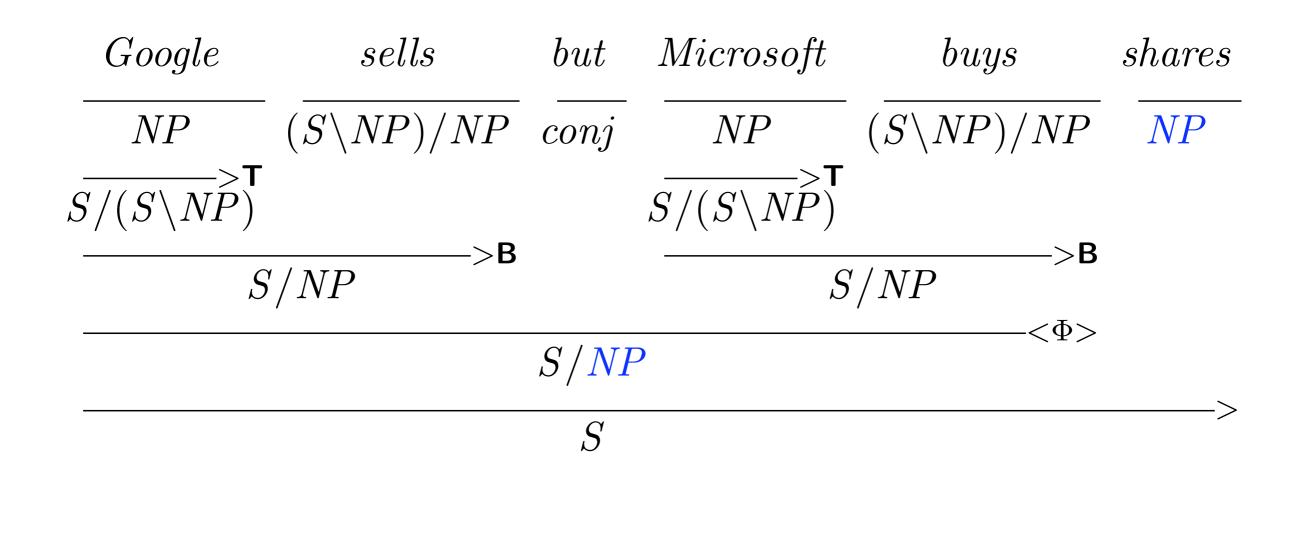


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 - $S[sem=loves(x,y)] \rightarrow NP[sem=x] loves NP[sem=y]$
 - Meaning of S depends on meaning of NPs



 Template filling: S[sem=showflights(x,y)] → I want a flight from NP[sem=x] to NP[sem=y]

"Non-constituents" in CCG – Right Node Raising



Practical Linguistically Motivated Parsing

JHU, June 2009

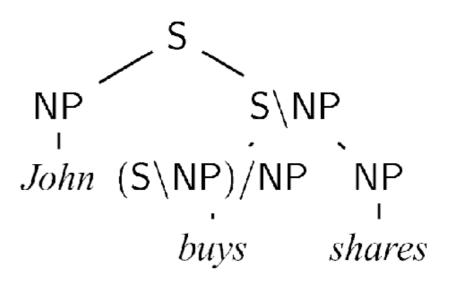
◆□▶ ◆□▶ ◆三▶ ◆三▶ ◆□▶

Stephen Clark

LUG semantics

- Categories encode argument sequences
- Parallel syntactic combinator operations and lambda calculus semantic operations

 $John \vdash \mathsf{NP} : john'$ $shares \vdash \mathsf{NP} : shares'$ $buys \vdash (\mathsf{S}\backslash\mathsf{NP})/\mathsf{NP} : \lambda x.\lambda y.buys'xy$ $sleeps \vdash \mathsf{S}\backslash\mathsf{NP} : \lambda x.sleeps'x$ $well \vdash (\mathsf{S}\backslash\mathsf{NP})\backslash(\mathsf{S}\backslash\mathsf{NP}) : \lambda f.\lambda x.well'(fx)$



- Represent each word type w by a point in kdimensional space
 - e.g., k is size of vocabulary
 - the 17th coordinate of w represents strength of w's association with vocabulary word 17

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 $(0, 0, 3, 1, 0, 7, \ldots 1, 0)$

Represent each word type w by a point in kdimensional space Party

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 $\frac{1}{1}$

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From corpus:

Arlen Specter **abandoned** the Republican **<u>party</u>**. There were lots of **abbots** and nuns dancing at that **<u>party</u>**. The **<u>party</u>** above the art gallery was, **above** all, a laboratory for synthesizing **zygotes** and beer.

