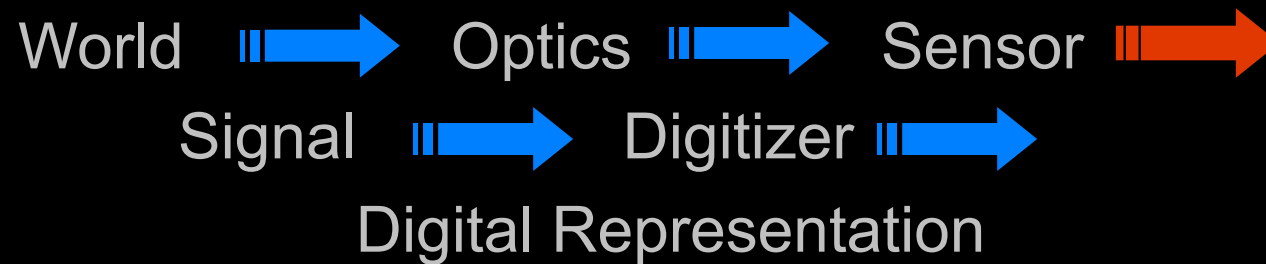


Introduction to

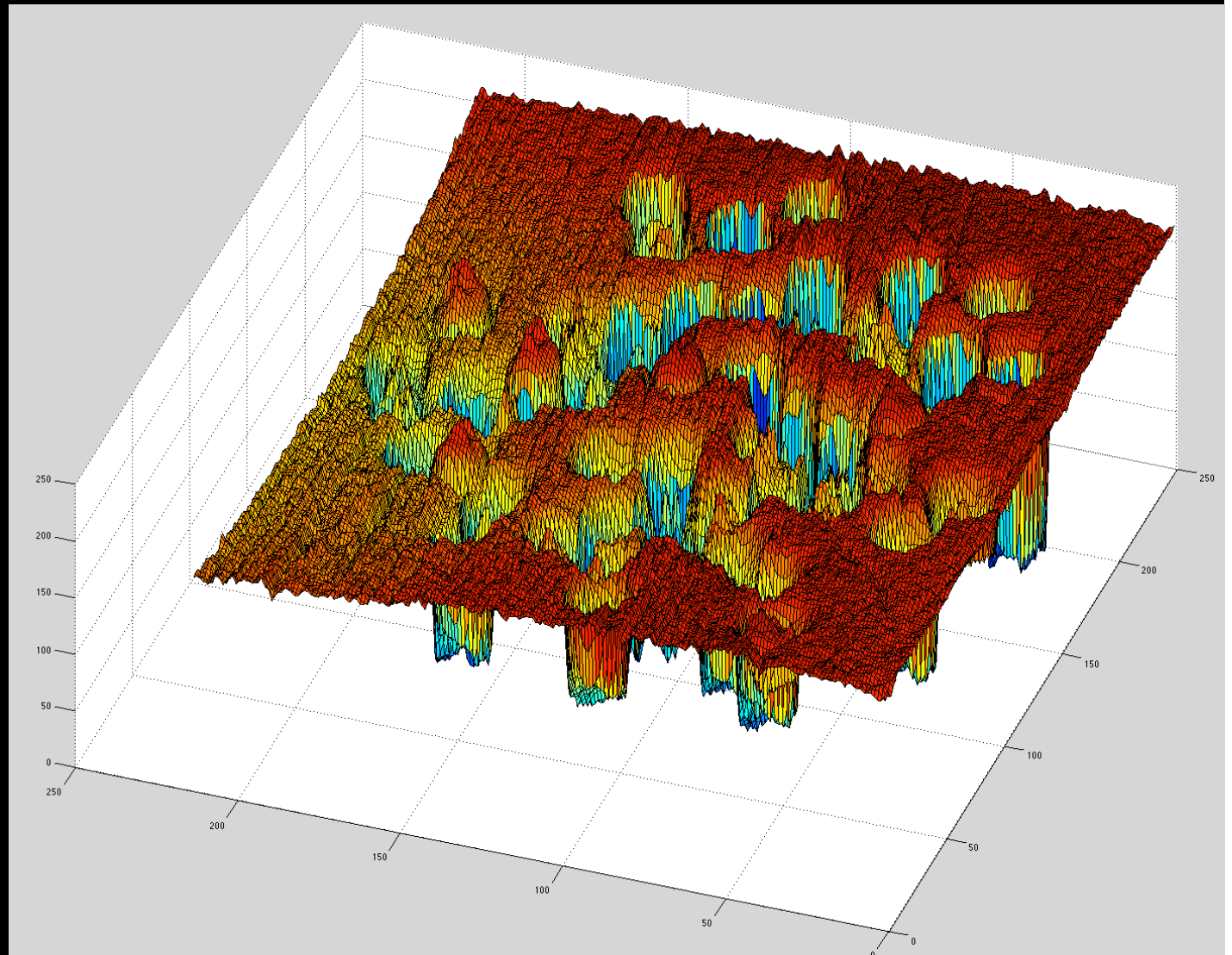
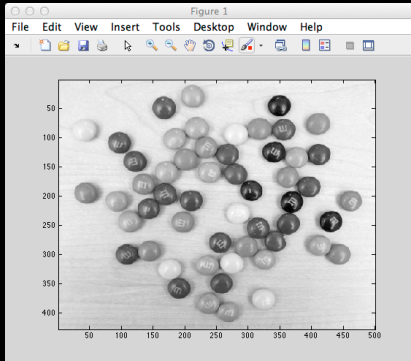
Computer Vision

