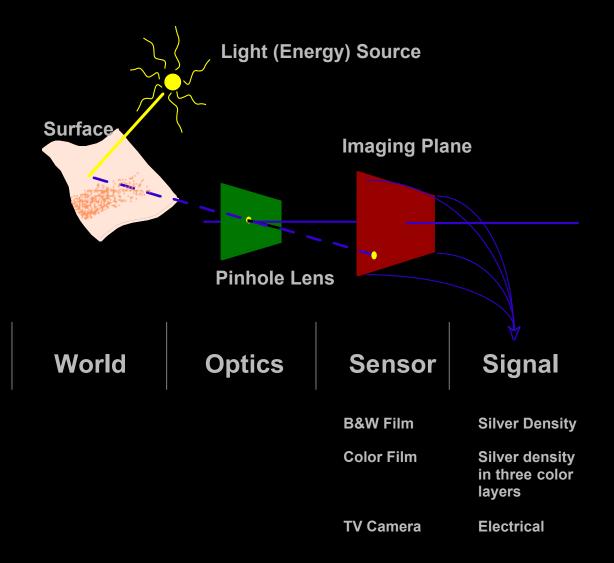


Computer Vision

Image Formation







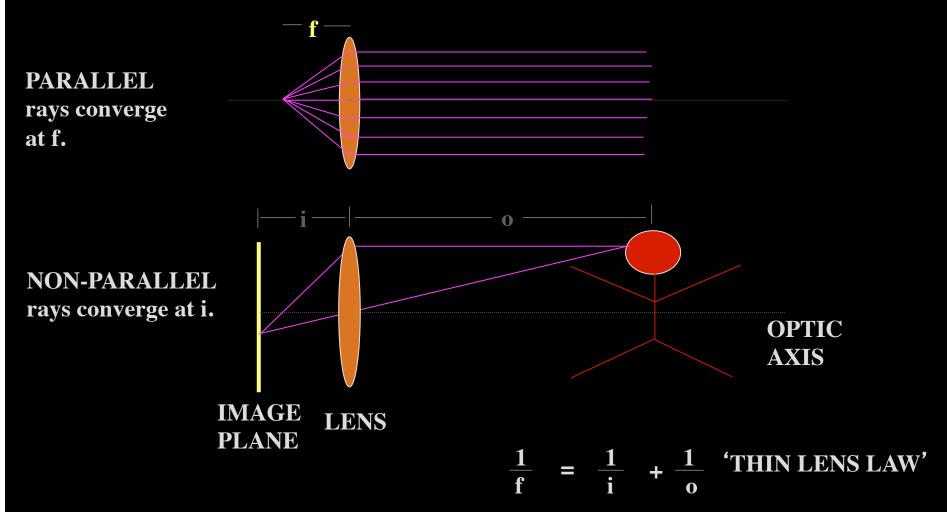
Optics:

- Pinhole cameras (last time).
- Lenses
- Artificial sensors
 - 1 sensor array vs. 3 sensor arrays
 - Bayer patterns



Thin Lens Model

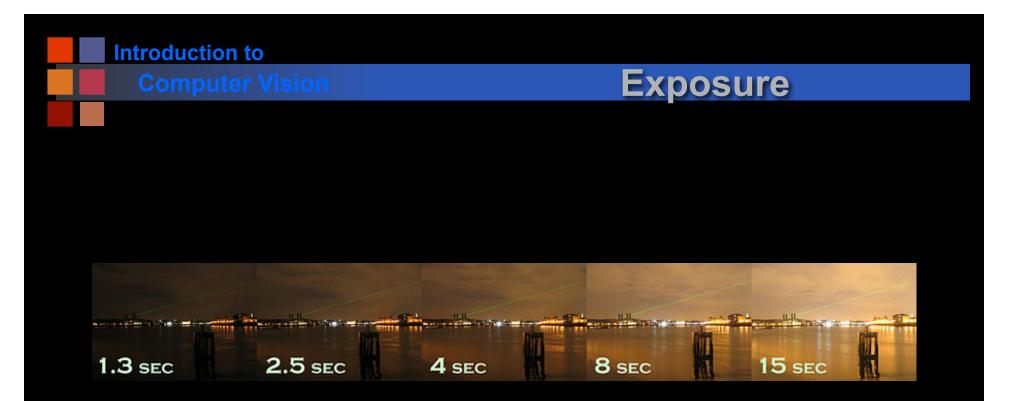
Rays entering parallel on one side converge at focal point.Rays diverging from the focal point become parallel.





Time of exposure

- Artificial cameras typically have a shutter that is opened and closed to let in light.
- The signal produced by the film or CCD array is typically *linear* in the exposure time.
- The more light that is let in, the less exposure time needed:
 - Bright light -> short exposure time
 - Low light -> long exposure time
 - Large aperture/lens -> short exposure time
 - Pinhole camera -> long exposure time.



http://en.wikipedia.org/wiki/File:Shutter_speed_in_Greenwich.jpg



Lenses

- Lenses allow the capture of more light.
- Suppose a pinhole camera with pinhole 1mm² needs an exposure time of 10 seconds to take a photo of a certain brightness?
- Consider a lens with diameter 2cm. How long would a photo need to be exposed using this lens?