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(too influential)

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aardwark abacus ndone about the abacus abandon about the abacus abandon about the about the abard about the abard abard about the abard abard about the abard abard abard about the abard abar

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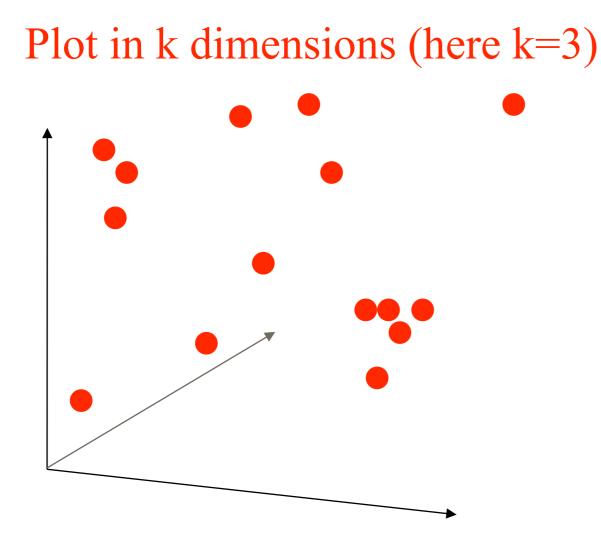
count

too low

24900 241 1

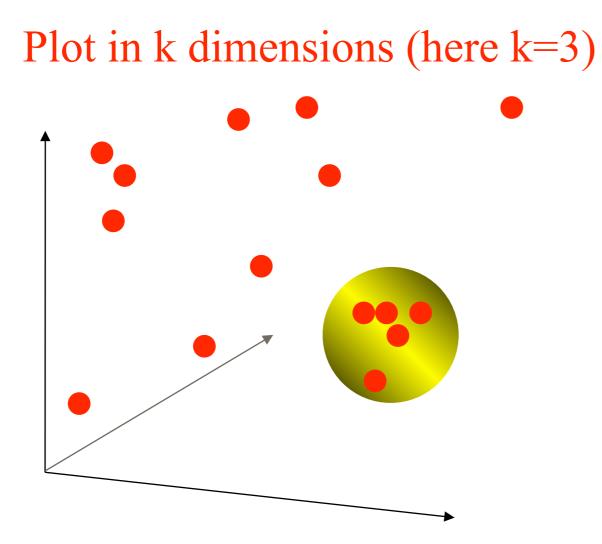
Learning Classes by Clustering

Plot all word types in k-dimensional space
Look for clusters of close-together types



Learning Classes by Clustering

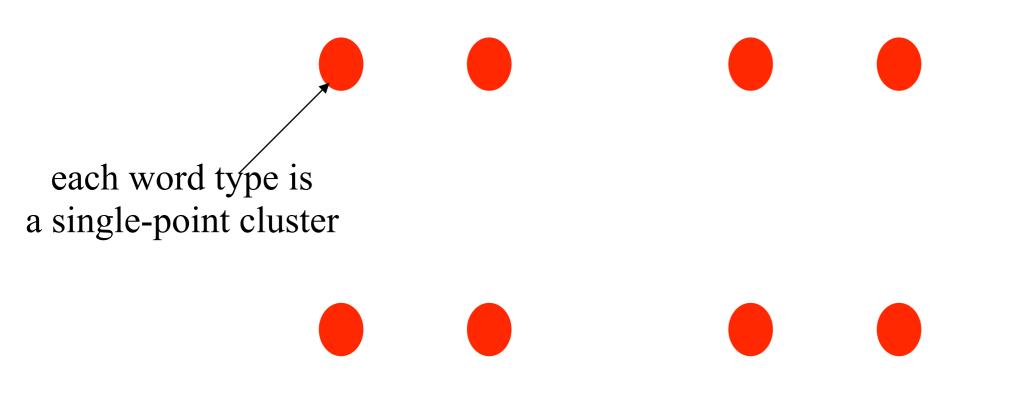
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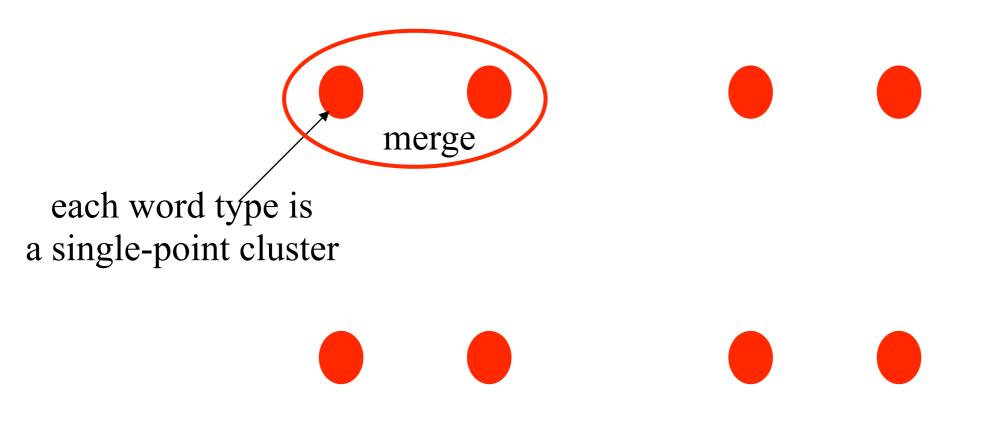


