### CMPSCI 611: Advanced Algorithms

Lecture 11: Network Flow

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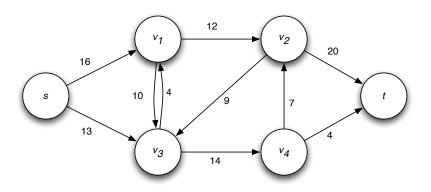
Last Compiled: April 4, 2024

### **Definitions**

### Input:

- ightharpoonup Directed Graph G = (V, E)
- ▶ Capacities C(u, v) > 0 for  $(u, v) \in E$  and C(u, v) = 0 for  $(u, v) \notin E$
- A source node s, and sink node t

# Capacity



### **Definitions**

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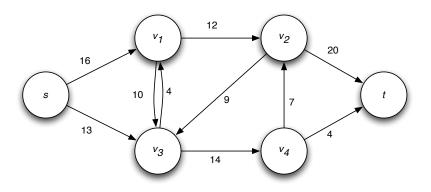
Output: A flow f from s to t where  $f: V \times V \to \mathbb{R}$  satisfies

- ▶ Skew-symmetry:  $\forall u, v \in V, f(u, v) = -f(v, u)$
- ► Conservation of Flow:  $\forall v \in V \{s, t\}, \sum_{u \in V} f(u, v) = 0$
- ▶ Capacity Constraints:  $\forall u, v \in V$ ,  $f(u, v) \leq C(u, v)$

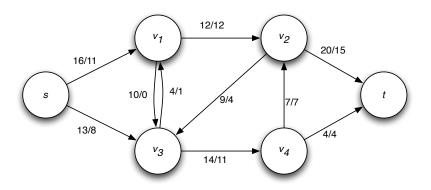
Goal: Maximize "size of the flow", i.e., the total flow coming leaving s:

$$|f| = \sum_{v \in V} f(s, v)$$

# Capacity



# Capacity/Flow



### **Cut Definitions**

#### Definition

An s-t cut of G is a partition of the vertices into two sets A and B such that  $s \in A$  and  $t \in B$ .

#### Definition

The capacity of a cut (A, B) is

$$C(A,B) = \sum_{u \in A, v \in B} C(u,v)$$

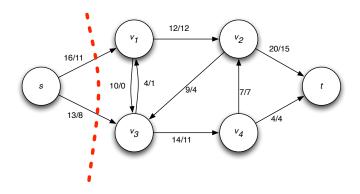
#### Definition

The flow across a cut (A, B) is

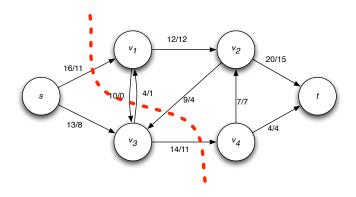
$$f(A,B) = \sum_{u \in A, v \in B} f(u,v)$$

Note that because of capacity constraints:  $f(A, B) \leq C(A, B)$ 

### First Cut



## Second Cut



### Max-Flow Min-Cut

#### Lemma

For any flow f: for all s-t cuts (A, B), f(A, B) equals |f|.

### Theorem (Max-Flow Min-Cut)

For any flow network and flow f, the following statements are equivalent:

- 1. f is a maximum flow.
- 2. There exists an s-t cut (A,B) such that |f|=C(A,B)

We'll prove both next class.

## Residual Networks and Augmenting Paths

Residual network encodes how you can change the flow between two nodes given the current flow and the capacity constraints.

#### Definition

Given a flow network G = (V, E) and flow f in G, the residual network  $G_f$  is defined as

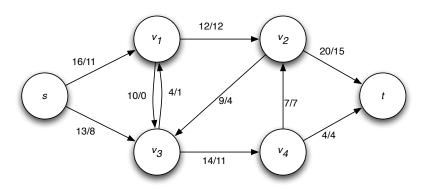
$$G_f = (V, E_f)$$
 where  $E_f = \{(u, v) : C(u, v) - f(u, v) > 0\}$  
$$C_f(u, v) = C(u, v) - f(u, v)$$

Note that  $(u, v) \in E_f$  implies either C(u, v) > 0 or C(v, u) > 0.

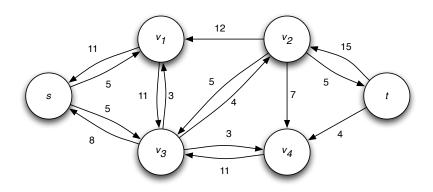
#### Definition

An augmenting path for flow f is a path from s to t in graph  $G_f$ . The bottleneck capacity b(p) is the minimum capacity in  $G_f$  of any edge of p. We can increase flow by b(p) along an augmenting path.

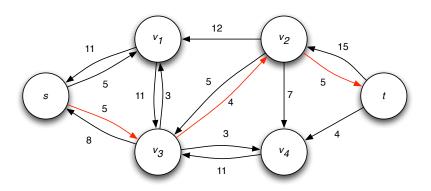
# Capacity/Flow



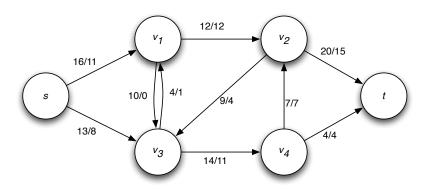
## Residual



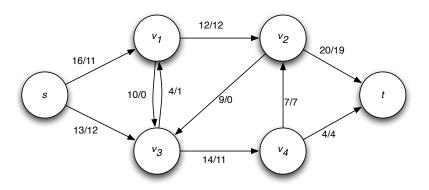
# Augmenting Path



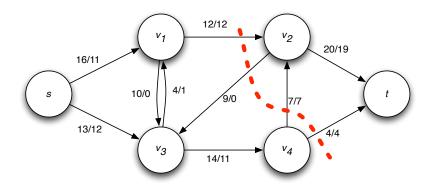
## Old Flow



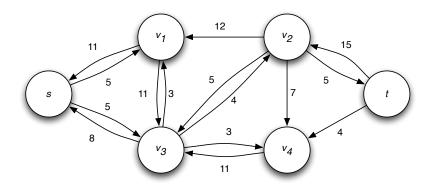
## **New Flow**



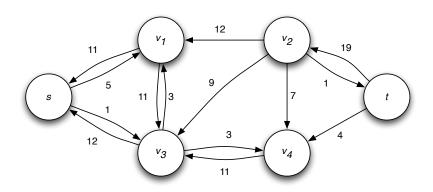
## Min Capacity Cut Proves this is Optimal



# Old Residual Graph



# New Residual Graph



### Ford-Fulkerson Algorithm

### Algorithm

- 1. flow f = 0
- 2. while there exists an augmenting path p for f
  - 2.1 find augmenting path p
  - 2.2 augment f by b(p) units along p
- 3. return f

#### **Theorem**

The algorithms finds a maximum flow in time  $O(|E||f^*|)$  if capacities are integral where  $|f^*|$  is the size of the maximum flow.

#### Proof.

O(|E|) time to find each augmenting path via BFS and  $|f^*|$  iterations because each augmenting path increases flow by at least 1.

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