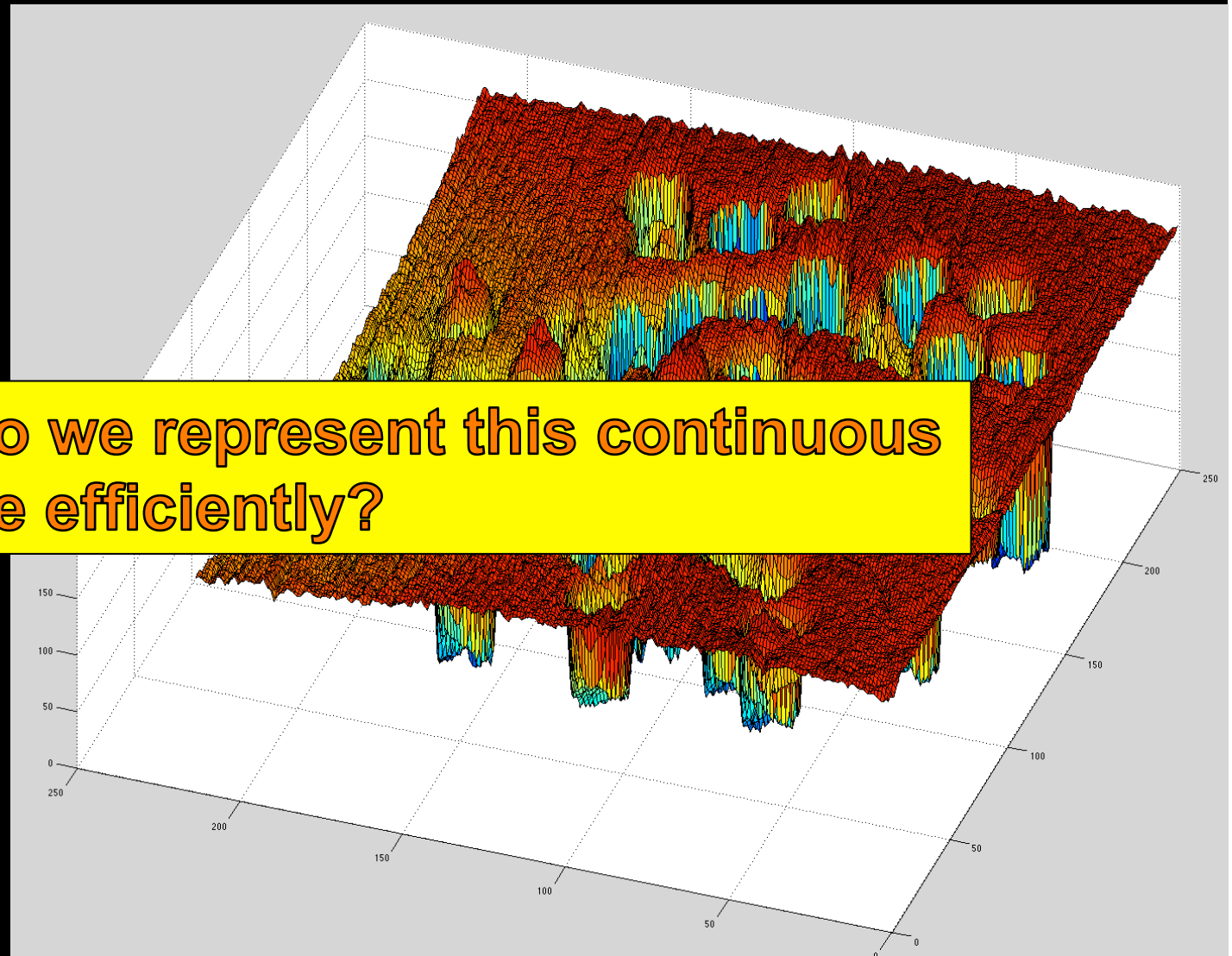
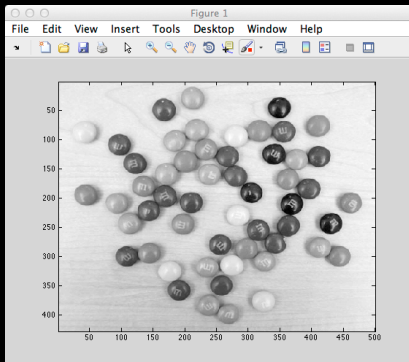
Digitization



- What is an image before we digitize it?
 - Continuous range of wavelengths.
 - 2-dimensional extent
 - Continuous range of power at each point.

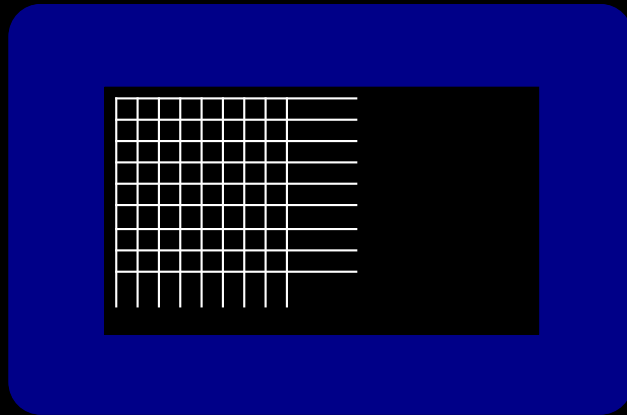
- To simplify, consider only a brightness image:
 - Two-dimensional (continuous range of locations)
 - Continuous range of brightness values.
- This is equivalent to a two-dimensional function over the plane.





How do we represent this continuous surface efficiently?

- Sampling strategies:
 - Spatial sampling
 - How many pixels?
 - What arrangement of pixels?
 - Brightness sampling
 - How many brightness values?
 - Spacing of brightness values?
 - For video, also the question of time sampling.