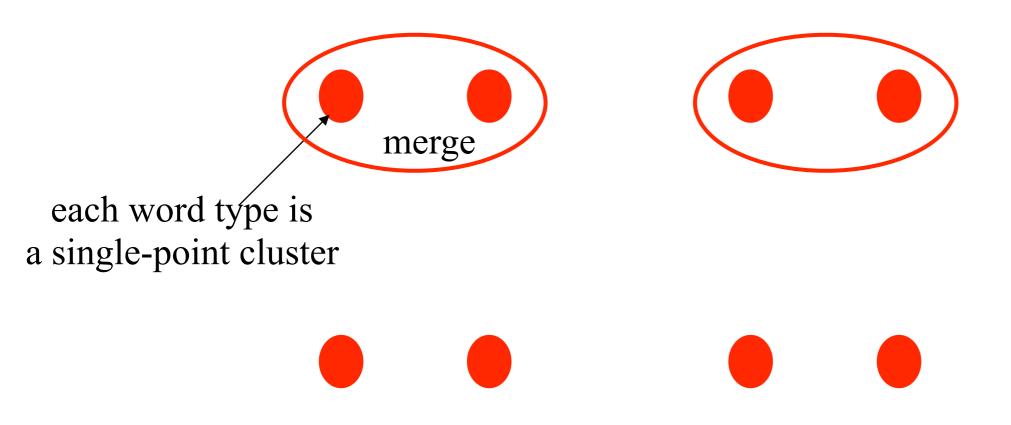
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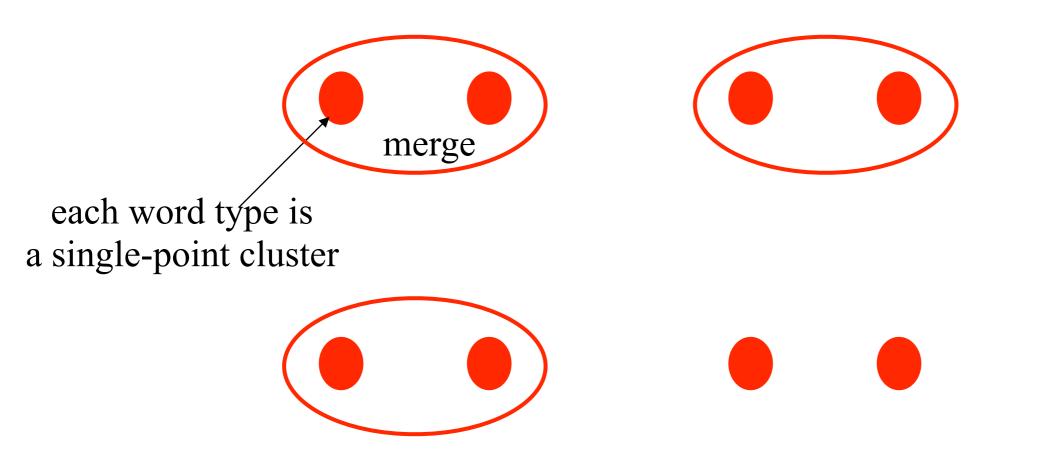
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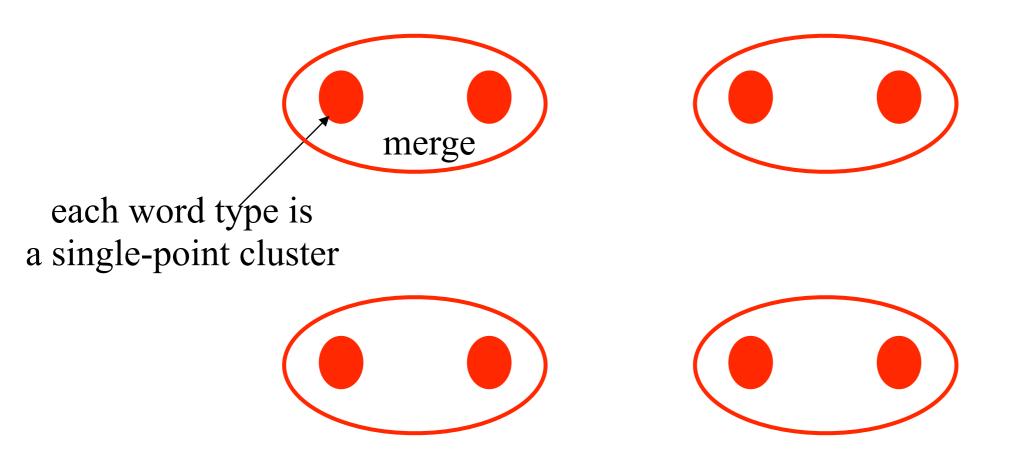
Plot in k dimensions (here k=3)