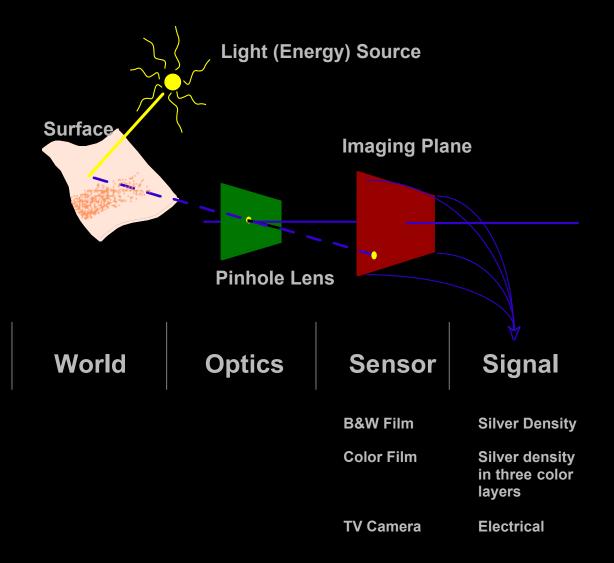
Lenses: practice

- Calculate "i" for objects at a certain distance.
- How much faster can we take a picture with a lens of diameter 2cm compared to a 1mm pinhole?



Computer Vision

Image Formation



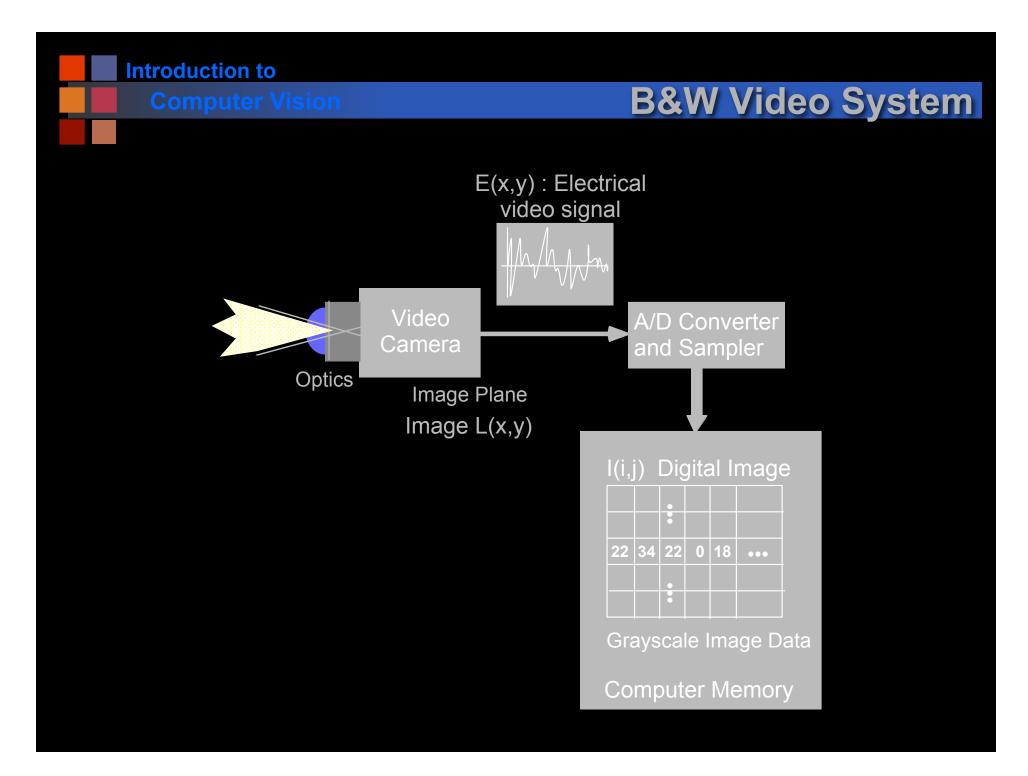


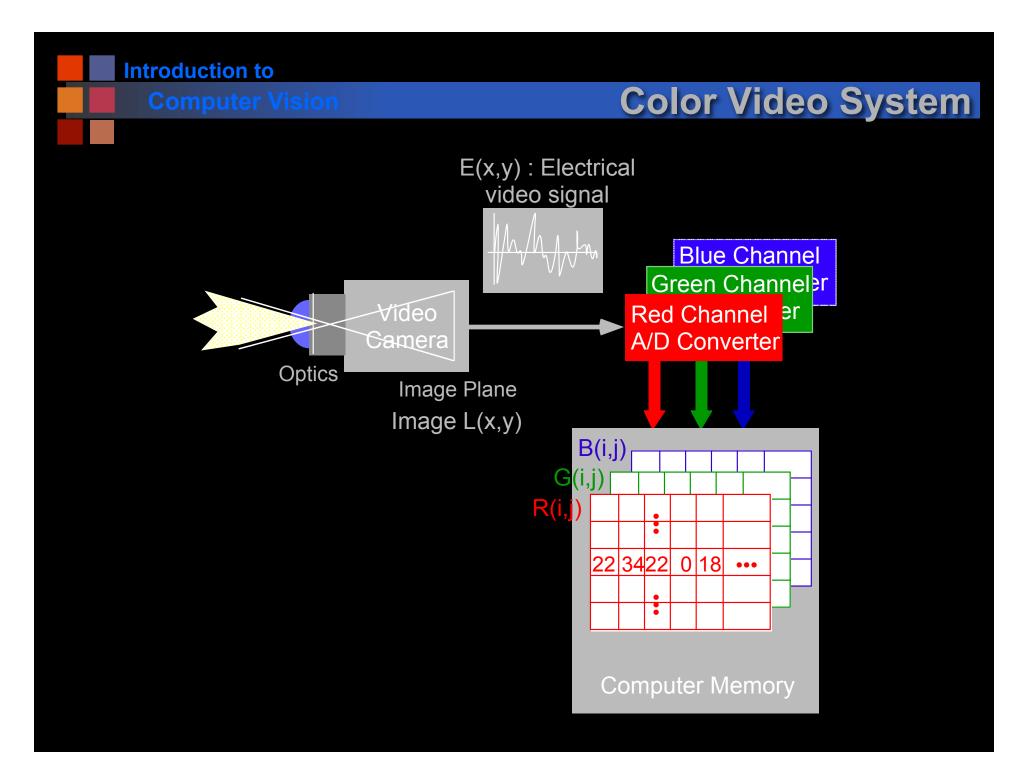
Photometry

Photometry:

Concerned with mechanisms for converting light energy into electrical energy.