Digitized 35mm Slide or Film

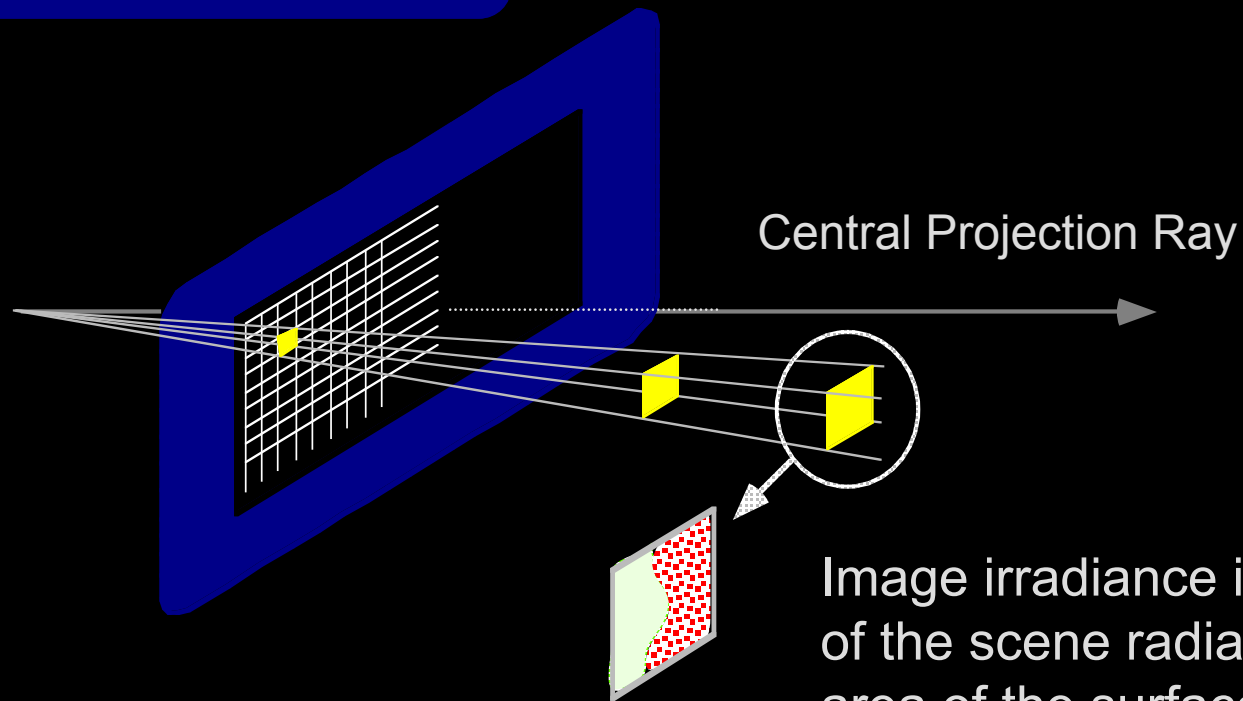
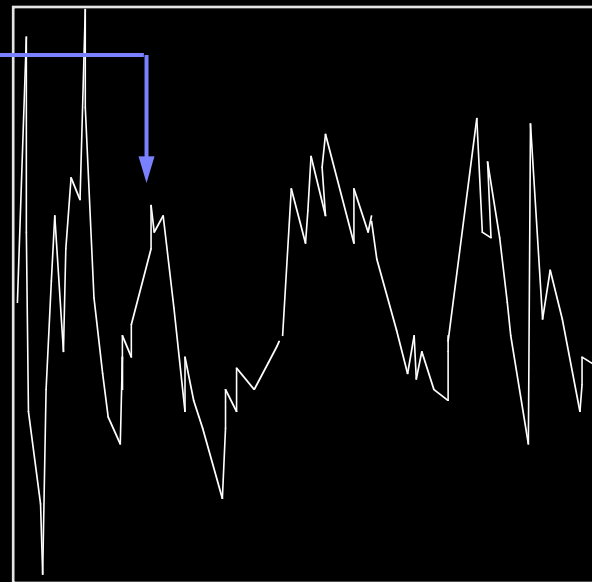


Image irradiance is the average of the scene radiance over the area of the surface intersecting the solid angle!

- Goal: determine a mapping from a continuous signal (e.g. analog video signal) to one of K discrete (digital) levels.

$I(x,y) = .1583$ volts

= ???? Digital
value

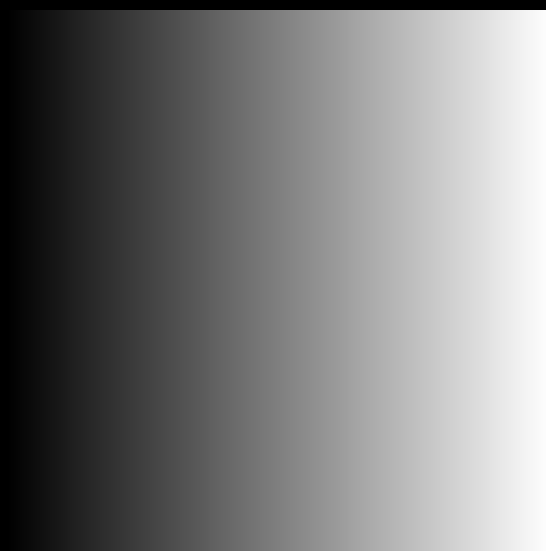


- $I(x,y)$ = continuous signal: $0 \leq I \leq M$
- Want to quantize to K values $0, 1, \dots, K-1$
- K usually chosen to be a power of 2:

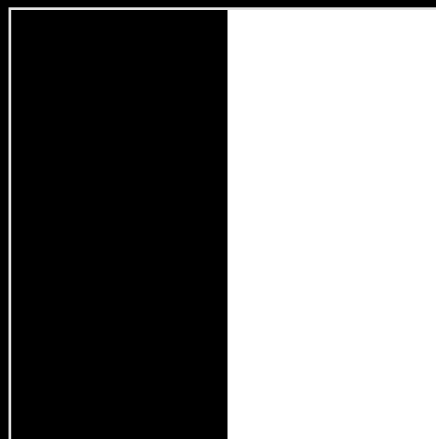
K: #Levels	#Bits
2	1
4	2
8	3
16	4
32	5
64	6
128	7
256	8

- Mapping from input signal to output signal is to be determined.
- Several types of mappings: uniform, logarithmic, etc.