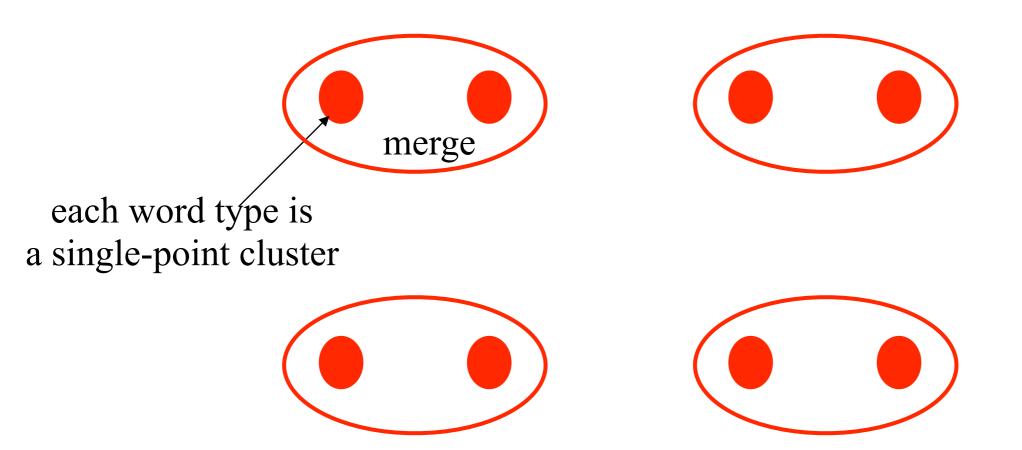






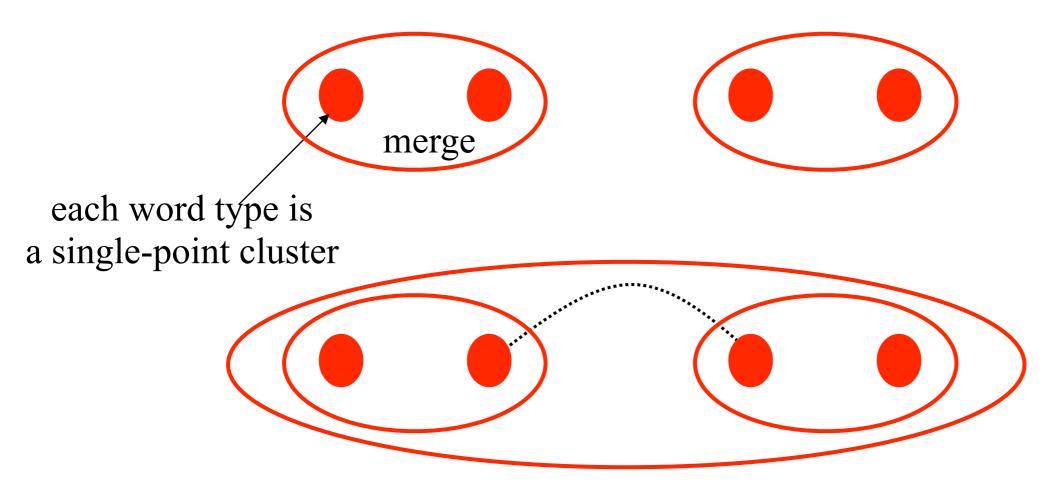


Bottom-Up Clustering – Single-Link



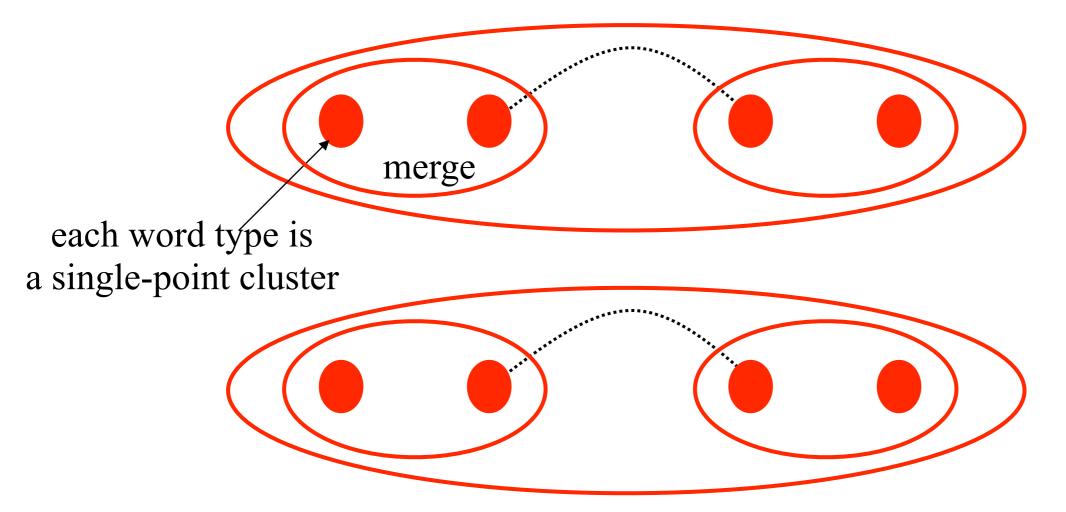
Again, merge closest pair of clusters: Single-link: clusters are close if any of their points are dist(A,B) = min dist(a,b) for $a \in A$, $b \in B$