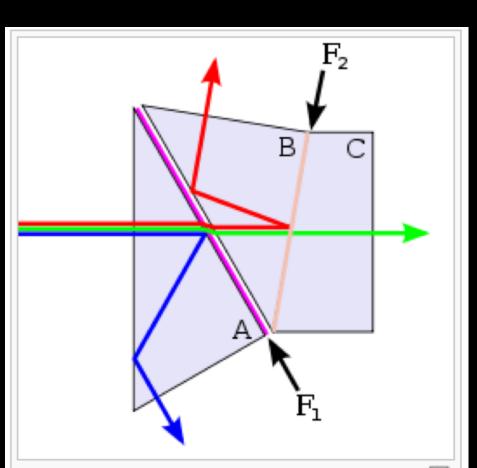






Computer Vision

Beam Splitter

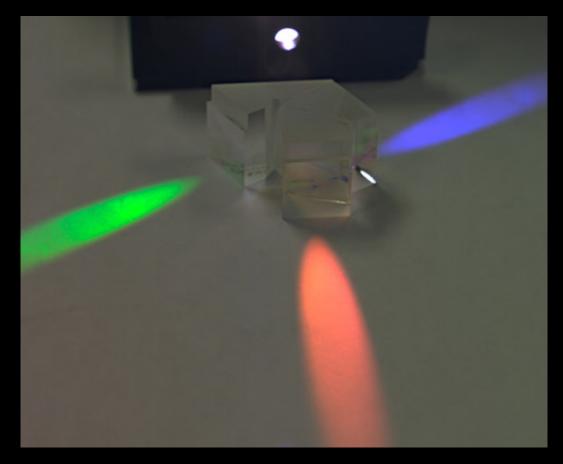


A Philips type trichroic beam splitter prism Schematic, with a different color separation order than the assembly shown in the photo. The red beam undergoes total internal reflection at the air gap, while the other reflections are dichroic.



Computer Vision

Trichroic Beam splitter





Computer Visior

3CCD cameras



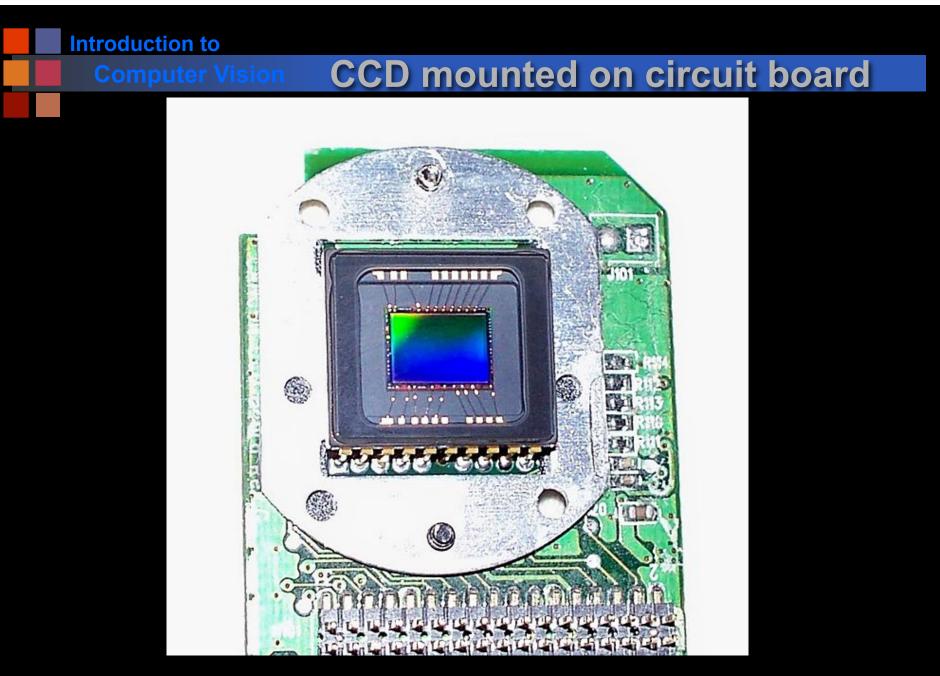
http://en.wikipedia.org/wiki/File:A_3CCD_imaging_block.jpg



Computer Vision

Sony 6 MegaPixel CCD



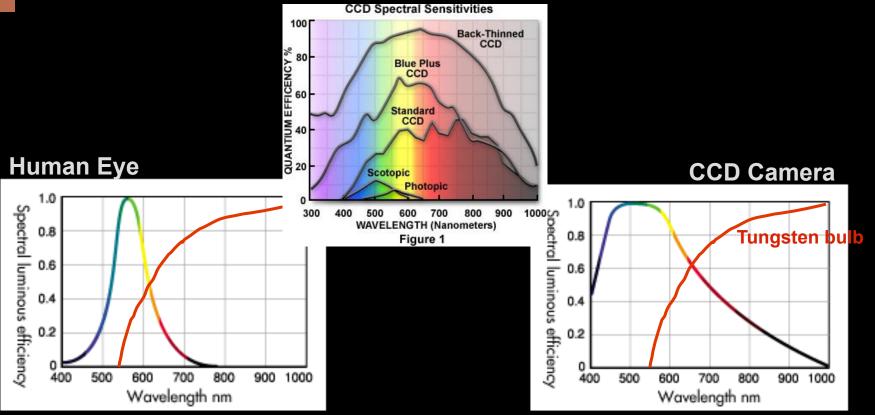


http://en.wikipedia.org/wiki/File:2.1_MP_CCD_Close_Up.JPG



Computer Vision

Spectral Sensitivity



- Figure 1 shows relative efficiency of conversion for the eye (scotopic and photopic curves) and several types of CCD cameras. Note the CCD cameras are much more sensitive than the eye.
- Note the enhanced sensitivity of the CCD in the Infrared and Ultraviolet (bottom two figures)
- Both figures also show a handrawn sketch of the spectrum of a tungsten light bulb