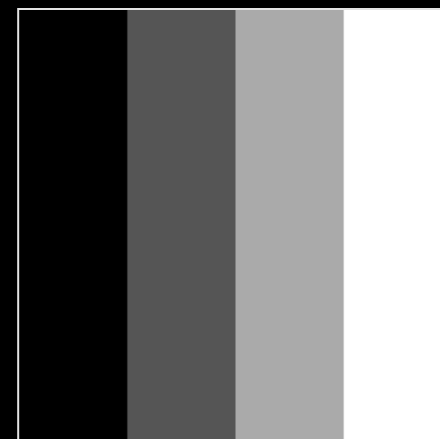
Original



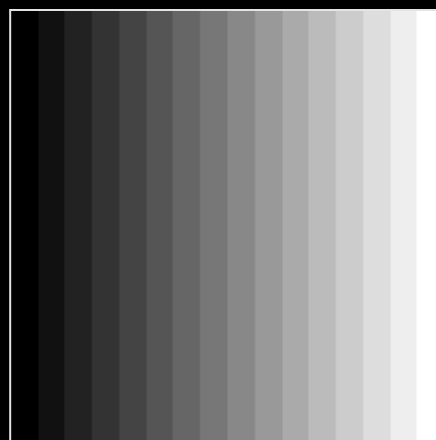
Linear Ramp



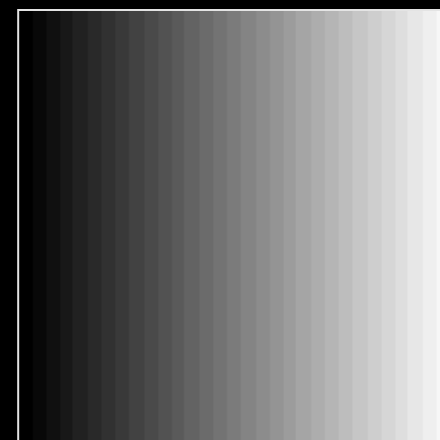
K=2



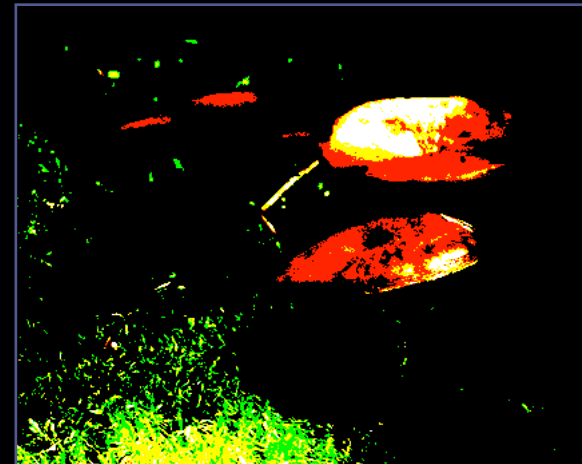
K=4



K=16



K=32

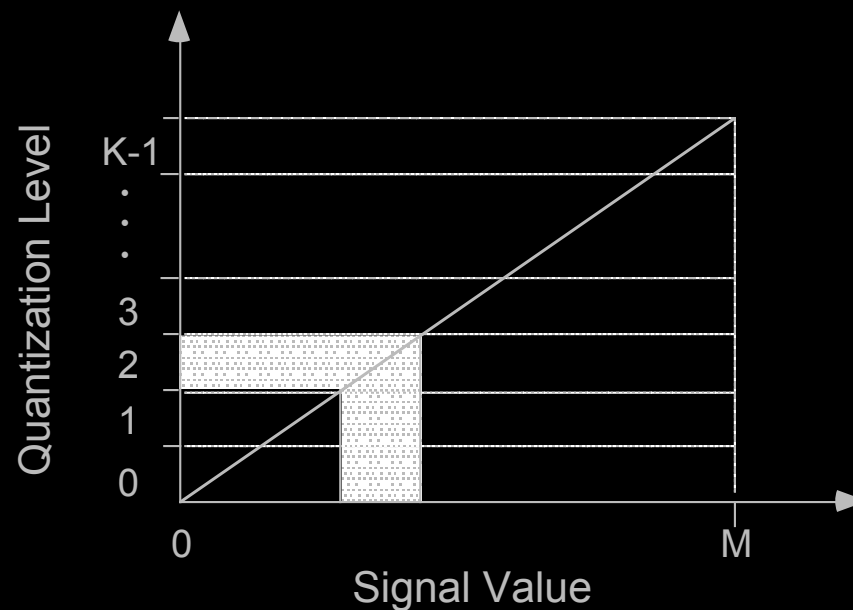


K=2 (each color)