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- Start with one cluster per point
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 - Complete-link: dist(A,B) = max dist(a,b) for $a \in A$, $b \in B$
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 - e.g., provide adequate support for backoff (on a development corpus)
- Some flexibility in defining dist(a,b)
 - Might not be Euclidean distance; e.g., use vector angle

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- Full EM version called "Gaussian mixtures"

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- Parameters: k points representing cluster centers
- Hidden structure: for each data point (word type), which center generated it?

Lexical translation

 \bullet How to translate a word \rightarrow look up in dictionary

Haus — house, building, home, household, shell.

- Multiple translations
 - some more frequent than others
 - for instance: *house*, and *building* most common
 - special cases: *Haus* of a *snail* is its *shell*
- Note: During all the lectures, we will translate from a foreign language into English

School of



Collect statistics

• Look at a *parallel corpus* (German text along with English translation)

Translation of Haus	Count
house	8,000
building	1,600
home	200
household	150
shell	50

3 informatics

Estimate translation probabilities

• Maximum likelihood estimation

$$p_f(e) = \begin{cases} 0.8 & \text{if } e = \text{house}, \\ 0.16 & \text{if } e = \text{building}, \\ 0.02 & \text{if } e = \text{home}, \\ 0.015 & \text{if } e = \text{household}, \\ 0.005 & \text{if } e = \text{shell}. \end{cases}$$

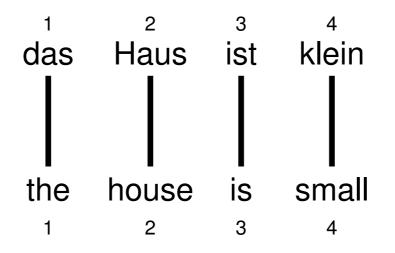
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Alignment

• In a parallel text (or when we translate), we align words in one language with the words in the other



• Word *positions* are numbered 1–4

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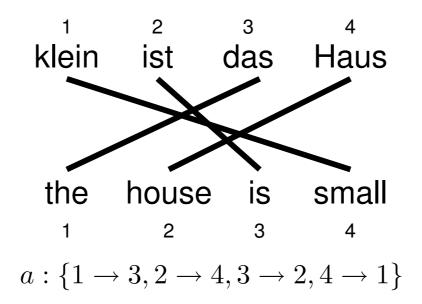
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4 Informatics

Reordering

• Words may be **reordered** during translation



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⁶ informatics

10 Informatics

IBM Model 1

- *Generative model*: break up translation process into smaller steps
 - IBM Model 1 only uses *lexical translation*
- Translation probability
 - for a foreign sentence $\mathbf{f} = (f_1, ..., f_{l_f})$ of length l_f
 - to an English sentence $\mathbf{e} = (e_1, ..., e_{l_e})$ of length l_e
 - with an alignment of each English word e_j to a foreign word f_i according to the alignment function $a: j \to i$

$$p(\mathbf{e}, a | \mathbf{f}) = \frac{\epsilon}{(l_f + 1)^{l_e}} \prod_{j=1}^{l_e} t(e_j | f_{a(j)})$$

– parameter ϵ is a *normalization constant*

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Example

d	as	Hau	Haus		ist		kle	ein
e	t(e f)	e	t(e f)		e	t(e f)	e	t(e f)
the	0.7	house	0.8		is	0.8	small	0.4
that	0.15	building	0.16		's	0.16	little	0.4
which	0.075	home	0.02		exists	0.02	short	0.1
who	0.05	household	0.015		has	0.015	minor	0.06
this	0.025	shell	0.005		are	0.005	petty	0.04

$$p(e, a|f) = \frac{\epsilon}{4^3} \times t(\text{the}|\text{das}) \times t(\text{house}|\text{Haus}) \times t(\text{is}|\text{ist}) \times t(\text{small}|\text{klein})$$
$$= \frac{\epsilon}{4^3} \times 0.7 \times 0.8 \times 0.8 \times 0.4$$
$$= 0.0028\epsilon$$