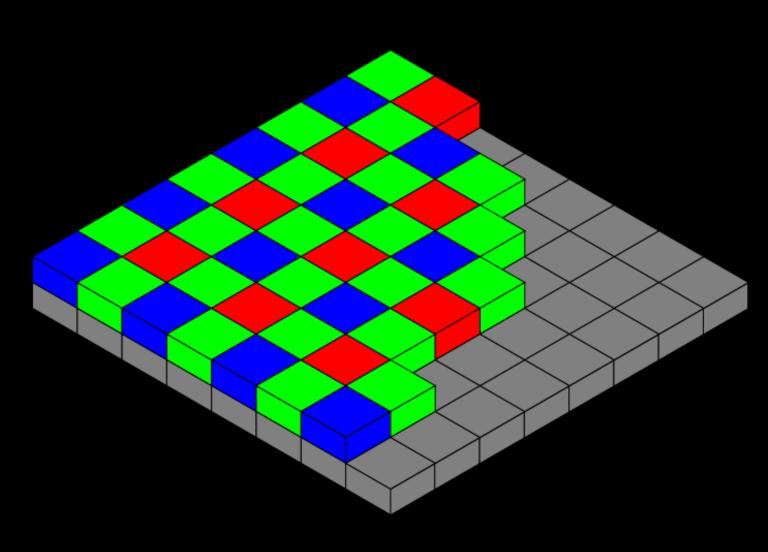
Building a camera with 1 CCD

- CCDs are expensive, and so are beam splitters.
- How do we build a camera with one CCD array?