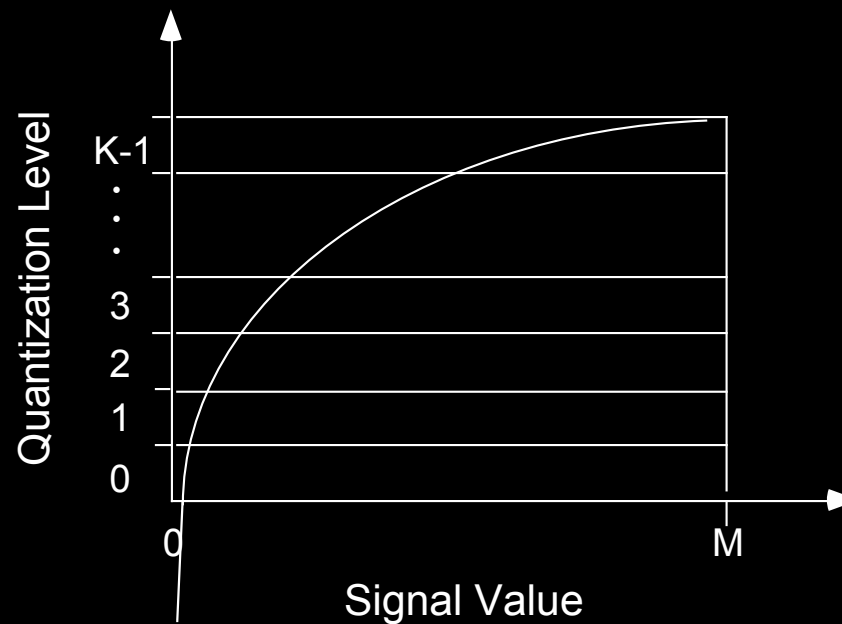


K=4 (each color)

- Uniform sampling divides the signal range $[0-M]$ into K equal-sized intervals.
- The integers $0, \dots, K-1$ are assigned to these intervals.
- All signal values within an interval are represented by the associated integer value.
- Defines a mapping:

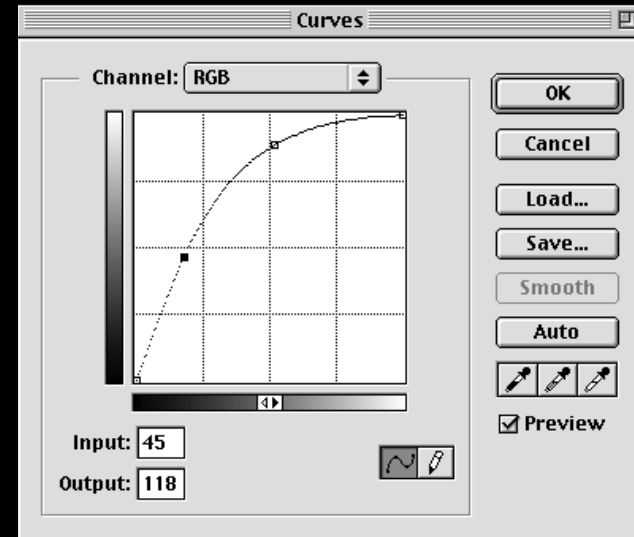


- Signal is $\log I(x,y)$.
- Effect is:

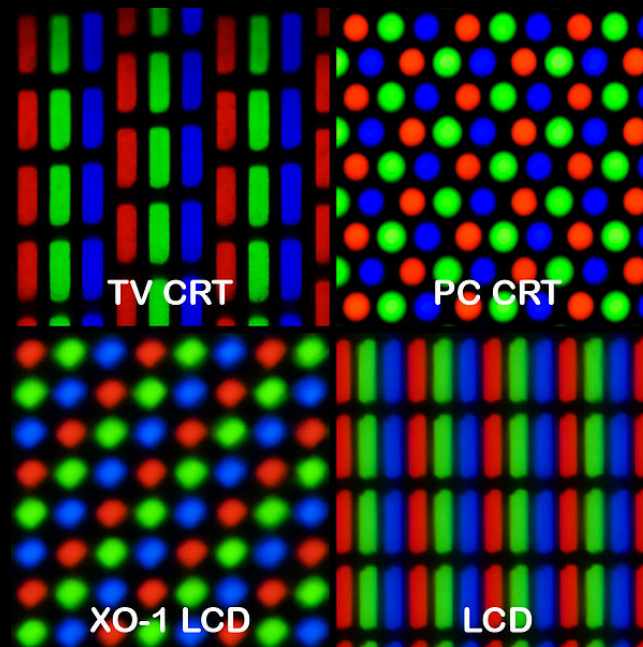


- Detail enhanced in the low signal values at expense of detail in high signal values.

Quantization Curve

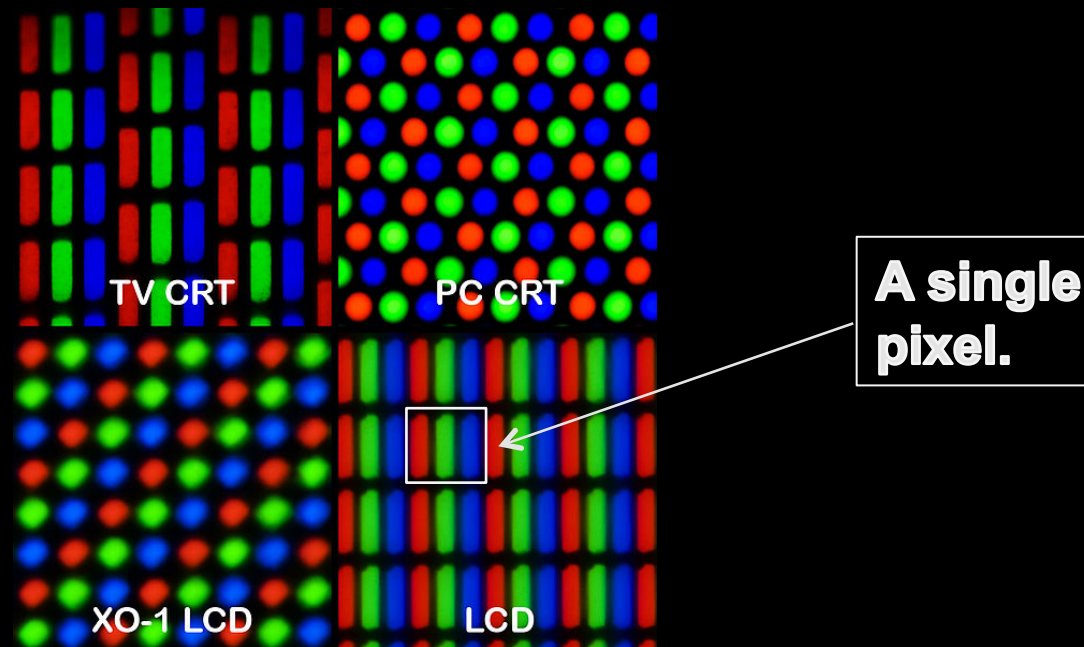


- Given a 24-bit color image (8 bits each for R,G,B)
 - Turn on 3 subpixels with power proportional to RGB values:





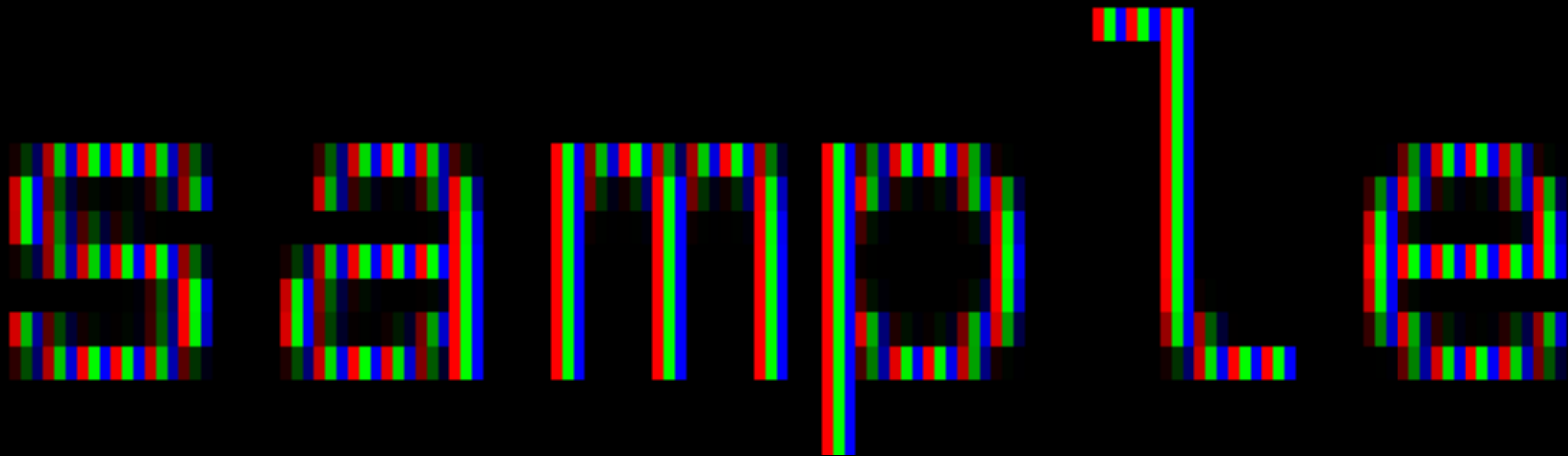
- Given a 24-bit color image (8 bits each for R,G,B)
 - Turn on 3 subpixels with power proportional to RGB values:



Introduction to

Computer Vision

“White” text on a color display



sample

http://en.wikipedia.org/wiki/Subpixel_rendering

  Introduction to

  Computer Vision

Color selector



  Introduction to

  Computer Vision **Constructing a Color LCD Display**

- See movie.

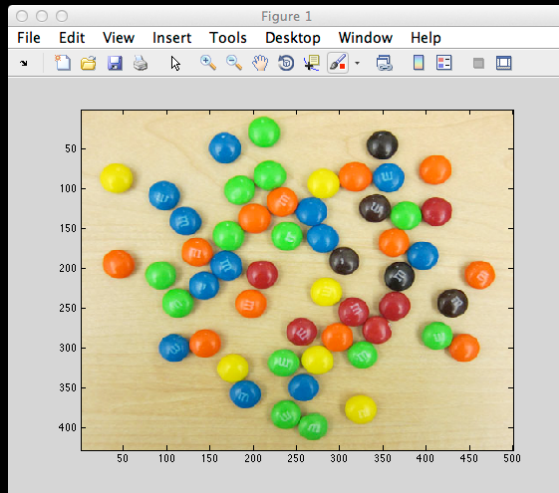


- 8 bit image: 256 different values.
 - Simplest way to display: map each number to a gray value:
 - 0-> (0.0, 0.0, 0.0)
 - 1->(0.0039, 0.0039, 0.0039) or (1,1,1)
 - 2->(0.0078, 0.0078, 0.0078) or (2,2,2)
 - ...
 - 255-> (1.0, 1.0, 1.0) or (255,255,255)
 - This is called a grayscale image.

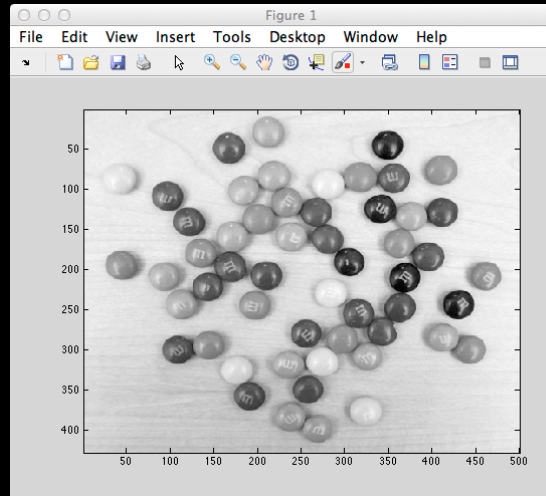
Introduction to

Computer Vision

Lookup tables



im (24 bits)
"true color"