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12 informatics

Learning lexical translation models

- We would like to estimate the lexical translation probabilities t(e|f) from a parallel corpus
- ... but we do not have the alignments
- Chicken and egg problem
 - if we had the *alignments*,
 - \rightarrow we could estimate the *parameters* of our generative model
 - if we had the *parameters*,
 - \rightarrow we could estimate the *alignments*

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EM algorithm

• Incomplete data

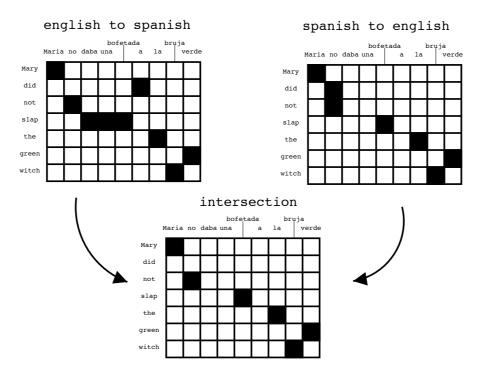
- if we had *complete data*, would could estimate *model*
- if we had *model*, we could fill in the *gaps in the data*
- Expectation Maximization (EM) in a nutshell
 - initialize model parameters (e.g. uniform)
 - assign probabilities to the missing data
 - estimate model parameters from completed data
 - iterate

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Symmetrizing word alignments

