

601 Lect 19: Recall Last Time: Finite Model Theory

Def: **FO** is the set of first-order definable decision problems on finite structures.

Def: **SO \exists** is the set of second-order-existential definable decision problems on finite structures.

Thm: **FO** \subseteq **L** = **DSPACE** $[\log n]$

Fagin's Thm: **NP** = **SO \exists** .

Cook's Thm: SAT is NP-complete.

Proof: Let $B \in \mathbf{NP}$. By Fagin's theorem,

$$B = \{ \mathcal{A} \mid \mathcal{A} \models \Phi \}; \quad \Phi \equiv \exists C_0^{2k} \dots C_{g-1}^{2k} \Delta^k \forall x_1 \dots x_t (\alpha(\bar{x}))$$

with α quantifier-free and CNF,

$$\alpha(\bar{x}) = \bigwedge_{i=1}^r \bigvee_{j=1}^s \lambda_{i,j}(\bar{x})$$

where each $\lambda_{i,j}$ is a literal.

\mathcal{A} arbitrary, $n = \|\mathcal{A}\|$, Define boolean formula $\varphi_{\mathcal{A}}$:

boolean variables: $C_i(e_1, \dots, e_{2k}), \Delta(e_1, \dots, e_k)$

$i = 1, \dots, g, e_1, \dots, e_{2k} \in |\mathcal{A}|$

literals: $\lambda_{i,j}(\bar{e}), i = 1, \dots, r, j = 1, \dots, s, \bar{e} \in |\mathcal{A}|^t$

$\lambda'_{i,j}(\bar{e})$ is $\lambda_{i,j}(\bar{e})$ with $R(\bar{e})$, replaced by \top or \perp according as $\mathcal{A} \models R(\bar{e})$; $C_i(\bar{e})$, and $\Delta(\bar{e})$ are just boolean variables.

$$\Phi \equiv \exists C_0^{2k} \dots C_{g-1}^{2k} \Delta^k \forall x_1 \dots x_t \bigwedge_{i=1}^r \bigvee_{j=1}^s \lambda_{i,j}(\bar{x})$$

$$\varphi(\mathcal{A}) \equiv \bigwedge_{e_1, \dots, e_t \in |\mathcal{A}|} \bigwedge_{i=1}^r \bigvee_{j=1}^s \lambda'_{i,j}(\bar{e})$$

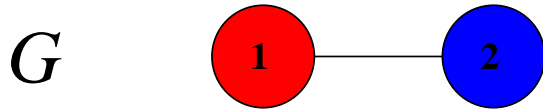
$$\mathcal{A} \in B \quad \Leftrightarrow \quad \mathcal{A} \models \Phi \quad \Leftrightarrow \quad \varphi(\mathcal{A}) \in \text{SAT} \quad \square$$

Example: Fagin's Theorem implies Cook's Theorem

$$\Phi_{2\text{-color}} \equiv \exists R^1 \exists B^1 \forall x, y [(R(x) \vee B(x))$$

$$\wedge (\neg E(x, y) \vee \neg R(x) \vee \neg R(y))$$

$$\wedge (\neg E(x, y) \vee \neg B(x) \vee \neg B(y))]$$



boolean variables: r_1, r_2, b_1, b_2

$$\varphi_G \equiv (r_1 \vee b_1) \wedge (\top \vee \overline{r_1} \vee \overline{r_1}) \wedge (\top \vee \overline{b_1} \vee \overline{b_1})$$

$$(r_1 \vee b_1) \wedge (\perp \vee \overline{r_1} \vee \overline{r_2}) \wedge (\perp \vee \overline{b_1} \vee \overline{b_2})$$

$$(r_2 \vee b_2) \wedge (\perp \vee \overline{r_2} \vee \overline{r_1}) \wedge (\perp \vee \overline{b_2} \vee \overline{b_1})$$

$$(r_2 \vee b_2) \wedge (\top \vee \overline{r_2} \vee \overline{r_2}) \wedge (\top \vee \overline{b_2} \vee \overline{b_2})$$

Simplifies to: $(r_1 \vee b_1) \wedge (r_2 \vee b_2) \wedge (\overline{r_1} \vee \overline{r_2}) \wedge (\overline{b_1} \vee \overline{b_2})$

3-SAT = $\{\varphi \in \text{CNF-SAT} \mid \varphi \text{ has } \leq 3 \text{ literals per clause}\}$

Prop: 3-SAT is NP-complete.

Proof: Show $\text{SAT} \leq 3\text{-SAT}$.