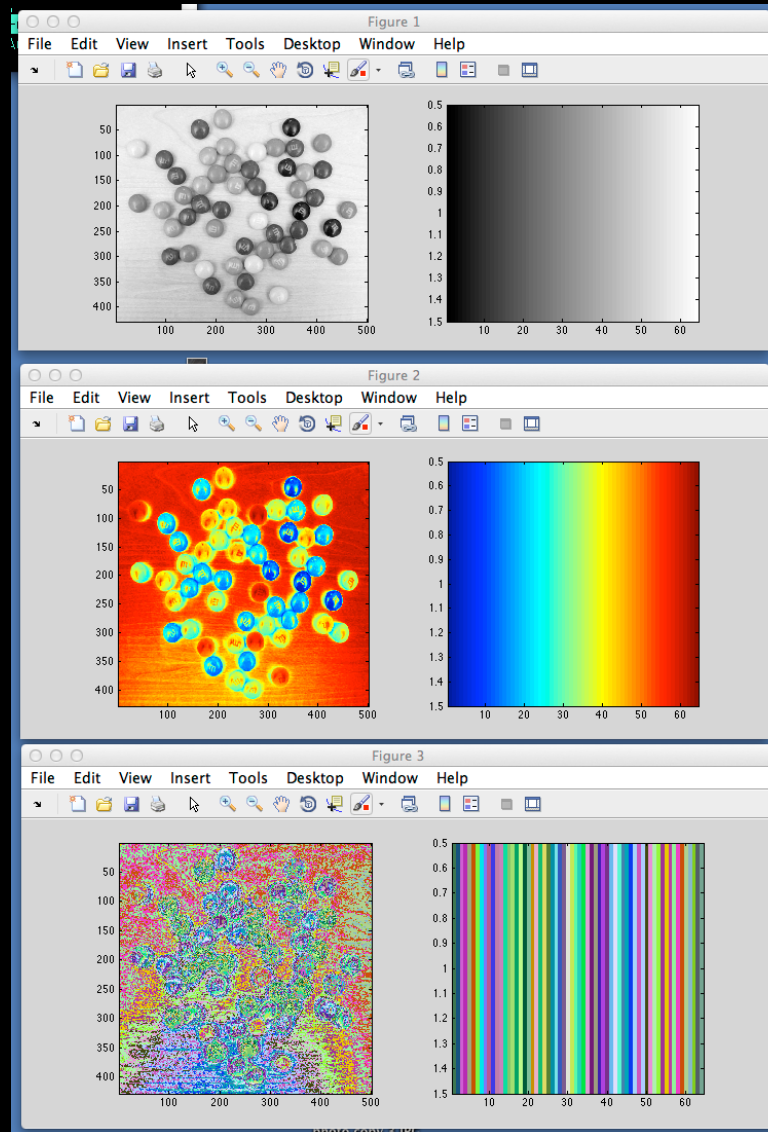
im8 (8 bits)
gray color look up table

```
>> imagesc(im);  
>> size(im)  
  
ans =  
  
    428    500     3  
  
>> im8=rgb2gray(im);  
>> size(im8)  
  
ans =  
  
    428    500  
  
>> imagesc(im8)  
>> colormap(gray)
```

- We can also use other mappings:
 - 0->(17, 25, 89)
 - 1-> (45, 32, 200)
 - ...
 - 255-> (233,1,4)
- These are called look up tables.

Introduction to
Computer Vision

More look up tables.



  Introduction to

  Computer Vision

Fun with matlab

- What can we do to “enhance” an image after it has already been digitized?
 - We can make the information that is there *easier to visualize*.
 - We can guess at data that is not there, but we cannot be sure, in general.

  Introduction to

  Computer Vision

Can we “enhance” an image after digitization?

- Two methods:
 - Change the data (histogram equalization)
 - Use a look up table (brightness or color remapping)