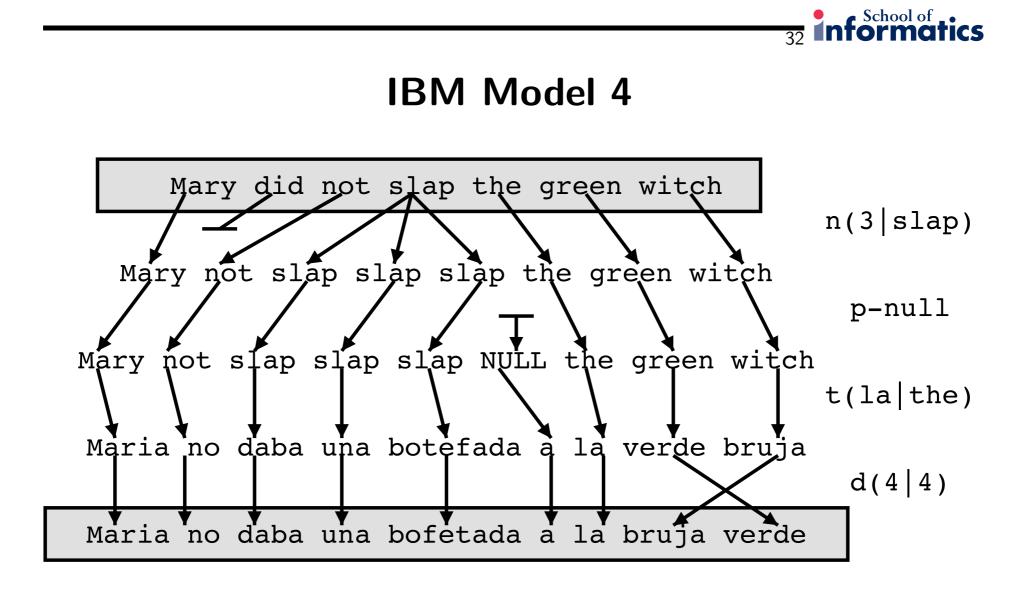


• *Intersection* of GIZA++ bidirectional alignments

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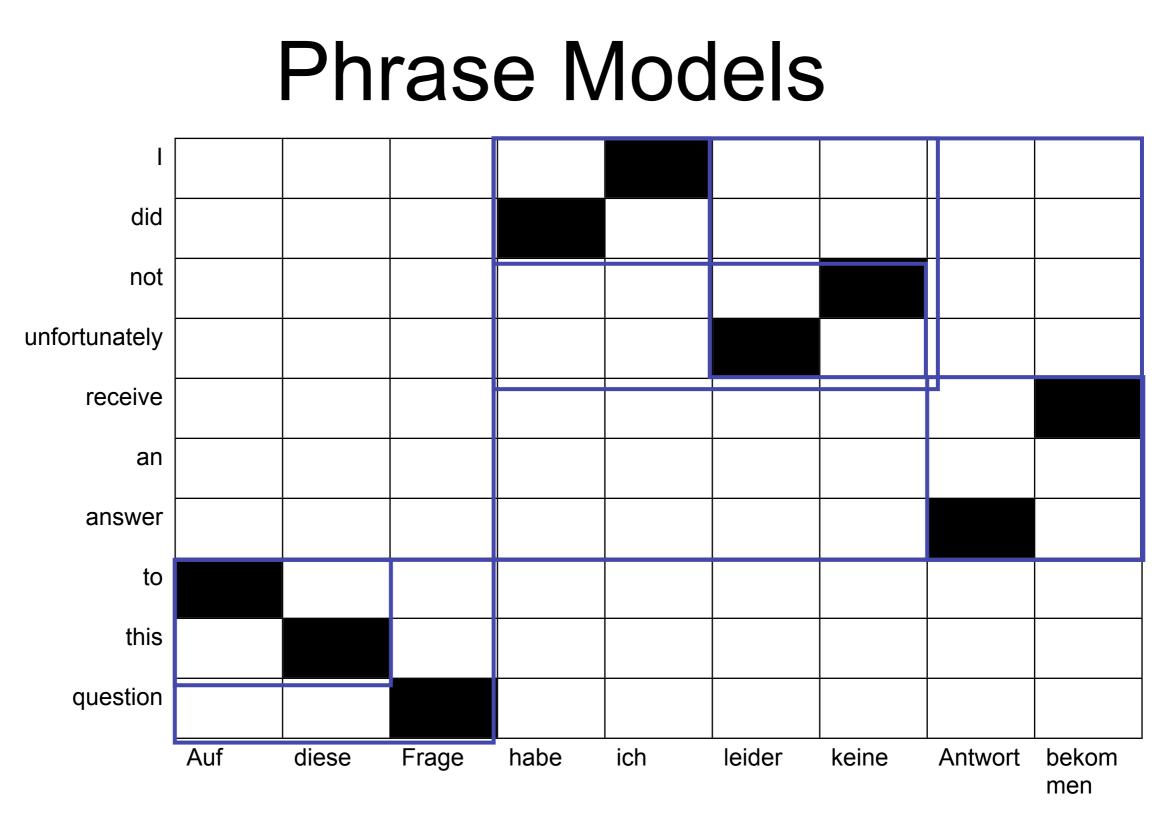
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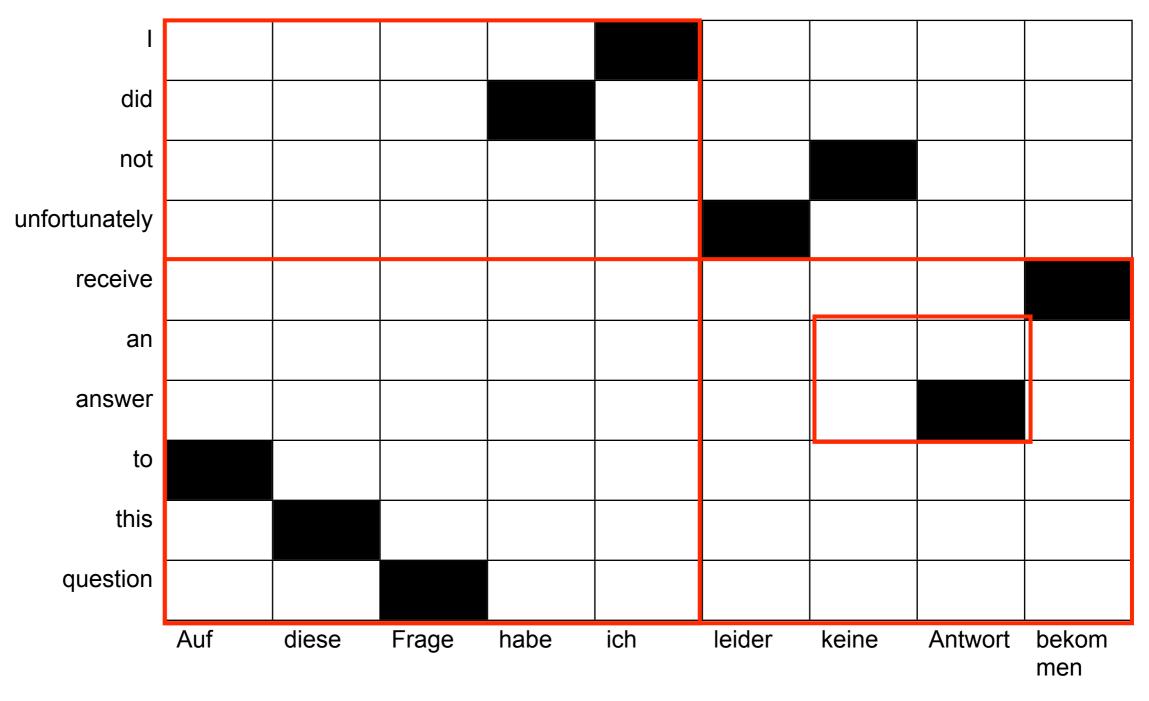
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Some good phrase pairs.

Phrase Models



Some bad phrase pairs.