Example: $C \equiv (l_1 \vee l_2 \vee \dots \vee l_7)$

$C' \equiv (l_1 \vee l_2 \vee d_1) \wedge (\overline{d_1} \vee l_3 \vee d_2) \wedge (\overline{d_2} \vee l_4 \vee d_3) \wedge$
 $(\overline{d_3} \vee l_5 \vee d_4) \wedge (\overline{d_4} \vee l_6 \vee l_7)$

Claim: $C \in \text{SAT} \iff C' \in 3\text{-SAT}$

Do this construction for each clause independently. □

Prop: 3-COLOR is NP-complete.

Proof: Saw last time that 3-COLOR \in **SO \exists** = **NP**.

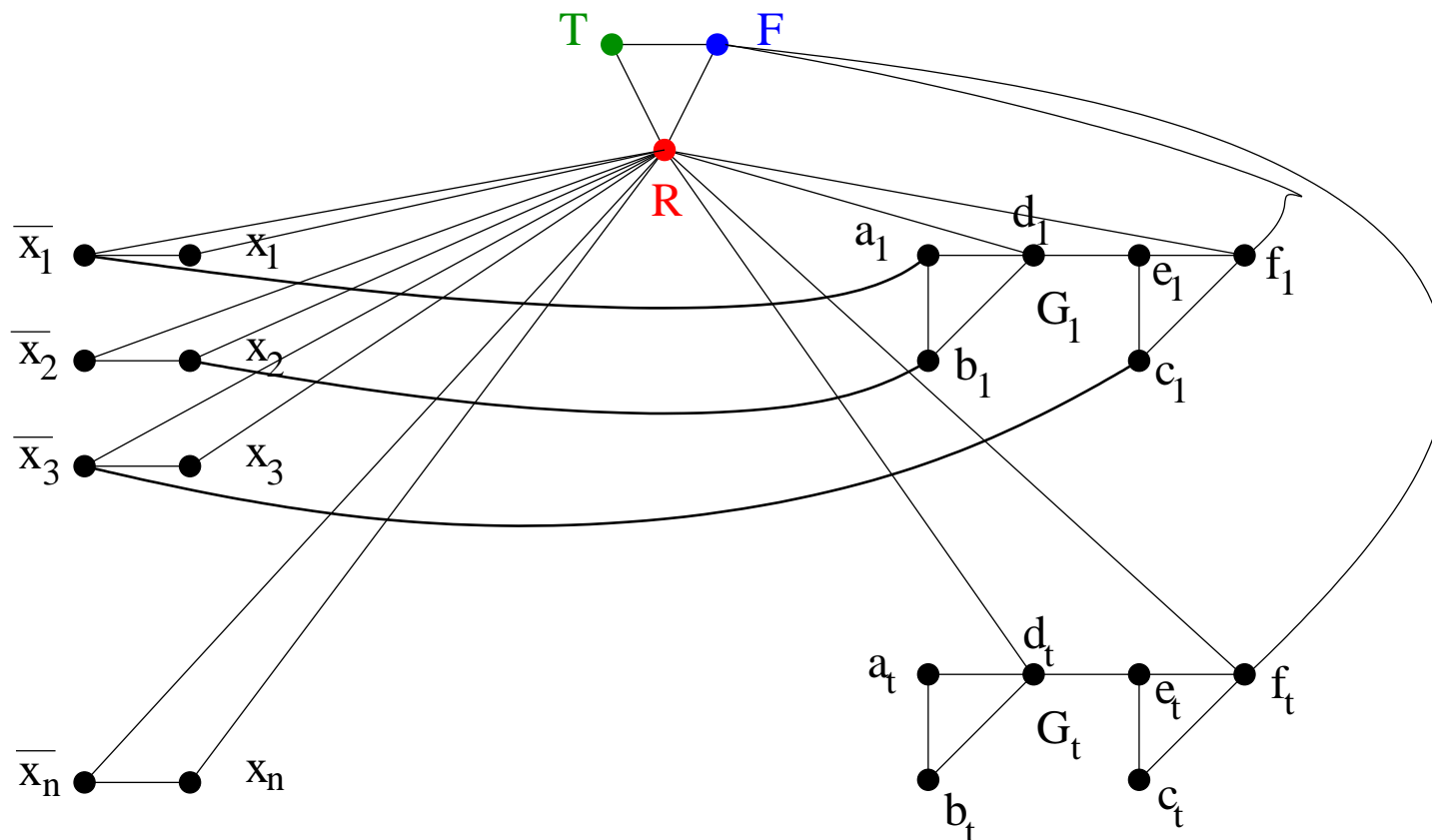
Show 3-SAT \leq 3-COLOR:

$$\varphi = C_1 \wedge C_2 \wedge \dots \wedge C_t \in \text{3-CNF}$$

$$\text{VAR}[\varphi] = \{x_1, x_2, \dots, x_n\}$$

Must build graph $G(\varphi)$ s.t.

$$\varphi \in \text{3-SAT} \iff G(\varphi) \in \text{3-COLOR}$$



G_1 encodes clause $C_1 = (\overline{x_1} \vee x_2 \vee \overline{x_3})$

Claim: Triangle a_1, b_1, d_1 serves as an “or”-gate:
 d_1 may be colored “true” iff at least one of its inputs $\overline{x_1}, x_2$ is colored “true”.