Introduction to

Computer Vision

Histogram Equalization



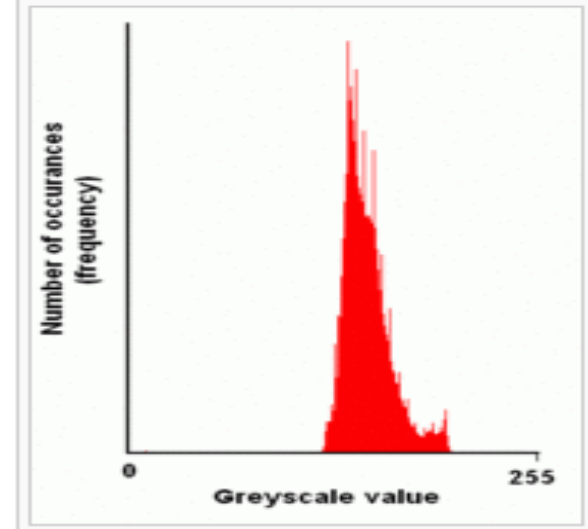
An unequalized image



Histogram Equalization



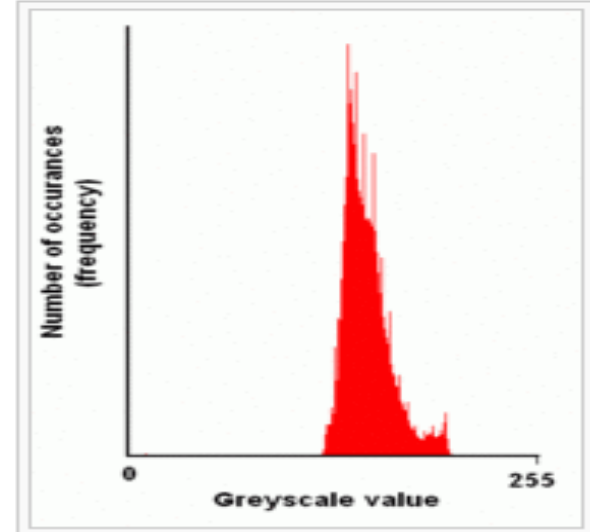
An unequalized image



Corresponding histogram



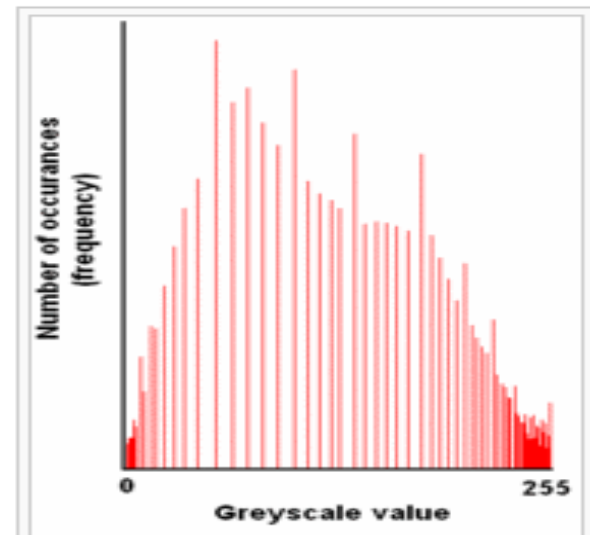
An unequalized image



Corresponding histogram

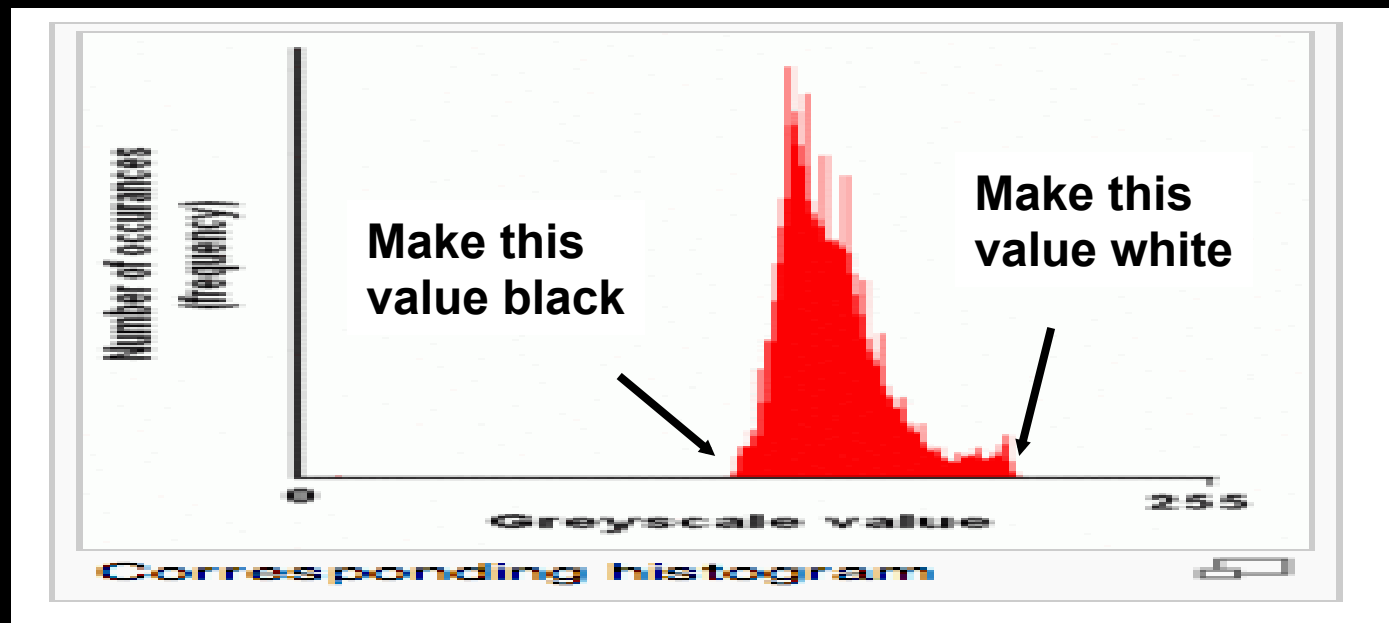


Same image after histogram equalization



Corresponding histogram

- Two methods:
 - Change the data (histogram equalization).
 - Use a look up table (brightness equalization).



Map lowest value in image to black, highest value to white.

- 0 -> (0, 0, 0)
- 1 -> (0, 0, 0)
- 2 -> (0, 0, 0)
- 3 -> (0, 0, 0)
- ...
- 130-> (0,0,0)
- 131-> (.01, .01, .01)
- 132-> (.02,.02,.02)
- ...
- 229->(1,1,1)
- 230->(1,1,1)
- ...
- 255 -> (1, 1, 1)



An unequalized image



Introduction to

Computer Vision

Mixed Pixel Problem





- Typical recognition problems:
 - Recognize letters and words
 - Recognize people
 - Recognize classes of objects
 - Recognize places

Introduction to

Computer Vision

Recognizing Text



UNITED STATES

*POSTAL SERVICE*TM



The image shows the United States Postal Service logo, which consists of the words "UNITED STATES" in a blue, italicized, sans-serif font, followed by a horizontal red line, and then the words "POSTAL SERVICE" in the same blue, italicized, sans-serif font. A small "TM" trademark symbol is located at the end of "SERVICE".









- Supervised learning:
 - Formalization of the idea of learning from examples.
- 2 elements:
 - Training data
 - Test data
- Training data:
 - Data in which the *class* has been identified.
 - Example: This is a “three”. 
- Test data:
 - Data which the algorithm is supposed to identify.
 - What is this? 

■ Formally:

- n training data pairs:

$$(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_n, y_n)$$

x's are "observations"

y's are the class labels

- m test data samples:

$$(\mathbf{x}_{n+1}, \mathbf{x}_{n+2}, \dots, \mathbf{x}_{n+m})$$