Computer Vision

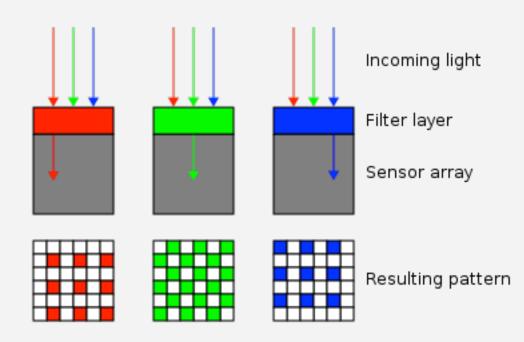
Bayer Filters





Computer Vision

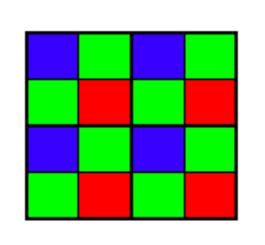
Bayer Filters





Computer Vision

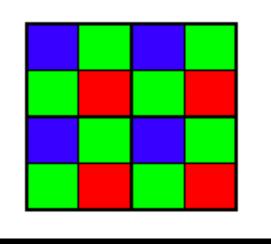
Bayer Filters

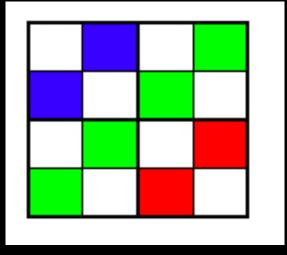




Computer Vision

Bayer Filters





Traditional design

Recent Kodak design

http://en.wikipedia.org/wiki/Bayer_filter



Introduction to

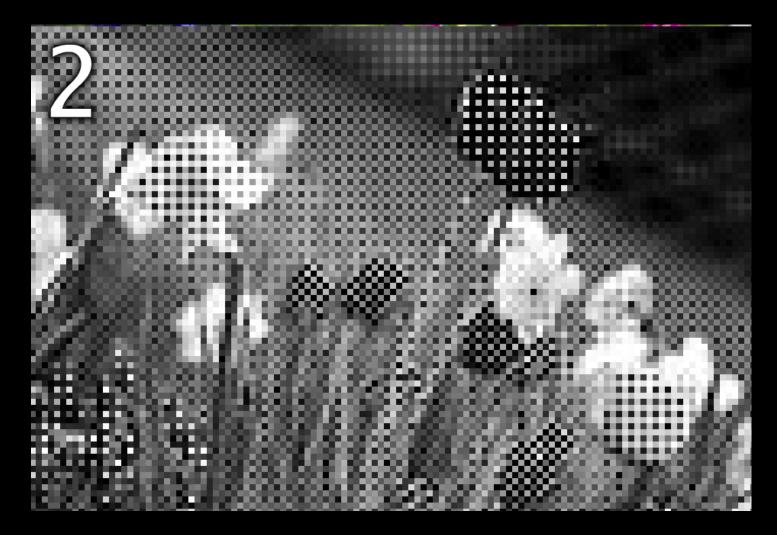
Bayer Filter Example





Introduction to

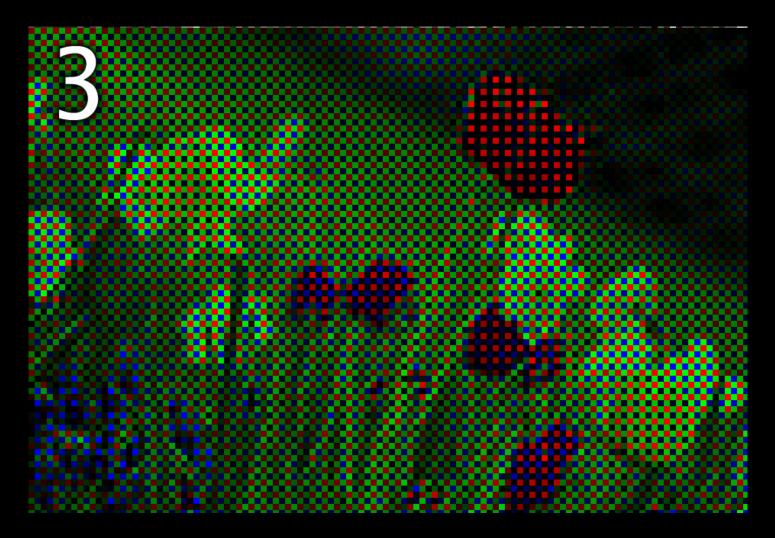
Bayer Filter Example





Introduction to

Bayer Filter Example





Introduction to

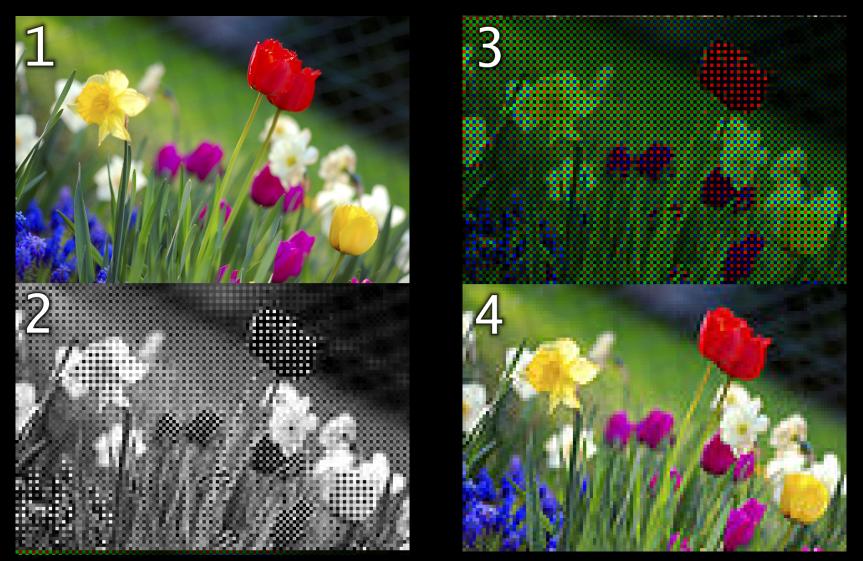
Bayer Filter Example





Computer Visior

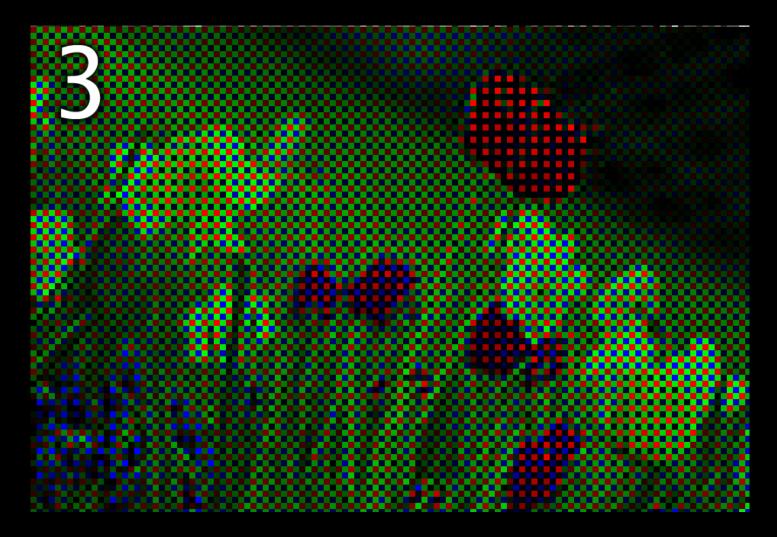
Bayer Filter





Introduction to

Interpolation techniques





Interpolation

- Copy pixel value to your left
- Bilinear interpolation within one color channel. 2.
 - Between 4 pixels: 1.
 - Take average of the 4.
 - Between 2 pixels: 2.
 - Take average of the 2.
- Many more sophisticated methods. 3.



Photometry

Photometry:

Concerned with mechanisms for converting light energy into electrical energy.





Pre-digitization image

What is an image before we digitize it?

- Continuous range of wavelengths.
- 2-dimensional extent
- Continuous range of power at each point.



Brightness images

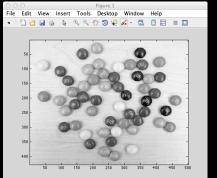
To simplify, consider only a brightness image:

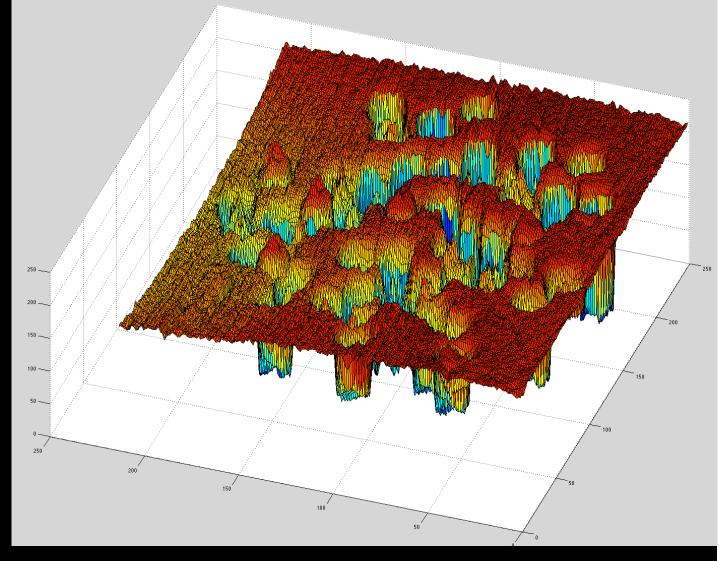
- Two-dimensional (continuous range of locations)
- Continuous range of brightness values.
- This is equivalent to a two-dimensional function over the plane.