A three coloring of the literals can be extended to color G_i iff the corresponding truth assignment makes C_i true. □

Prop: CLIQUE is NP-complete.

Proof: Show $\text{SAT} \leq \text{CLIQUE}$.

$$\varphi = C_1 \wedge C_2 \wedge \cdots \wedge C_t \in \text{CNF}$$

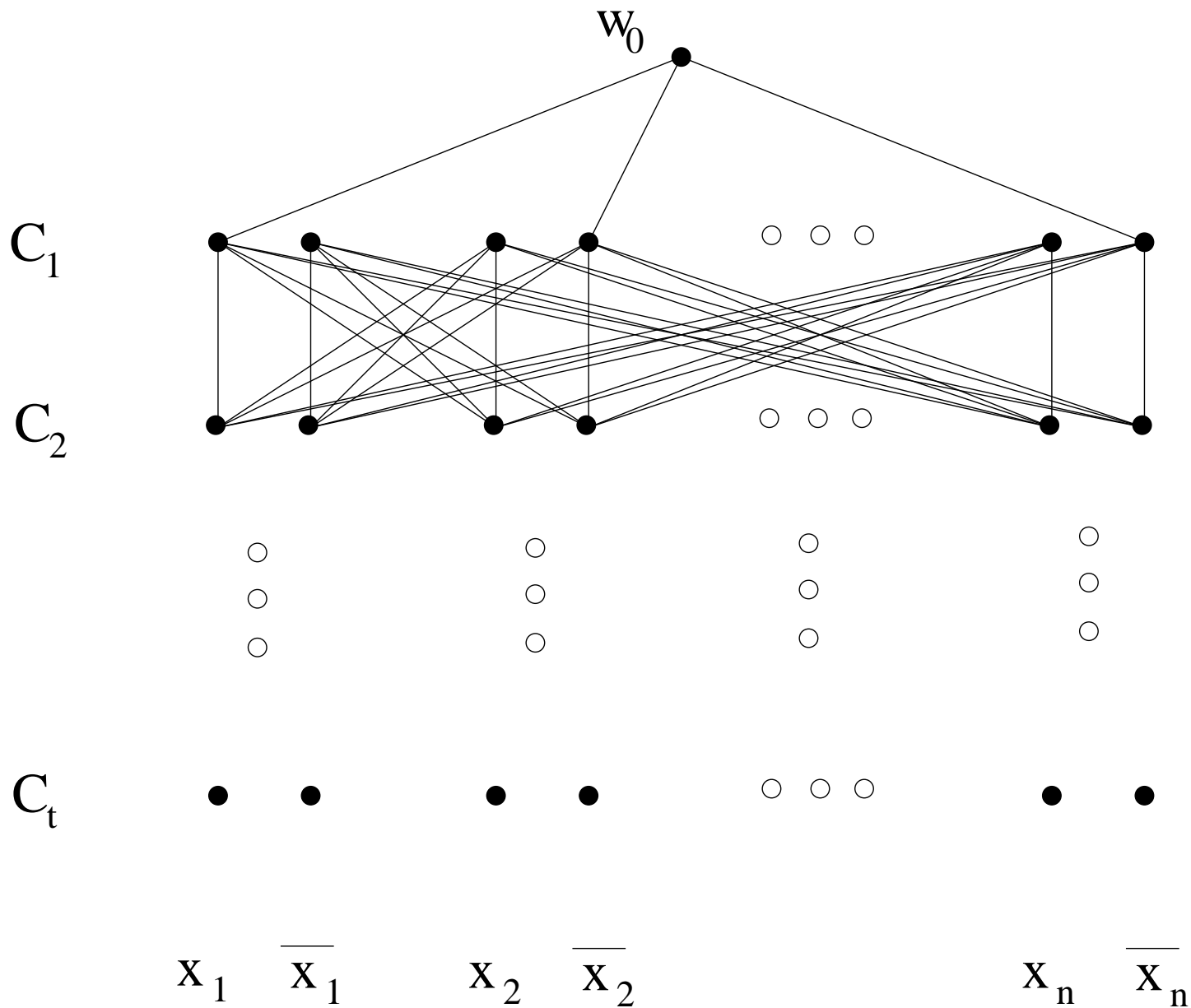
$$\text{VAR}[\varphi] = \{x_1, x_2, \dots, x_n\}$$

Must build graph $g(\varphi)$ s.t.

