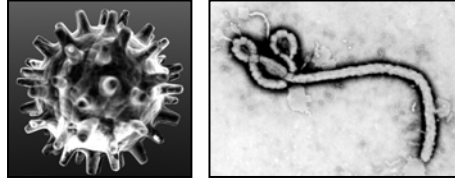
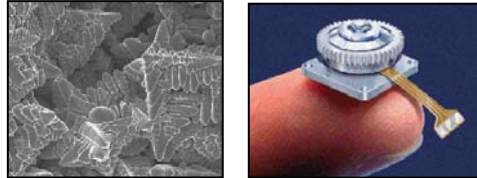


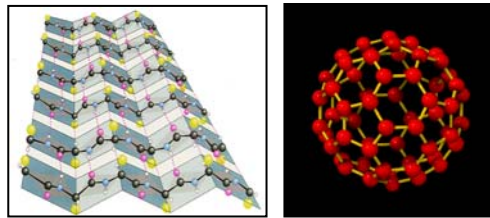
Why build a nano robot?



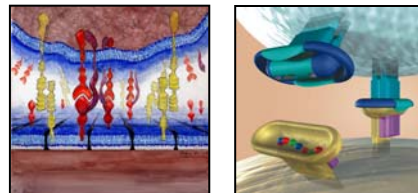
What must we consider when designing “small” robots?



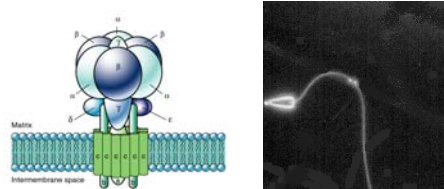
What are possible building blocks for nano robots?



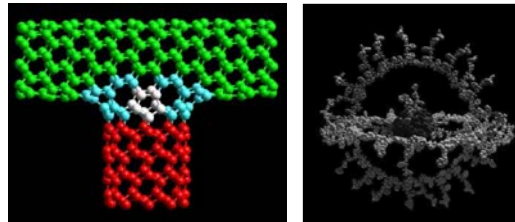
What sensors might a nano robot possess?



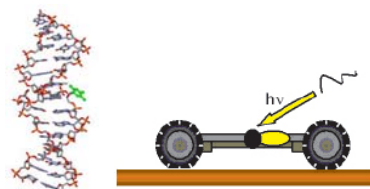
How might we enable a nano robot to exhibit motion?



How do we assemble a nano robot?
Modular design?
Why?



How can we control a nano robot?



Intelligence?
Self-replication?