Computer Vision

An image as a surface

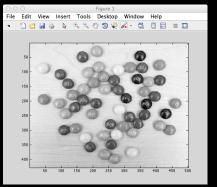




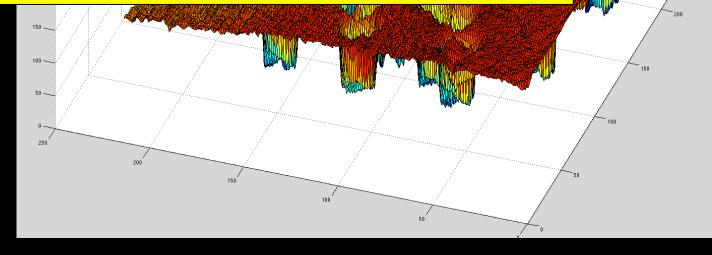


Computer Vision

An image as a surface



How do we represent this continuous surface efficiently?





Discretization

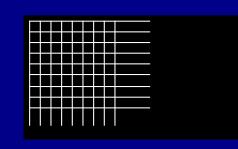
Sampling strategies:

- Spatial sampling
 - How many pixels?
 - What arrangement of pixels?
- Brightness sampling
 - How many brightness values?
 - Spacing of brightness values?
- For video, also the question of time sampling.



Computer Vision

Projection through a pixel



Digitized 35mm Slide or Film

Central Projection Ray

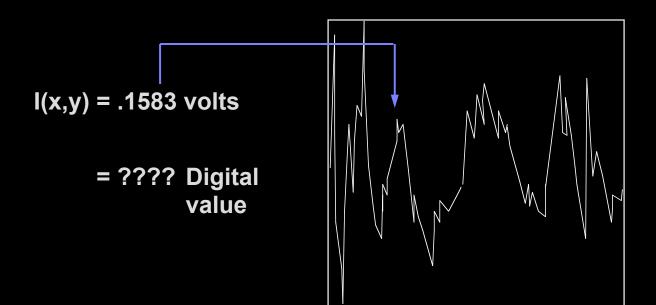
Image irradiance is the average of the scene radiance over the area of the surface intersecting the solid angle!



Computer Visior

Signal Quantization

Goal: determine a mapping from a continuous signal (e.g. analog video signal) to one of K discrete (digital) levels.

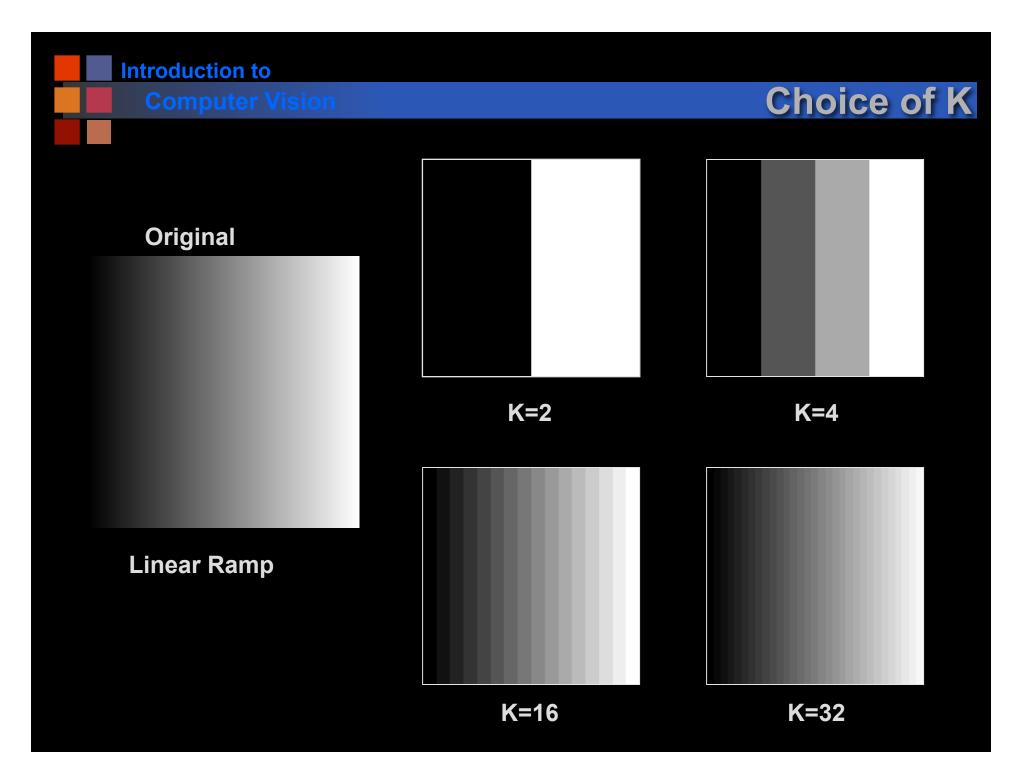




- $I(x,y) = continuous signal: 0 \le I \le M$
- Want to quantize to K values 0,1,....K-1
- K usually chosen to be a power of 2:

K:	#Levels	#Bits
	2	1
	4	2
	8	3
	16	4
	32	5
	64	6
	128	7
	256	8

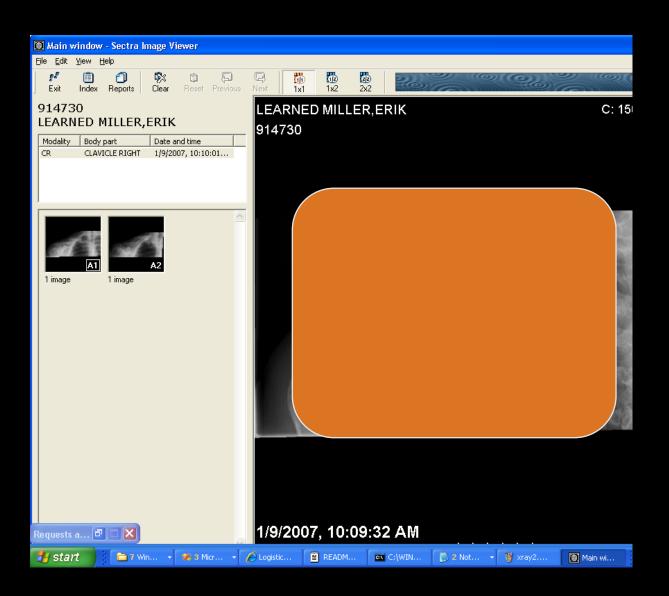
Mapping from input signal to output signal is to be determined.
Several types of mappings: uniform, logarithmic, etc.





Computer Vision

Digital X-rays





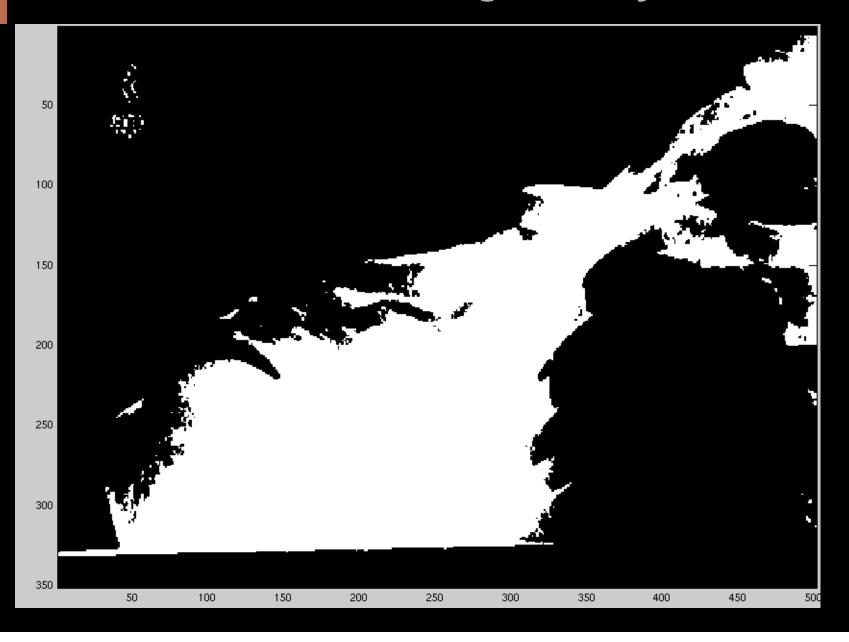
How many bits do we need?