$$\varphi \in \text{SAT} \iff g(\varphi) \in \text{CLIQUE}$$

$$L = \{x_1, \dots, x_n, \bar{x}_1, \dots, \bar{x}_n\}; \quad C = \{c_1, \dots, c_t\}$$

$$g(\varphi) = (V^{g(\varphi)}, E^{g(\varphi)}, k^{g(\varphi)})$$



$$g(\varphi), \quad C_1 = (x_1 \vee \overline{x_2} \vee \overline{x_n})$$

$$V^{g(\varphi)} = (C \times L) \cup \{w_0\}$$

$$E^{g(\varphi)} = \{(\langle c_1, \ell_1 \rangle, \langle c_2, \ell_2 \rangle) \mid c_1 \neq c_2 \text{ and } \bar{\ell}_1 \neq \ell_2\} \cup \\ \{(w_0, \langle c, \ell \rangle), (\langle c, \ell \rangle, w_0) \mid \ell \text{ occurs in } c\}$$

$$k^{g(\varphi)} = t + 1$$

$$(\varphi \in \text{SAT}) \iff (g(\varphi) \in \text{CLIQUE})$$

Claim: $g \in F(\mathbf{L})$

Prop: Subset Sum is NP-Complete.

$$\left\{ m_1, \dots, m_r, T \in \mathbf{N} \mid \exists S \subseteq \{1, \dots, r\} \left(\sum_{i \in S} m_i = T \right) \right\}$$

Show $3\text{-SAT} \leq \text{Subset Sum}$.

$$\varphi \equiv C_1 \wedge C_2 \wedge \dots \wedge C_t \in \mathbf{3\text{-CNF}}$$

$$\mathbf{VAR}[\varphi] = \{x_1, x_2, \dots, x_n\}$$

Build $f \in F(\mathbf{L})$ such that for all φ ,

$$\varphi \in \mathbf{3\text{-SAT}} \iff f(\varphi) \in \text{Subset Sum}$$

	x_1	x_2	\dots	x_n	C_1	C_2	\dots	C_t	
T	1	1	\dots	1	3	3	\dots	3	
x_1	1	0	\dots	0	1	0	\dots	1	$C_1 = (x_1 \vee \overline{x_2} \vee x_3)$
$\overline{x_1}$	1	0	\dots	0	0	1	\dots	0	
x_2	0	1	\dots	0	0	1	\dots	1	$C_2 = (\overline{x_1} \vee x_2 \vee x_n)$
$\overline{x_2}$	0	1	\dots	0	1	0	\dots	0	
\vdots	\vdots	\vdots	\dots	\vdots	\vdots	\vdots	\dots	\vdots	$C_t = (x_1 \vee x_2 \vee \overline{x_n})$
x_n	0	0	\dots	1	0	1	\dots	0	
$\overline{x_n}$	0	0	\dots	1	0	0	\dots	1	
a_1	0	0	\dots	0	1	0	\dots	0	
b_1	0	0	\dots	0	1	0	\dots	0	
a_2	0	0	\dots	0	0	1	\dots	0	
b_2	0	0	\dots	0	0	1	\dots	0	
\vdots	\vdots	\vdots	\dots	\vdots	\vdots	\vdots	\dots	\vdots	
a_t	0	0	\dots	0	0	0	\dots	1	
b_t	0	0	\dots	0	0	0	\dots	1	

Knapsack

n objects; W = max weight I can carry in my knapsack.

object	o_1	o_2	\cdots	o_n	
weight	w_1	w_2	\cdots	w_n	≥ 0
value	v_1	v_2	\cdots	v_n	

Optimization Problem: choose $S \subseteq \{1, \dots, n\}$ to

maximize $\sum_{i \in S} v_i$ such that $\sum_{i \in S} w_i \leq W$

Decision Problem: Given \bar{w}, \bar{v}, W, V , can I get

total value $\geq V$ while

total weight is $\leq W$?

Prop: Knapsack is NP-Complete.

Proof: Let $I = \langle m_1, \dots, m_n, T \rangle$ be a Subset Sum instance.

Problem: $\exists S \subseteq \{1, \dots, n\} \left(\sum_{i \in S} m_i = T \right)$

$f(I) = \langle m_1, \dots, m_n, m_1, \dots, m_n, T, T \rangle$ is a Knapsack instance.

Claim: $I \in \text{Subset Sum} \iff f(I) \in \text{Knapsack}$

$$\exists S \subseteq \{1, \dots, n\} \left(\sum_{i \in S} m_i = T \right) \iff$$

$$\exists S \subseteq \{1, \dots, n\} \left(\sum_{i \in S} m_i \geq T \quad \wedge \quad \sum_{i \in S} m_i \leq T \right) \quad \square$$

Fact: Even though Knapsack is **NP-Complete** there is an efficient dynamic programming algorithm that can closely approximate the maximum possible V .

More about that next class . . .