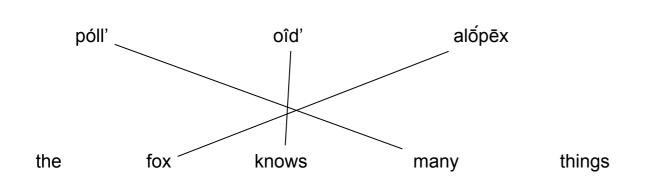
Synchronous Grammars

- Just like monolingual grammars except...

 Each rule involves pairs (tuples) of nonterminals
 Tuples of elementary trees for TAG, etc.
- First proposed for source-source translation in compilers
- Can be constituency, dependency, lexicalized, etc.
- Parsing speedups for monolingual grammar don't necessarily work

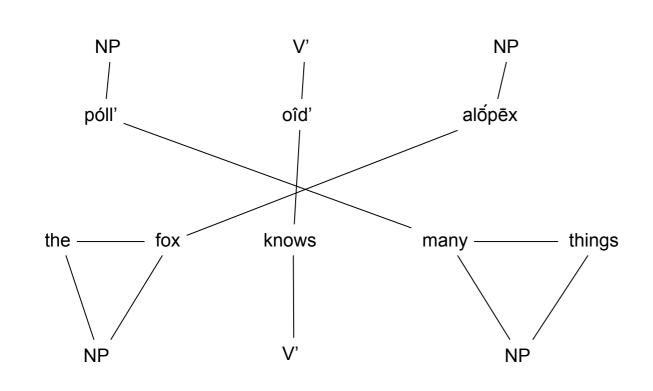
-E.g., no split-head trick for lexicalized parsing

Binarization less straightforward

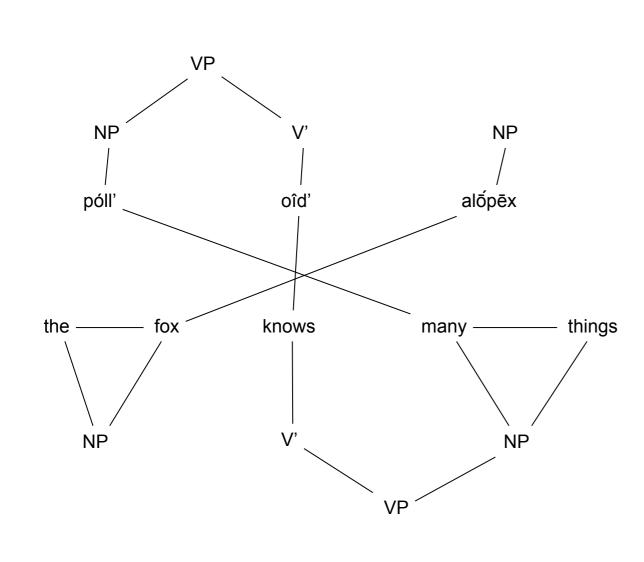


	póll'	oîd'	alốpēx
the			
fox			NN/NN
knows		VB/VB	
many	JJ/JJ		
things			

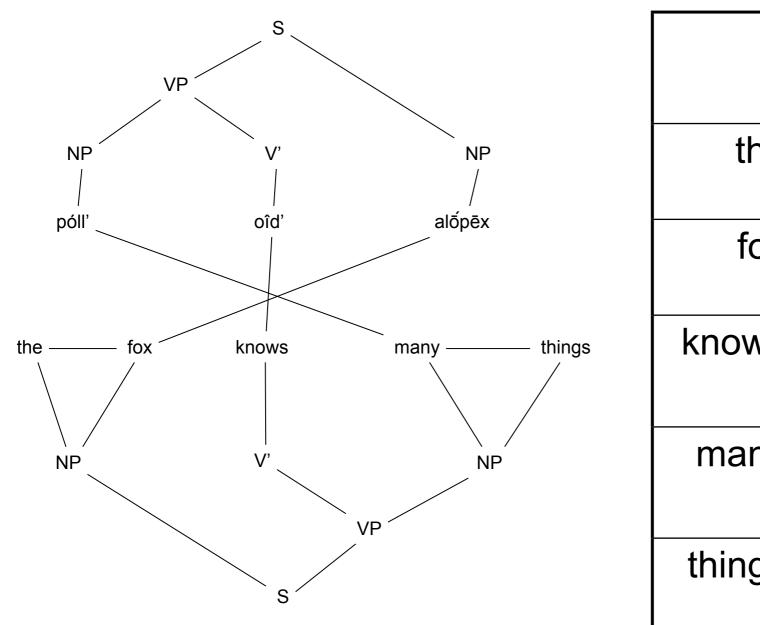
A variant of CKY chart parsing.



	póll'	oîd'	alốpēx	
the			NP/NP	
fox				
knows		VP/VP		
many				
things	NP/NP			



	póll'	oîd'	alốpēx
the			NP/NP
fox			
knows			
many	VP	/VP	
things			



	póll'	oîd'	alốpēx
the			
fox			
knows		S/S	
many			
things			