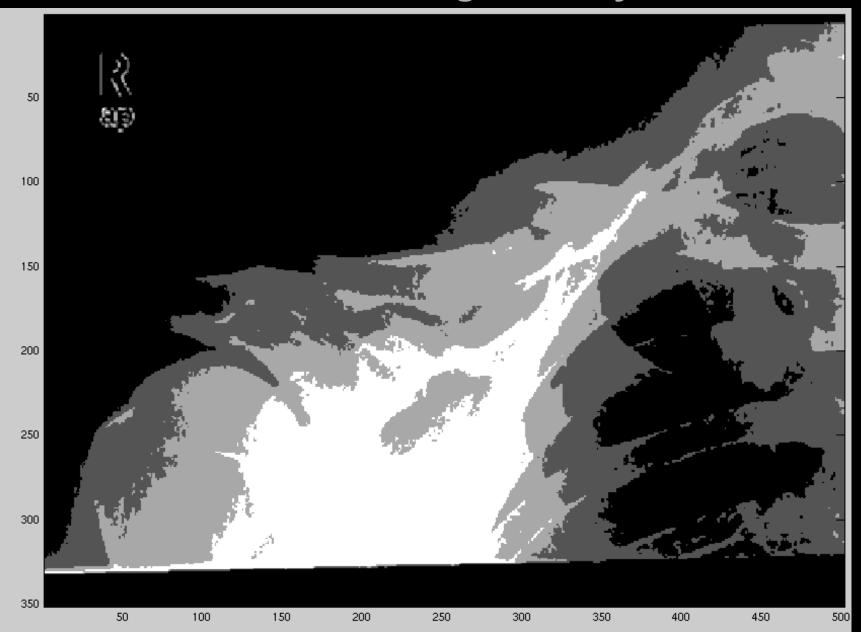
Computer Vision

Digital X-rays: 1 bit



Computer Visior

Digital X-rays: 2 bits

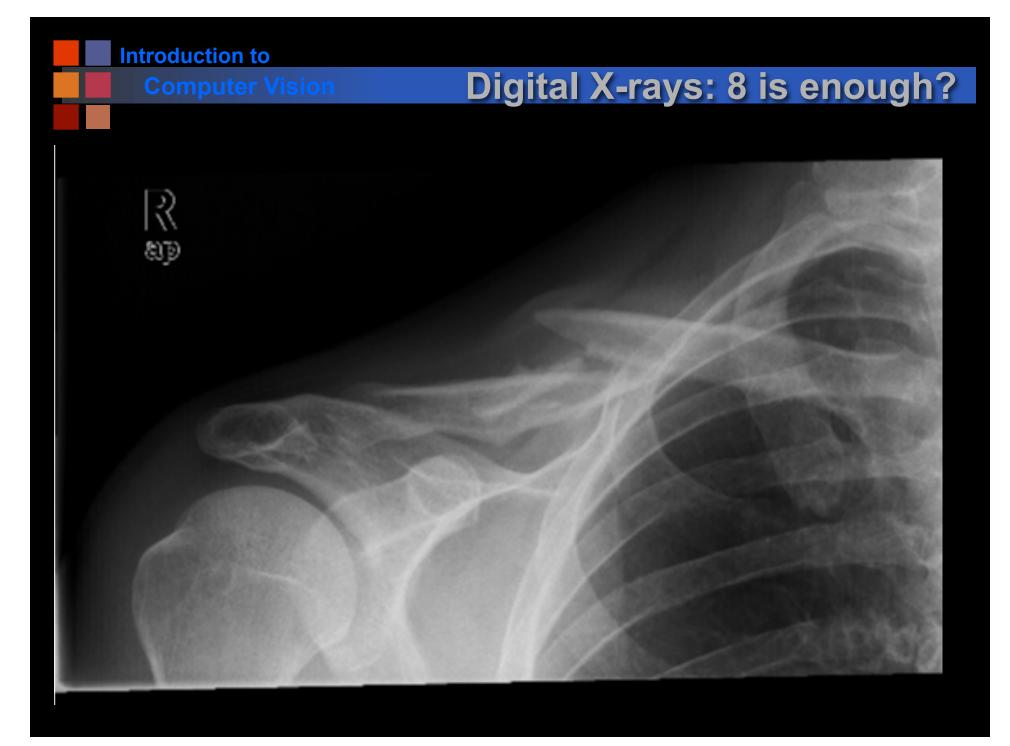




Computer Vision

Digital X-rays: 3 bit

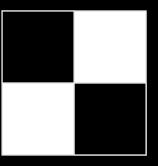






Gray Levels-Resolution Trade Off

- More gray levels can be simulated with more resolution.
- A "gray" pixel:



Doubling the resolution in each direction adds at least 3 new gray levels. But maybe more?



Computer Visior

Pseudocolor





Computer Vision

Digital X-rays: 8 is enough?





Computer Visior







Computer Vision

Choice of K





K=2 (each color)

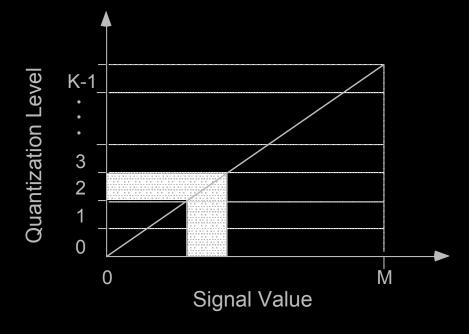


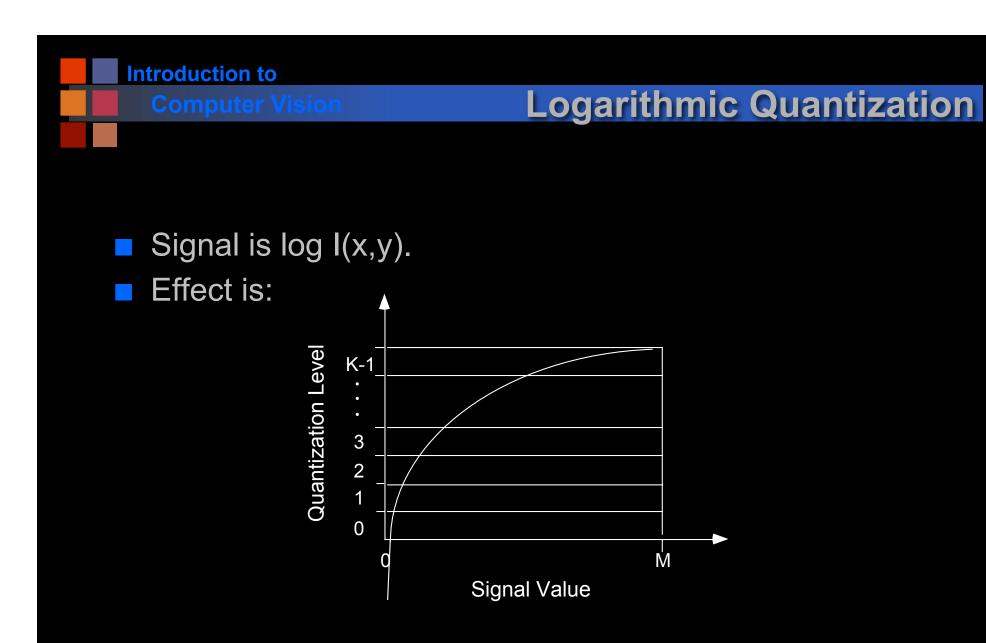
K=4 (each color)

Introduction to

Choice of Function: Uniform

- Uniform sampling divides the signal range [0-M] into K equal-sized intervals.
- The integers 0,...K-1 are assigned to these intervals.
- All signal values within an interval are represented by the associated integer value.
- Defines a mapping:





Detail enhanced in the low signal values at expense of detail in high signal values.

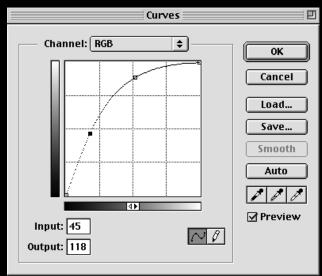


Computer Visior

Logarithmic Quantization



Quantization Curve







Computer Vision

